

# **Joint Center for Satellite Data Assimilation**

## **CRTM: v2.0 User Guide**

November 21, 2012; rev22704

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## Change History

| Date       | Author      | Change   |
|------------|-------------|--|
| 2009-01-30 | P.van Delst | Initial release.   |
| 2009-02-03 | P.van Delst | Updated chapter 2 with descriptions of the example code and coefficient tarballs. Added explanation of layering convention in chapter 4. |
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# What's New in v2.0

## New Science

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**Multiple transmittance algorithms** There are now two transmittance models available for use in the CRTM: ODAS (Optical Depth in Absorber Space), which is equivalent to the previous CompactOPTRAN algorithm; and ODPS (Optical Depth in Pressure Space) which is similar to the RTTOV-type of transmittance algorithm, except here OPTRAN is used for water vapor line absorption.

The algorithm is selectable by the user via the transmittance coefficient (`TauCoeff`) data file used to initialise the CRTM. This method, rather than a switch argument in the `CRTM.Init()` function, was chosen to allow users to “mix-and-match” transmittance algorithms for different sensors in the same initialisation call.

**SSU-specific transmittance model** Similar to the multiple transmittance algorithm approach, a separate algorithm *just* for the SSU instrument has been constructed. The algorithm is based on the ODAS approach, but with elements to account for the time-dependence of the SSU CO<sub>2</sub> cell pressures.

**Zeeman-splitting transmittance model for SSMIS upper-level channels** A separate algorithm is available to account for the change in absorption at very low pressures due to the Zeeman-splitting of absorption lines. Currently this algorithm has only been applied to the affected channels in the SSMIS instrument, 19-22.

**Visible sensor capability** The CRTM now supports radiative transfer for visible instruments/channels. The treatment of visible channels was handled in the CRTM framework by considering them separate instruments. The sensor identifier for these instruments/channels are differentiated from their infrared counterparts by a “v.” prefix. For example, while `modis_aqua` is the sensor identifier for the infrared channels, `v.modis_aqua` identifies the visible channels.

**Inclusion of Matrix Operator Method (MOM) in radiative transfer** To handle visible wavelength radiative transfer in the presence of aerosols, the Advanced Doubling-Adding (ADA) algorithm was adapted to use the MOM technique [Liu and Ruprecht, 1996].

**Inclusion of additional infrared sea surface emissivity model** Files containing the emissivity data (`EmisCoeff`) for the Nalli et al. [2008a] model are provided. Previously, only the `EmisCoeff` files for the Wu and Smith [1997] model were provided. Users can now select between the Nalli et al. [2008a] or Wu and Smith [1997] models by specifying the requisite filename in the call to `CRTM.Init()`.

**Surface BRDF for solar-affected shortwave IR channels** A bi-directional reflectance distribution function (BRDF) has been added to account for reflected solar in affected shortwave infrared channels [Breon, 1993].

**Reflectivity for downwelling infrared over water** The reflectivity for downwelling infrared radiation over water surface has been changed from Lambertian to specular.

**Aerosol type changes** To account for changes in the handling of GOCART [Chin et al., 2002] aerosol model output, additional sea salt coarse modes were added to the list of allowed aerosol types. Also, the separate dry and wet types for organic and black carbon aerosols were combined, with a relative humidity of 0% used to indicate the previous “dry” aerosol type. See table A.5 for the new list of accepted aerosol types.

## Interface Changes

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**CRTM Initialisation function** The changes to the `CRTM_Init()` interface were relatively minor but do require calling codes to be modified:

- The `Sensor_Id` argument is now mandatory. This argument is used to construct the sensor-specific `SpcCoeff` and `TauCoeff` filename and in the past was optional to allow for “generic” filenames. This is no longer allowed and generic `SpcCoeff` and `TauCoeff` files are no longer used.
- The loading of the `CloudCoeff` and `AerosolCoeff` datafiles containing the optical properties of cloud and aerosol particulates is no longer mandatory. For cloud-free CRTM runs, the load of the `CloudCoeff` and `AerosolCoeff` datafiles can be disabled via the optional `Load_CloudCoeff` and `Load_AerosolCoeff` arguments which are logical switches (true or false).

**User accessible structures** The structures are defined as those that are used in the argument lists of the main CRTM functions (e.g. initialisation; the forward, tangent-linear, adjoint, and K-matrix models; and destruction). Changes were made to both the structure definitions and their procedures. To mitigate the possibility of memory leaks, the definitions of array members of structures have had their `POINTER` attribute replaced with `ALLOCATABLE`. This was a first step in preparation for use of Fortran2003 Object Oriented features in the CRTM (once Fortran2003 compiler become widely available), where the derived type structure definitions will be reclassified as objects and their procedures will be type-bound. To delineate this change from previous versions of CRTM the interfaces of the derived type procedures have been altered by:

- changing the procedure names to use the convention `CRTM_object_action` where an *object* can be any of the user accessible CRTM derived types (e.g. `CRTM_Atmosphere_type`, `CRTM_RTSolution_type` etc), and the *action* can be those defined operations for the structure (e.g. `Create`, `Destroy`, `Inspect`, etc).
- making the first dummy argument of the definition module procedures the derived type itself. This will eventually allow the procedures to be called via an instance of the derived type<sup>12</sup>

All of the current derived type definitions and their associated procedures and interfaces are shown in appendix A.

**GeometryInfo to Geometry structure name change** Previously, the `GeometryInfo` structure held both the user input to the CRTM as well as the internally computed geometry data. To separate these two sets of quantities, the name of the geometry information structure that is passed into the CRTM functions was changed from `CRTM_GeometryInfo_type` to `CRTM_Geometry_type`. This means that *all* of the user input structures are now strictly `INTENT(IN)` arguments.

**Options structure specific changes** The additional changes made to the `CRTM_Options_type` definition:

- all usage on/off switches have been changed from integers (0/1) to logicals (true/false),
- a logical switch to control input checking, `Check_Input`, has been added.
- structure components for `SSU-specific` and `Zeeman model` input have been added.

To migrate from the CRTM v1.2.x calling structures to those implemented in v2.0.x, see Appendix C, “[Migration Path from REL-1.2 to REL-2.0](#).”

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<sup>1</sup>Interested readers can investigate the `PASS` attribute that can be used in the `PROCEDURE` statement within derived type definitions in Fortran2003.

<sup>2</sup>The I/O functions do not yet follow this convention, since they are considered secondary to the definition module procedures used to manipulate the derived types.

# What's New in v2.0.1

The v2.0.1 update to the CRTM was done to

- Fix defects of varying severity
- Refactor some modules to work around compiler bugs
- Reorganise the testing/example program.

## Bug Fixes

---

**Replacing CRTM\_Atmosphere\_IsValid WARNING message for missing ozone with FAILURE** The CRTM contains two different transmittance model algorithm: the Optical Depth in Absorber Space (ODAS) algorithm and the Optical Depth in Pressure Space (ODPS) algorithm. The ODPS algorithm was constructed to handle “missing” profiles of major trace gas absorbers (e.g. ozone). The ODAS algorithm, however, cannot yet handle a missing ozone profile. As such, we have switched back to missing ozone being a **FAILURE** error, regardless of whether or not the ODAS or ODPS transmittance algorithm is being used. See ticket [150](#)<sup>3</sup>.

**Allowed for user profile top level pressures to be less than 0.005hPa in the ODAS algorithm.** This corrected a bug that generated negative absorber amounts for the top layer when a user input a profile where the top level pressure is *less than* 0.005hPa. See ticket [151](#).

**Fixed test of SensorData%Tb component** The previous test (called within the `CRTM_Surface_IsValid` procedure) caused a **FAILURE** when *any* of the supplied brightness temperatures were less than zero. This test has been changed to fail only when *all* of the input brightness temperatures are less than zero to allow channel subsets of data to be passed. See ticket [110](#).

**Corrected error message in CRTM\_Atmosphere\_IsValid function.** The error message for invalid input absorber units was corrected. See ticket [141](#).

**Coefficient load message suppression in the CRTM\_Init function was not occurring correctly** This problem was traced to a logic error in several of the coefficient load procedures when the optional MPI process identifier arguments were passed in. The logic has been corrected in the affected load procedures. See ticket [143](#).

## Refactor for Compiler Defects

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**Memory leak in CRTM\_IRSSEM module fixed** This was a bug caused by apparent compiler bugs (in more than one compiler) where declaring the internals of a local (i.e. not **PUBLIC**) structure as **PRIVATE** caused a memory leak. Removal of the internal **PRIVATE** statement solved the problem. See ticket [144](#).

---

<sup>3</sup>The ticket references and links are included to allow CRTM developers to easily navigate to the CRTM Source Code Management system from this document

**Modification of Type\_Kinds module to allow for Intel ifort compilation** This work around was necessary due to an ifort v11.1 compiler bug that surfaced due to the CRTM build switches for this compiler promote compiler warnings to errors. Rather than require users to modify their compilation setup to avoid this error, the `Type_Kinds` module was modified to avoid it entirely. See ticket [112](#).

**Modification of CRTM\_Atmosphere\_AddLayerCopy procedure to allow for PGI pgf95 compilation** The REL-2.0 version of the `CRTM_Atmosphere_AddLayerCopy` procedure was identified as a problem for the PGI pgf95 v10.2-1 compiler. A bug report was submitted to PGI Support and filed as TPR 16814. The bug is fixed in the v10.4 release of the pgf95 compiler, which does not have a problem with the original CRTM code. See ticket [114](#).

## Reorganisation of Test/Example Programs

---

This update is probably the biggest change in REL-2.0.1. The CRTM tarball structure was updated to include the test/example codes – as opposed to supplying a separate tarball just for the example programs. The reasoning here was to establish the typical “`make, make test`” procedures for building packages, but be aware that the setup is still rather unsophisticated; we are still investigating ways to more easily configure the CRTM library and test/example programs (e.g. [autoconf](#)).

For a full description of the necessary steps to build the CRTM library and test/example programs, refer to the `README` file supplied with the CRTM release tarball.

# *What's New in v2.0.2*

The v2.0.2 update to the CRTM was done to

- Fix two critical defects: one introduced in v2.0; another in the v2.0.1 update.
- Add additional tests.

## Bug Fixes

---

**Fix for specular reflection of IR sensors over water** In v2.0, the reflectance behaviour for IR sensors over water was changed from Lambertian to specular. The problem with the update is due to the design of how sub-FOV surface differences are handled in the CRTM. Currently there is no way to handle a mixed land/water FOV where land reflectivity is assumed Lambertian and water reflectivity specular. The reflectivity behaviour ended up being that associated with the surface type having the largest FOV fraction. The temporary fix applied is that *all* IR sensor reflectivities are now treated as specular. See ticket [164](#).

**Fix for invalid maximum number of azimuth angles for visible sensors** To speed up visible sensor calculations in v2.0.1, the maximum number of azimuth angles used was switched from a fixed maximum to a dynamic one based on the number of Legendre terms required to properly simulate molecular scattering. However, the maximum number of azimuth angle assignment was being performed prior to the minimum acceptable value being set. This lead to an invalid value being specified for the number of azimuth angles in some cases. See ticket [165](#).

## Addition of Test/Example Programs

---

An additional forward model test, `Example5_ClearSky`, was introduced to test the bug fixes mentioned above. All test comparison output files have been updated accordingly.

# *What's New in v2.0.4*

The v2.0.4 update to the CRTM was done to

- Update the sensor coefficient files, including the renaming of the hyperspectral infrared sensor identifiers.
- Fix a number of defects.

## Update of sensor coefficient files

An update of all the sensor coefficient files (the `SpcCoeff` and `TauCoeff` files) was carried out, introducing many new sensors. See table [B.1](#) for the full listing of instruments for which there are CRTM datafiles.

Additionally, to facilitate use of a generic sensor identifier for CRTM datafiles containing channel subsets of hyperspectral instruments such as AIRS, IASI, and CrIS, the "all channel" files (constructed from the individual module or band files) are now tagged with the total channel count. The rename of the `Sensor_Id`'s for the current hyperspectral sensors are shown below.

| Old Sensor_Id             | New Sensor_Id                 |
|---------------------------|-------------------------------|
| <code>airs_aqua</code>    | <code>airs2378_aqua</code>    |
| <code>iasi_metop-a</code> | <code>iasi8461_metop-a</code> |
| <code>iasi_metop-b</code> | <code>iasi8461_metop-b</code> |
| <code>cris_npp</code>     | <code>cris1305_npp</code>     |

## Bug Fixes

**Fix an initialisation error in the `CRTM_IRSSEM` module** In the adjoint procedure, `CRTM_Compute_IRSSEM_AD()` some local adjoint variable were not initialised prior to their use. Under certain run conditions (based on compiler, platform, and sensors run), this was generated floating point exceptions and halting execution. The fix applied was to initialise the local adjoint variables in question. See ticket [259](#).

**Fix a memory leak in the `ODPS_Predictor_Define` module** A deallocation statement was missing a single structure component leading to a small memory leak. The fix applied was to ensure that the components of the allocation and deallocation statements matched. See ticket [260](#).



## *What's New in v2.0.5*

The v2.0.5 update to the CRTM was done to

- Alter the intent of a number of dummy arguments in the internal cloud and aerosol scattering routines from `INTENT(OUT)` to `INTENT(IN OUT)` to prevent automatic (re)initialisation. On some systems (primarily linux) this can have a not insignificant effect on execution time for scattering atmosphere inputs. Results were *not* changed at all via this update.

A separate release has been created to satisfy NCEP Central Operations (NCO) revision numbering conventions. This v2.0.5 release is identical to the previous v2.0.4-p1 “patch” release.

# What's New in v2.0.6

The v2.0.6 update to the CRTM was done to

- Address memory allocation issues on linux systems, and
- Update some sensor coefficient files.

## Bug Fixes

---

**Made internal scattering structures allocatable** It was found (on linux systems only) that when the CRTM is called to process a profile at a time – as opposed to passing in a block of profiles – the clear sky computation ran up to a factor of three slower for sensors with a low channel count. This was found to be caused by the internal scattering structures (used to hold intermediate forward results) containing fixed-size arrays. It appears that, on linux systems independent of compiler, these local scattering structures were being allocated (system allocation, not Fortran allocation) on each CRTM call, *even if they were never used*. To overcome this problem, these internal structures (one for cloud and one for aerosol scattering) were defined with their components being allocatable. This eliminated the problem. CRTM results are not affected. See ticket [374](#).

## Update of sensor coefficient files

---

**Update of MetOp-B AMSU-A SpcCoeff and TauCoeff coefficient files** NESDIS/STAR researchers noticed a large difference between observed and calculated brightness temperatures for channel 15 of MetOp-B AMSU-A. Inspection of the sensor's parameters used in the CRTM revealed that the central frequency for channel 15 was incorrect, 88GHz instead of 89GHz. The central frequency was updated and the **SpcCoeff** and **TauCoeff** coefficient files recreated. See tickets [304](#) and [368](#).

**Update of various HIRS SpcCoeff and TauCoeff coefficient files** New HIRS spectral response functions (SRFs) for NOAA-09 to MetOp-A were release by NESDIS/STAR. New **SpcCoeff** and **TauCoeff** coefficient files were generated for these updated SRFs. See tickets [309](#) and [375](#).

## 1.1 Conventions

The following are conventions that have been adhered to in the current release of the CRTM framework. They are guidelines intended to make understanding the code at a glance easier, to provide a recognisable “look and feel”, and to minimise name space clashes.

### 1.1.1 Naming of Structure Types and Instances of Structures

The derived data type, or structure<sup>1</sup> type, naming convention adopted for use in the CRTM is,

```
[CRTM_]name_type
```

where *name* is an identifier that indicates for what a structure is to be used. All structure type names are suffixed with “\_type” and CRTM-specific structure types are prefixed with “CRTM\_”. Some examples are,

```
CRTM_Atmosphere_type
CRTM_RTSolution_type
```

An instance of a structure is then referred to via its *name*, or some sort of derivate of its *name*. Some structure declarations examples are,

```
TYPE(CRTM_Atmosphere_type) :: atm, atm_K
TYPE(CRTM_RTSolution_type) :: rts, rts_K
```

where the K-matrix structure variables are identified with a “\_K” suffix. Similarly, tangent-linear and adjoint variables are suffixed with “\_TL” or “\_AD” respectively.

### 1.1.2 Naming of Definition Modules

Modules containing structure type definitions are termed *definition modules*. These modules contain the actual structure definitions as well as various utility procedures to allocate, destroy, copy etc. structures of the designated type. The naming convention adopted for definition modules in the CRTM is,

```
[CRTM_]name_Define
```

where, as with the structure type names, all definition module names are suffixed with “\_Define” and CRTM-specific definition modules are prefixed with “CRTM\_”. Some examples are,

```
CRTM_Atmosphere_Define
CRTM_RTSolution_Define
```

The actual source code files for these modules have the same name with a “.f90” suffix.

<sup>1</sup>The terms “derived type” and “structure” are used interchangeably in this document.

### 1.1.3 Naming of Application Modules

Modules containing the routines that perform the calculations for the various components of the CRTM are termed *application modules*. The naming convention adopted for application modules in the CRTM is,

`CRTM_name`

Some examples are,

```
CRTM_Atmosphere_IO
CRTM_SfcOptics
CRTM_RTSolution
```

However, in this case, *name* does not necessarily refer just to a structure type. Separate application modules are used as required to split up tasks in manageable (and easily maintained) chunks. For example, separate modules have been provided to contain the cloud and aerosol optical property retrieval; similarly separate modules handle different surface types for different instrument types in computing surface optics.

Again, the actual source code files for these modules have the same name with a “.f90” suffix. Note that not all definition modules have a corresponding application module since some structures (e.g. `SpcCoeff` structures) are simply data containers.

### 1.1.4 Naming of I/O Modules

Modules containing routines that read and write data from and to files are, naturally, termed I/O modules. Not all data structures have associated I/O modules. The naming convention adopted for these modules in the CRTM is,

`[CRTM_]name_Binary_IO`

or just

`[CRTM_]name_IO`

Some examples are,

```
CRTM_Atmosphere_IO
CRTM_RTSolution_IO
```

As with the other module types, the actual source code files for these modules have the same name with a “.f90” suffix.

In the context of the CRTM, the term “Binary” is a euphemism for sequential, unformatted I/O in Fortran.

## 1.2 Components

---

The CRTM is designed around three broad categories: atmospheric optics, surface optics and radiative transfer.

### 1.2.1 Atmospheric Optics

(`AtmOptics`) This category includes computation of the absorption by atmospheric gases (`AtmAbsorption`) and scattering and absorption by both clouds (`CloudScatter`) and aerosols (`AerosolScatter`).

The gaseous absorption component computes the optical depth of the absorbing constituents in the atmosphere given the pressure, temperature, water vapour, and ozone concentration<sup>2</sup> profiles.

---

<sup>2</sup>Additional trace gas absorption capabilities are being added.

The scattering component simply interpolates look-up-tables (LUTs) of optical properties – such as mass extinction coefficient and single scatter albedo – for cloud and aerosol types that are then used in the radiative transfer component. See tables A.4 and A.5 for the valid cloud and aerosol types, respectively, that are valid in the CRTM.

### 1.2.2 Surface Optics

(**SfcOptics**) This category includes the computation of surface emissivity and reflectivity for four gross surface types (land, water, snow, and ice). Each gross surface type has a specified number of specific surface types associated with it. See tables A.8, A.9, A.10, and A.11 for the land, water, snow, and ice surface types, respectively, that are valid in the CRTM.

The CRTM utilises separate models for each gross surface type for each spectral type (infrared and microwave). These models can be either physical models or database/LUT type of models.

### 1.2.3 Radiative Transfer Solution

(**RTSolution**) This category takes the **AtmOptics** and **SfcOptics** data and solves the radiative transfer problem in either clear or scattering atmospheres.

## 1.3 Models

---

The CRTM is composed of four models: a forward model, a tangent-linear model, an adjoint model, and a K-matrix model. These can be represented as shown in equations 1.1a to 1.1d.

$$\mathbf{T}_B, \mathbf{R} = \mathbf{F}(\mathbf{T}, \mathbf{q}, T_s, \dots) \quad (1.1a)$$

$$\delta \mathbf{T}_B, \delta \mathbf{R} = \mathbf{H}(\mathbf{T}, \mathbf{q}, T_s, \dots, \delta \mathbf{T}, \delta \mathbf{q}, \delta T_s, \dots) \quad (1.1b)$$

$$\delta^* \mathbf{T}, \delta^* \mathbf{q}, \delta^* T_s, \dots = \mathbf{H}^T(\mathbf{T}, \mathbf{q}, T_s, \dots, \delta^* \mathbf{T}_B) \quad (1.1c)$$

$$\delta^* \mathbf{T}_l, \delta^* \mathbf{q}_l, \delta^* T_{s,l}, \dots = \mathbf{K}(\mathbf{T}, \mathbf{q}, T_s, \dots, \delta^* \mathbf{T}_B) \text{ for } l = 1, 2, \dots, L \quad (1.1d)$$

Here  $\mathbf{F}$  is the forward operator that, given the atmospheric temperature and absorber profiles ( $\mathbf{T}$  and  $\mathbf{q}$ ), surface temperature ( $T_s$ ), etc., produces a vector of channel brightness temperatures ( $\mathbf{T}_B$ ) and radiances ( $\mathbf{R}$ ).

The tangent-linear operator,  $\mathbf{H}$ , represents a linearisation of the forward model about  $\mathbf{T}$ ,  $\mathbf{q}$ ,  $T_s$ , etc. and when also supplied with perturbations about the linearisation point (quantities represented by the  $\delta$ 's) produces the expected perturbations to the brightness temperature and channel radiances.

The adjoint operator,  $\mathbf{H}^T$ , is simply the transpose of the tangent-linear operator and produces gradients (the quantities represented by the  $\delta^*$ 's). It is worth noting that, in the CRTM, these adjoint gradients are accumulated over channel and thus do not represent channel-specific Jacobians.

The K-matrix operator<sup>3</sup>,  $\mathbf{K}$ , is effectively the same as the adjoint but with the results preserved by channel (indicated via the subscript  $l$ ). In the CRTM, the adjoint and K-matrix results are related by,

$$\delta^* x = \sum_{l=1}^L \delta^* x_l \quad (1.2)$$

---

<sup>3</sup>The term K-matrix is used because references to this operation in the literature commonly use the symbol  $\mathbf{K}$

Thus, the K-matrix results are the derivatives of the diagnostic variables with respect to the prognostic variables, e.g.

$$\delta^* x_l = \frac{\partial T_{B,l}}{\partial x} \quad (1.3)$$

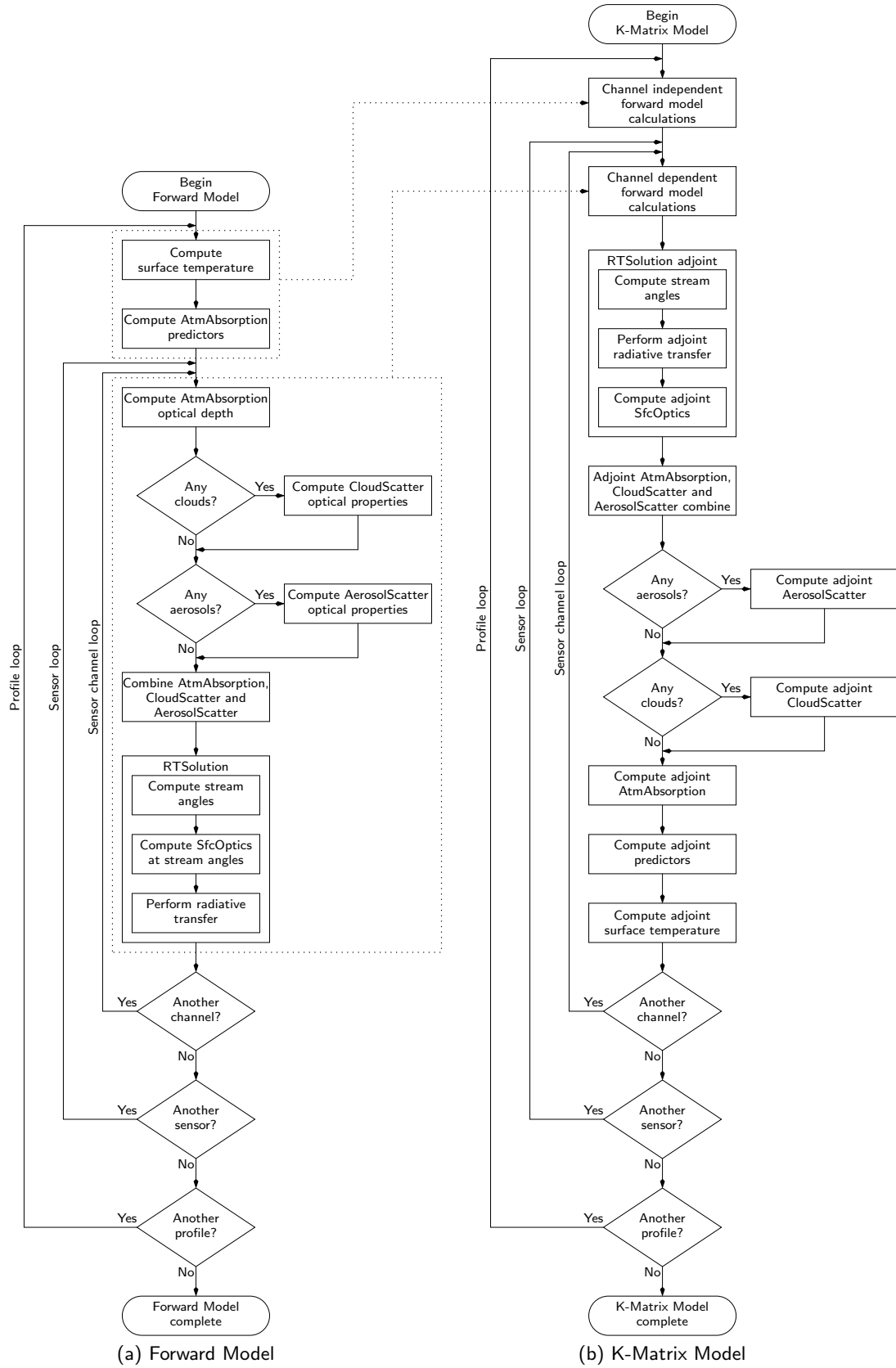
Typically, only the forward or K-matrix models are used in applications. However, the intermediate models are generated and retained for maintenance and testing purposes. Any changes to the CRTM forward model are translated to the tangent-linear model and the latter tested against the former. When the tangent-linear model changes have been verified, the changes then translated to the adjoint model and, as before, the latter is tested against the former. This process is repeated for the adjoint-to-K-matrix models also.

## 1.4 Design Framework

---

This document is not really the place to fully discuss the design framework of the CRTM, so it will only be briefly mentioned here. Where appropriate, different physical processes are isolated into their own modules. The CRTM interfaces presented to the user are, at their core, simply drivers for the individual parts. This is shown schematically in the forward and K-matrix model flowcharts of figure 1.1.

A fundamental tenet of the CRTM design is that each component define its own structure definition and application modules to facilitate independent development of an algorithm outside of the mainline CRTM development. By isolating different processes, we can more easily identify requirements for an algorithm with a view to minimise or eliminate potential software conflicts and/or redundancies. The end result sought via this approach is that components developed by different groups can more easily be added into the framework leading to faster implementation of new science and algorithms.



**Figure 1.1:** Flowchart of the CRTM Forward and K-Matrix models.

## *How to obtain the CRTM*

### 2.1 CRTM ftp download site

---

The CRTM source code and coefficients are released in a compressed tarball<sup>1</sup> via the CRTM ftp site:

<ftp://ftp.emc.ncep.noaa.gov/jcsda/CRTM/>

The REL-2.0.4 release is available directly from

<ftp://ftp.emc.ncep.noaa.gov/jcsda/CRTM/REL-2.0.4>

Also note that additional releases, e.g. beta or experimental branches, may also be made available on this ftp site.

### 2.2 Coefficient Data

---

All of the transmittance, spectral, cloud, aerosol, and emissivity coefficient data needed by the CRTM are available in the `fix`/<sup>2</sup> subdirectory. The coefficient directory structure is organised by coefficient and format type as shown in figure 2.1.

Both big- and little-endian format files are provided to save users the trouble of switching what they use for their system<sup>3</sup>. Note in the `TauCoeff` directory there are two subdirectories: `ODAS` and `ODPS`. These directories correspond to the coefficient files for the different transmittance model algorithms. The user can select which algorithm to use by using the corresponding `TauCoeff` file.

To run the CRTM, all the required coefficient files need to be in the same path (see the [CRTM initialisation function](#) description) so users will have to move/link the datafiles as required.

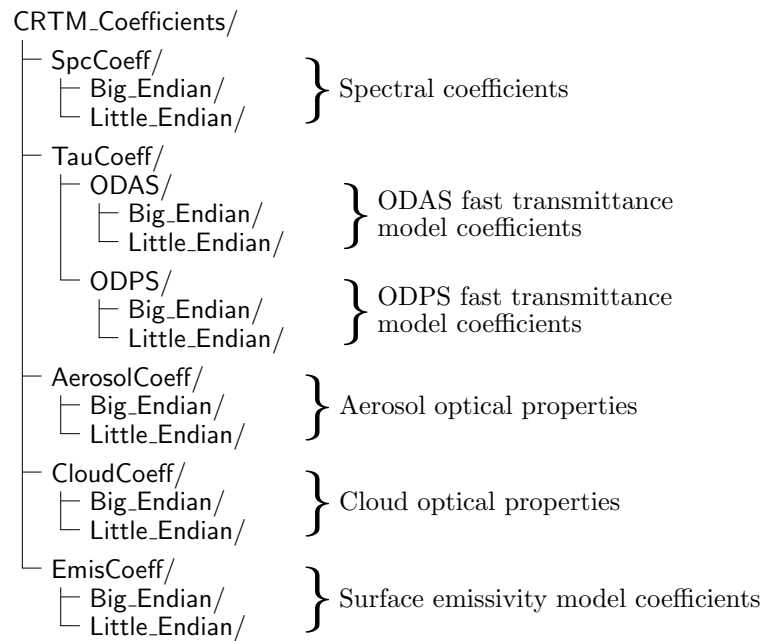
---

<sup>1</sup>A compressed (e.g. gzip'd) tape archive (tar) file.

<sup>2</sup>The directory name "fix" is an NCEP standard name for a location containing files that do not change (frequently), i.e. they are "fixed".

<sup>3</sup>All of the supplied configurations for little-endian platforms described in Section 3 use compiler switches to default to big-endian format.





**Figure 2.1:** The CRTM coefficients directory structure

## *How to build the CRTM library*

### 3.1 Build Files

The build system for the CRTM is currently quite unsophisticated. It consists of a number of make, include, and configuration files in the CRTM tarball hierarchy:

**makefile** : The main makefile  
**make.macros** : The include file containing the defined macros.  
**make.rules** : The include file containing the suffix rules for compiling Fortran95/2003 source code.  
**configure** : The directory containing build environment definitions.

### 3.2 Predefined Configuration Files

The build makefiles now assumes that environment variables (envars) will be defined that describe the compilation and link environment. The envars that *must* be defined are:

**FC** : the Fortran95/2003 compiler executable,  
**FC\_FLAGS** : the flags/switches provided to the Fortran compiler,  
**FL** : the linker used to create the executable test/example programs, and  
**FL\_FLAGS** : the flags/switches provided to the linker.

Several shell source files are provided for the build environment definitions for the compilers to which we have access and have tested here at the JCSDA. These shell source files are in the **configure** subdirectory of the tarball. The configuration files provided are shown in table 3.1. Both “production” and debug configurations are supplied, with the former using compiler switches to produce fast code and the latter using compiler switches to turn on all the available debugging capabilities. Note that the debug configurations will produce executables much slower than the production builds.

| Platform | Compiler     | Production     | Debug                |
|----------|--------------|----------------|----------------------|
| Linux    | GNU gfortran | gfortran.setup | gfortran.debug.setup |
|          | Intel ifort  | intel.setup    | intel.debug.setup    |
|          | PGI pgf95    | pgi.setup      | pgi.debug.setup      |
|          | g95          | g95.setup      | g95.debug.setup      |
| IBM      | AIX xlf95    | xlf.setup      | xlf.debug.setup      |

**Table 3.1:** Supplied configuration files for the CRTM library and test/example program build.

## 3.3 Compilation Environment Setup

---

To set the compilation envvars for your CRTM build, you need to source the required “setup” file. For example, to use gfortran to build the CRTM you would type

```
. configure/gfortran.setup
```

in the main directory. Note the “.” and space preceding the filename. This should print out something like the following:

```
=====
CRTM compilation environment variables:
FC:      gfortran
FC_FLAGS: -c -O3 -fconvert=big-endian -ffast-math -ffree-form
          -fno-second-underscore -frecord-marker=4 -funroll-loops
          -ggdb -static -Wall
FL:      gfortran
FL_FLAGS:
=====
```

indicating the values to which the envvars have been set.

Change the supplied setups to suit your needs. If you use a different compiler please consider submitting your compilation setup to be included in future releases.

Note that as of CRTM v2.0, the Fortran compiler needs to be compatible with the ISO TR-15581 Allocatable Enhancements update to Fortran95. Most current Fortran95 compilers do support TR-15581.

## 3.4 Building the library

---

Once the compilation environment has been set, the CRTM library build is performed by simply typing,

```
make
```

If you are using the DEBUG compiler flags you may, unfortunately, see many warnings similar to:

```
Warning (137): Variable 'cosaz' at (1) is never used and never set
Warning (112): Variable 'rlongitude' at (1) is set but never used
Warning (140): Implicit conversion at (1) may cause precision loss
Warning: Unused dummy argument 'group_index' at (1)
PGF90-I-0035-Predefined intrinsic scale loses intrinsic property
etc..
```

The actual format of the warning message depends on the compiler. We are working on eliminating these warning messages.

## 3.5 Testing the library

---

Several test/example programs exercising the forward and K-matrix functions have been supplied with the CRTM. To build and run all these tests, type,

```
make test
```

This process does generate a lot of output to screen so be prepared to scroll through it. Currently there are five forward model test, or example, programs:

```
test/forward/Example1_Simple
test/forward/Example2_SSU
test/forward/Example3_Zeeman
test/forward/Example4_ODPS
test/forward/Example5_ClearSky
```

And there are four cases for the K-matrix model:

```
test/k_matrix/Example1_Simple
test/k_matrix/Example2_SSU
test/k_matrix/Example3_Zeeman
test/k_matrix/Example4_ODPS
```

Both the forward and K-matrix tests *should* end with output that looks like:

```
=====
SUMMARY OF ALL RESULTS
=====

Passed 14 of 14 tests.
Failed 0 of 14 tests.
```

Currently they both have the same number of tests. If you encounter failures you might see something like:

```
=====
SUMMARY OF ALL RESULTS
=====

Passed 10 of 14 tests.
Failed 4 of 14 tests.  <----<<<  **WARNING**
```

Some important things to note about the tests:

- The supplied results were generated using the gfortran DEBUG build.
- Comparisons between DEBUG and PRODUCTION builds can be different due to various compiler switches that modify floating point arithmetic (e.g. optimisation levels), or different hardware.
- For test failures, you can view the differences between the generated and supplied ASCII output files. For example, to view the K-matrix **Example1\_Simple** test case differences for the **amsua\_metop-a** sensor you would do something like:

```
$ cd test/k_matrix/Example1_Simple
$ diff -u amsua_metop-a.output results/amsua_metop-a.output | more
```

where the **amsua\_metop-a.output** file is generated during the test run, and the **results/amsua\_metop-a.output** file is supplied with the CRTM tarball.

## 3.6 Installing the library

---

A very simple install target is specified in the supplied makefile to put all the necessary include files (the generated \*.mod files containing all the procedure interface information) in an **/include** subdirectory and the library itself (the generated libCRTM.a file) in a **/lib** subdirectory. The make command is

```
make install
```

The **/include** and **/lib** subdirectories can then be copied/moved/linked to a more suitable location on your system, for example: **\$HOME/local/CRTM**

NOTE: Currently, running the tests also invokes this install target. That will change in future tarball releases so do not rely on the behaviour.

## 3.7 Clean Up

---

Two cleanup targets are provided in the makefile:

```
make clean
```

Removes all the compilation and link products from the **libsrc/** directory.

```
make distclean
```

This does the same as the “clean” target but also deletes the library and include directories created by the “install” target.

## 3.8 Linking to the library

---

Let’s assume you’ve built the CRTM library and placed the **/include** and **/lib** subdirectories in your own local area, **\$HOME/local/CRTM**. In the makefile for your application that uses the CRTM, you will need to add

```
-I$HOME/local/CRTM/include
```

to your list of compilation switches, and the following to your list of link switches,

```
-L$HOME/local/CRTM/lib -lcrtm
```

## *How to use the CRTM library*

### 4.1 Step by Step Guide

This section will hopefully get you started using the CRTM library as quickly as possible. Refer to the following sections for more information about the structures and interfaces.

The examples shown here assume you are processing one sensor at a time. The CRTM can handle multiple sensors at once, but specifying the input information in a simple way is difficult; e.g. the [Geometry](#) structure that is used to specify the sensor viewing geometry – even sensors on the same platform typically have different numbers of fields-of-view (FOVs) per scan. For multiple sensor processing, we’ll assume they will be separately processed in parallel.

Because there are many variations in what information is known ahead of time (and by “ahead of time” we mean at compile-time of your code), let’s approach this via examples for a fixed number of atmospheric profiles, and a known sensors. It is left as an exercise to the reader to tailor calls to the CRTM in their application code according to their particular needs.

With regards to sensor identification, the CRTM uses a character string – referred to as the **Sensor\_Id** – to distinguish sensors and platforms. The lists of currently supported sensors, along with their associated **Sensor\_Id**’s, are shown in [appendix B](#).

#### 4.1.1 Step 1: Access the CRTM module

All of the CRTM user procedures, parameters, and derived data type definitions are accessible via the container module **CRTM\_Module**. Thus, one needs to put the following statement in any calling program, module or procedure,

```
USE CRTM_Module
```

Once you become familiar with the components of the CRTM you require, you can also specify an **ONLY** clause with the **USE** statement,

```
USE CRTM_Module[, ONLY:only-list]
```

where *only-list* is a list of the symbols you want to “import” from **CRTM\_Module**. This latter form is the preferred style for self-documenting your code; e.g. when you give the code to someone else, they will be able to identify from which module various symbols in your code originate.

#### 4.1.2 Step 2: Declare the CRTM structures

To compute satellite radiances you need to declare structures for the following information,

1. Atmospheric profile data such as pressure, temperature, absorber amounts, clouds, aerosols, etc. Handled using the [Atmosphere](#) structure.

2. Surface data such as type of surface, temperature, surface type specific parameters etc. Handled using the [Surface](#) structure.
3. Geometry information such as sensor scan angle, zenith angle, etc. Handled using the [Geometry](#) structure.
4. Instrument information, particularly which instrument(s), or sensor(s)<sup>1</sup>, you want to simulate. Handled using the [ChannelInfo](#) structure.
5. Results of the radiative transfer calculation. Handled using the [RTSolution](#) structure.
6. Optional inputs. Handled using the [Options](#) structure.

Let's assume you want to process, say, 50 profiles for the NOAA-18 AMSU-A sensor which has 15 channels. The forward model declarations would look something like,

```
! Processing parameters
INTEGER      , PARAMETER :: N_SENSORS  =  1
INTEGER      , PARAMETER :: N_CHANNELS = 15
INTEGER      , PARAMETER :: N_PROFILES = 50
CHARACTER(*) , PARAMETER :: SENSOR_ID(N_SENSORS) = ('amsua_n18')
TYPE(CRTM_ChannelInfo_type) :: chInfo(N_SENSORS)
TYPE(CRTM_Geometry_type)    :: geo(N_PROFILES)
TYPE(CRTM_Options_type)     :: opt(N_PROFILES)
! Forward declarations
TYPE(CRTM_Atmosphere_type)  :: atm(N_PROFILES)
TYPE(CRTM_Surface_type)     :: sfc(N_PROFILES)
TYPE(CRTM_RTSolution_type)  :: rts(N_CHANNELS,N_PROFILES)
```

If you are also interested in calling the K-matrix model, you will also need the following declarations,

```
! K-Matrix declarations
TYPE(CRTM_Atmosphere_type) :: atm_K(N_CHANNELS,N_PROFILES)
TYPE(CRTM_Surface_type)    :: sfc_K(N_CHANNELS,N_PROFILES)
TYPE(CRTM_RTSolution_type) :: rts_K(N_CHANNELS,N_PROFILES)
```

### 4.1.3 Step 3: Initialise the CRTM

The CRTM is initialised by calling the [CRTM\\_Init\(\)](#) function. This loads all the various coefficient data used by CRTM components into memory for later use. We'll assume that all the required datafiles reside in the subdirectory `./coeff_data` and follow on from the example of Step 2. The CRTM initialisation is profile independent, so we're only dealing with sensor information here. The CRTM initialisation function call looks like,

```
INTEGER :: errStatus
....
errStatus = CRTM_Init( SENSOR_ID, chInfo, File_Path='./coeff_data' )
IF ( errStatus /= SUCCESS ) THEN
    handle error...
END IF
```

Here we see for the first time how the CRTM functions let you know if they were successful. As you can see the [CRTM\\_Init\(\)](#) function result is an error status that is checked against a parameterised integer error code, `SUCCESS`. The function result should *not* be tested against the actual value of the error code, just its parameterised name. Other available error code parameters are `FAILURE`, `WARNING`, and `INFORMATION` – although the latter is never used as a function result.

For a list of all the accepted sensor identifiers, see appendix [B](#).

---

<sup>1</sup>The terms “instrument” and “sensor” are used interchangeably in this document.

#### 4.1.4 Step 4: Allocate the CRTM structures

Now we need to create instances of the various CRTM structures where necessary to hold the input or output data. Functions are used to perform any necessary component allocations. The function naming convention is `CRTM_object_Create` where, for typical usage, the CRTM structures that need to be allocated are the [Atmosphere](#), [RTSolution](#) and, if used, [Options](#) structures. Potentially, the [SensorData](#) component of the [Surface](#) structure may also need to be allocated to allow for input of sensor observations for some of the NESDIS microwave surface emissivity models.

##### Allocation of the Atmosphere structures

First, we'll allocate the atmosphere structures to the required dimensions. The forward variable is allocated like so:

```
! Allocate the forward atmosphere structure
CALL CRTM_Atmosphere_Create( atm      , & ! Object
                           n_Layers  , & ! Input
                           n_Absorbers, & ! Input
                           n_Clouds  , & ! Input
                           n_Aerosols ) ! Input

! Check it was actually allocated
IF ( ANY(.NOT. CRTM_Atmosphere_Associated( atm )) ) THEN
  handle error...
END IF
```

and the K-matrix variable is allocated by looping over all profiles<sup>2</sup>,

```
! Allocate the K-matrix atmosphere structure
DO m = 1, N_PROFILES
  CALL CRTM_Atmosphere_Create( atm_k(:,m) , & ! Object
                              n_Layers    , & ! Input
                              n_Absorbers , & ! Input
                              n_Clouds    , & ! Input
                              n_Aerosols   ) ! Input

  ! Check they were actually allocated
  IF ( ANY(.NOT. CRTM_Atmosphere_Associated( atm_k(:,m) )) ) THEN
    handle error...
  END IF
END DO
```

Note that for the ODAS algorithm the allowed number of absorbers is at most two: that of H<sub>2</sub>O and O<sub>3</sub>. For the ODPS algorithm, CO<sub>2</sub> can also be specified. In future releases, trace gases such as CO, CH<sub>4</sub>, and N<sub>2</sub>O will also be accepted as input.

##### Allocation of the RTSolution structure

To return additional information used in the radiative transfer calculations, such as [upwelling radiance and layer optical depth profiles](#), the RTSolution structure must be allocated to the number of atmospheric layers used:

```
! Allocate the RTSolution structure
CALL CRTM_RTSolution_Create( rts      , & ! Object
                           n_Layers  ) ! Input
```

---

<sup>2</sup>The `CRTM_Atmosphere_Create` function is defined as elemental so the profile loop is not strictly needed



```

! Check it was actually allocated
IF ( ANY(.NOT. CRTM_RTSolution_Associated( rts )) ) THEN
    handle error...
END IF

```

Note that internal checks are performed in the CRTM to determine if the RTSolution structure has been allocated before its array components are accessed. Thus, if the additional information is not required, the RTSolution structure does not need to be allocated. Also, the extra information returned is only applicable to the forward model, not any of the tangent-linear, adjoint, or K-matrix models.

### Allocation of the Options structure

If user-supplied surface emissivity data is to be used, then the options structure must first be allocated to the necessary number of channels:

```

! Allocate the options structure
CALL CRTM_Options_Create( opt      , & ! Object
                        n_Channels ) ! Input
! Check it was actually allocated
IF ( ANY(.NOT. CRTM_Options_Associated( opt )) ) THEN
    handle error...
END IF

```

If no emissivities are to be input, the options structure does not need to be allocated.

#### 4.1.5 Step 5: Fill the CRTM input structures with data

This step simply entails filling the input `atm`, `sfc`, `geo`, and, if used, `opt` structures with the required information. However, there are some issues that need to be mentioned:

- In the CRTM, all profile layering is from top-of-atmosphere (TOA) to surface (SFC). So, for an atmospheric profile layered as  $k = 1, 2, \dots, K$ , layer 1 is the TOA layer and layer  $K$  is the SFC layer.
- In the `Atmosphere` structure, the `Climatology` component is not yet used.
- In the `Atmosphere` structure, *both* the level and layer pressure profiles must be specified.
- In the `Atmosphere` structure, the absorber profile data units *must* be mass mixing ratio for water vapour and ppmv for other absorbers. The `Absorber.Units` component is not yet utilised to allow conversion of different user-supplied concentration units.
- In the `Atmosphere` structure, the `Absorber.Id` array must be set to the correct absorber identifiers (see table A.2) to allow the software to find a particular absorber. There is no necessary order in specifying the concentration profiles for different gaseous absorbers.
- In the `Surface` structure, the sum of the coverage types *must* add up to 1.0.
- In the `Geometry` structure, the sensor zenith and sensor scan angles should be consistent.
- Graphical definitions of the `Geometry` structure sensor scan, sensor zenith, sensor azimuth, source zenith, and source azimuth angles are shown in figures A.8, A.9, A.10, A.11, and A.12 respectively.
- The `Options` structure contains two “substructures”, `SSU.Input` and `Zeeman.Input` to hold the necessary inputs for the SSU and Zeeman transmittance models. These substructures are private and can only be access via “GetValue” and “SetValue” functions as discussed further below.

For the K-matrix structures, you should zero the K-matrix *outputs*, `atm_K`, `sfc_K`,

```
! Zero the K-matrix OUTPUT structures
CALL CRTM_Atmosphere_Zero( atm_K )
CALL CRTM_Surface_Zero( sfc_K )
```

and initialise the K-matrix *input*, `rts_K`, to provide you with the derivatives you want. For example, if you want the `atm_K`, `sfc_K` outputs to contain brightness temperature derivatives, you should initialise `rts_K` like so,

```
! Initialise the K-Matrix INPUT to provide dTb/dx derivatives
rts_K%Radiance = ZERO
rts_K%Brightness_Temperature = ONE
```

Alternatively, if you want radiance derivatives returned in `atm_K` and `sfc_K`, the `rts_K` structure should be initialised like so,

```
! Initialise the K-Matrix INPUT to provide dR/dx derivatives
rts_K%Radiance = ONE
rts_K%Brightness_Temperature = ZERO
```

### Filling the Options substructures for SSU and Zeeman model input

As mentioned above, the `SSU_Input` and `Zeeman_Input` data structures are private. This means the contents of the structure cannot be accessed directly, but via helper subroutines. For example, to set the SSU instrument mission time, one would call the `SSU_Input_SetValue` subroutine,

```
! Set the SSU input data in the options substructure
CALL SSU_Input_SetValue( opt%SSU_Input , & ! Object
                        Time=mission_time ) ! Optional input
```

where the local variable `mission_time` contains the required time.

Similarly for the necessary Zeeman model parameters,

```
! Set the Zeeman input data in the options substructure
CALL Zeeman_Input_SetValue( opt%Zeeman_Input , & ! Object
                          Field_Strength=Be , & ! Optional input
                          Cos_ThetaB =angle ) ! Optional input
```

where, again, `Be` and `angle` are the local variables for the necessary data.

#### 4.1.6 Step 6: Call the required CRTM function

At this point, much of the preparatory heavy lifting has been done. The CRTM function calls themselves are quite simple. For the forward model we do,

```
errStatus = CRTM_Forward( atm      , & ! Input
                        sfc      , & ! Input
                        geo      , & ! Input
                        chInfo   , & ! Input
                        rts      , & ! Output
                        Options=opt ) ! Optional input
IF ( errStatus /= SUCCESS ) THEN
    handle error...
END IF
```

and for the K-matrix model, the calling syntax is,

```
errStatus = CRTM_K_Matrix( atm      , & ! Forward input
                          sfc      , & ! Forward input
                          rts_K    , & ! K-matrix input
                          geo      , & ! Input
                          chInfo   , & ! Input
                          atm_K    , & ! K-matrix output
                          sfc_K    , & ! K-matrix output
                          rts      , & ! Forward output
                          Options=opt ) ! Optional input
IF ( errStatus /= SUCCESS ) THEN
    handle error...
END IF
```

Note that the K-matrix model also returns the forward model radiances. The [tangent-linear](#) and [adjoint](#) models have similar call structures and will not be shown here.

#### 4.1.7 Step 7: Destroy the CRTM and cleanup

The last step is to cleanup. This involves calling the CRTM destruction function

```
errStatus = CRTM_Destroy( chInfo )
IF ( errStatus /= SUCCESS ) THEN
    handle error...
END IF
```

to deallocate all the shared coefficient data, as well as calling the individual structure destroy functions to deallocate as required. For the example here, that entails deallocating the various structure arrays that were created in Step [4.1.4](#). The cleanup mirrors that of the create step:

```
CALL CRTM_Options_Destroy(opt)
CALL CRTM_RTSolution_Destroy(rts)
CALL CRTM_Atmosphere_Destroy(atm_K)
CALL CRTM_Atmosphere_Destroy(atm)
```

## 4.2 Interface Descriptions

---

### 4.2.1 CRTM\_Init interface

NAME:

CRTM\_Init

PURPOSE:

Function to initialise the CRTM.

CALLING SEQUENCE:

```
Error_Status = CRTM_Init( Sensor_ID      , &
                          ChannelInfo    , &
                          CloudCoeff_File = CloudCoeff_File , &
                          AerosolCoeff_File = AerosolCoeff_File, &
```

```

EmisCoeff_File      = EmisCoeff_File      , &
File_Path           = File_Path           , &
Load_CloudCoeff     = Load_CloudCoeff     , &
Load_AerosolCoeff   = Load_AerosolCoeff   , &
Quiet               = Quiet               , &
Process_ID          = Process_ID          , &
Output_Process_ID   = Output_Process_ID   )

```

#### INPUTS:

**Sensor\_ID:** List of the sensor IDs (e.g. hirs3\_n17, amsua\_n18, ssmis\_f16, etc) with which the CRTM is to be initialised. These sensor ids are used to construct the sensor specific SpcCoeff and TauCoeff filenames containing the necessary coefficient data, i.e.

<Sensor\_ID>.SpcCoeff.bin

and

<Sensor\_ID>.TauCoeff.bin

for each sensor Id in the list.

UNITS: N/A

TYPE: CHARACTER(\*)

DIMENSION: Rank-1 (n\_Sensors)

ATTRIBUTES: INTENT(IN), OPTIONAL

#### OUTPUTS:

**ChannelInfo:** ChannelInfo structure array populated based on the contents of the coefficient files and the user inputs.

UNITS: N/A

TYPE: CRTM\_ChannelInfo\_type

DIMENSION: Same as input Sensor\_Id argument

ATTRIBUTES: INTENT(OUT)

#### OPTIONAL INPUTS:

**CloudCoeff\_File:** Name of the CRTM Binary format CloudCoeff file containing the scattering coefficient data. If not specified the default filename is "CloudCoeff.bin".

UNITS: N/A

TYPE: CHARACTER(\*)

DIMENSION: Scalar

ATTRIBUTES: INTENT(IN), OPTIONAL

**AerosolCoeff\_File:** Name of the CRTM Binary format AerosolCoeff file containing the aerosol absorption and scattering coefficient data. If not specified the default filename is "AerosolCoeff.bin".

UNITS: N/A

TYPE: CHARACTER(\*)

DIMENSION: Scalar

ATTRIBUTES: INTENT(IN), OPTIONAL

**EmisCoeff\_File:** Name of the CRTM Binary format EmisCoeff file containing the IRSSEM coefficient data. If not specified the default filename is "EmisCoeff.bin".

UNITS: N/A

TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**File\_Path:** Character string specifying a file path for the input data files. If not specified, the current directory is the default.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**Load\_CloudCoeff:** Set this logical argument for not loading the CloudCoeff data to save memory space under the clear conditions  
 If == .FALSE., the CloudCoeff data will not be loaded;  
     == .TRUE., the CloudCoeff data will be loaded.  
 If not specified, default is .TRUE. (will be loaded)  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**Load\_AerosolCoeff:** Set this logical argument for not loading the AerosolCoeff data to save memory space under the clear conditions  
 If == .FALSE., the AerosolCoeff data will not be loaded;  
     == .TRUE., the AerosolCoeff data will be loaded.  
 If not specified, default is .TRUE. (will be loaded)  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**Quiet:** Set this logical argument to suppress INFORMATION messages being printed to stdout  
 If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
     == .TRUE., INFORMATION messages are SUPPRESSED.  
 If not specified, default is .FALSE.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**Process\_ID:** Set this argument to the MPI process ID that this function call is running under. This value is used solely for controlling INFORMATION message output. If MPI is not being used, ignore this argument. This argument is ignored if the Quiet argument is set.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

**Output\_Process\_ID:** Set this argument to the MPI process ID in which all INFORMATION messages are to be output. If

the passed Process\_ID value agrees with this value  
the INFORMATION messages are output.  
This argument is ignored if the Quiet argument  
is set.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### **FUNCTION RESULT:**

Error\_Status: The return value is an integer defining the error  
status. The error codes are defined in the  
Message\_Handler module.  
If == SUCCESS the CRTM initialisation was successful  
== FAILURE an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### **SIDE EFFECTS:**

All public data arrays accessed by this module and its dependencies  
are overwritten.

#### **RESTRICTIONS:**

If specified, the length of the combined file path and filename strings  
cannot exceed 2000 characters.

### *4.2.2 CRTM\_Forward interface*

#### **NAME:**

CRTM\_Forward

#### **PURPOSE:**

Function that calculates top-of-atmosphere (TOA) radiances  
and brightness temperatures for an input atmospheric profile or  
profile set and user specified satellites/channels.

#### **CALLING SEQUENCE:**

```
Error_Status = CRTM_Forward( Atmosphere      , &
                             Surface         , &
                             Geometry        , &
                             ChannelInfo     , &
                             RTSolution      , &
                             Options = Options )
```

#### **INPUTS:**

Atmosphere: Structure containing the Atmosphere data.  
UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Rank-1 (n\_Profiles)

ATTRIBUTES: INTENT(IN)

Surface: Structure containing the Surface data.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Same as input Atmosphere structure  
ATTRIBUTES: INTENT(IN)

Geometry: Structure containing the view geometry  
information.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type  
DIMENSION: Same as input Atmosphere structure  
ATTRIBUTES: INTENT(IN)

ChannelInfo: Structure returned from the CRTM\_Init() function  
that contains the satellite/sensor channel index  
information.  
UNITS: N/A  
TYPE: CRTM\_ChannelInfo\_type  
DIMENSION: Rank-1 (n\_Sensors)  
ATTRIBUTES: INTENT(IN)

#### OUTPUTS:

RTSolution: Structure containing the solution to the RT equation  
for the given inputs.  
UNITS: N/A  
TYPE: CRTM\_RTSolution\_type  
DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
ATTRIBUTES: INTENT(IN OUT)

#### OPTIONAL INPUTS:

Options: Options structure containing the optional arguments  
for the CRTM.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Same as input Atmosphere structure  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS the computation was successful  
== FAILURE an unrecoverable error occurred  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### COMMENTS:

- The Options optional input structure argument contains spectral information (e.g. emissivity) that must have the same spectral dimensionality (the "L" dimension) as the output RTSolution structure.

- The INTENT on the output RTSolution argument is IN OUT rather than just OUT. This is necessary because the argument may be defined upon input. To prevent memory leaks, the IN OUT INTENT is a must.

### 4.2.3 CRTM\_Tangent\_Linear interface

#### NAME:

CRTM\_Tangent\_Linear

#### PURPOSE:

Function that calculates tangent-linear top-of-atmosphere (TOA) radiances and brightness temperatures for an input atmospheric profile or profile set and user specified satellites/channels.

#### CALLING SEQUENCE:

```
Error_Status = CRTM_Tangent_Linear( Atmosphere      , &
                                     Surface          , &
                                     Atmosphere_TL     , &
                                     Surface_TL        , &
                                     Geometry           , &
                                     ChannelInfo        , &
                                     RTSolution         , &
                                     RTSolution_TL      , &
                                     Options = Options  )
```

#### INPUTS:

|                |   |
|----------------|---|
| Atmosphere:    | Structure containing the Atmosphere data.<br>UNITS: N/A<br>TYPE: CRTM_Atmosphere_type<br>DIMENSION: Rank-1 (n_Profiles)<br>ATTRIBUTES: INTENT(IN)                               |
| Surface:       | Structure containing the Surface data.<br>UNITS: N/A<br>TYPE: CRTM_Surface_type<br>DIMENSION: Same as input Atmosphere structure<br>ATTRIBUTES: INTENT(IN)                      |
| Atmosphere_TL: | Structure containing the tangent-linear Atmosphere data.<br>UNITS: N/A<br>TYPE: CRTM_Atmosphere_type<br>DIMENSION: Same as input Atmosphere structure<br>ATTRIBUTES: INTENT(IN) |
| Surface_TL:    | Structure containing the tangent-linear Surface data.<br>UNITS: N/A<br>TYPE: CRTM_Surface_type<br>DIMENSION: Same as input Atmosphere structure<br>ATTRIBUTES: INTENT(IN)       |



Geometry: Structure containing the view geometry information.  
 UNITS: N/A  
 TYPE: CRTM\_Geometry\_type  
 DIMENSION: Same as input Atmosphere structure  
 ATTRIBUTES: INTENT(IN)

ChannelInfo: Structure returned from the CRTM\_Init() function that contains the satellite/sensor channel index information.  
 UNITS: N/A  
 TYPE: CRTM\_ChannelInfo\_type  
 DIMENSION: Rank-1 (n\_Sensors)  
 ATTRIBUTES: INTENT(IN)

OUTPUTS:

RTSolution: Structure containing the solution to the RT equation for the given inputs.  
 UNITS: N/A  
 TYPE: CRTM\_RTSolution\_type  
 DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
 ATTRIBUTES: INTENT(IN OUT)

RTSolution\_TL: Structure containing the solution to the tangent-linear RT equation for the given inputs.  
 UNITS: N/A  
 TYPE: CRTM\_RTSolution\_type  
 DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
 ATTRIBUTES: INTENT(IN OUT)

OPTIONAL INPUTS:

Options: Options structure containing the optional forward model arguments for the CRTM.  
 UNITS: N/A  
 TYPE: CRTM\_Options\_type  
 DIMENSION: Same as input Atmosphere structure  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status. The error codes are defined in the Message\_Handler module.  
 If == SUCCESS the computation was successful  
 == FAILURE an unrecoverable error occurred  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar

COMMENTS:

- The Options optional input structure arguments contain spectral information (e.g. emissivity) that must have the same spectral dimensionality (the "L" dimension) as the output RTSolution structures.
- The INTENT on the output RTSolution arguments are IN OUT rather

than just OUT. This is necessary because the arguments may be defined upon input. To prevent memory leaks, the IN OUT INTENT is a must.

#### 4.2.4 CRTM\_Adjoint interface

NAME:

CRTM\_Adjoint

PURPOSE:

Function that calculates the adjoint of top-of-atmosphere (TOA) radiances and brightness temperatures for an input atmospheric profile or profile set and user specified satellites/channels.

CALLING SEQUENCE:

```
Error_Status = CRTM_Adjoint( Atmosphere      , &
                             Surface         , &
                             RTSolution_AD   , &
                             Geometry        , &
                             ChannelInfo     , &
                             Atmosphere_AD   , &
                             Surface_AD      , &
                             RTSolution      , &
                             Options = Options )
```

INPUTS:

Atmosphere: Structure containing the Atmosphere data.  
UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Rank-1 (n\_Profiles)  
ATTRIBUTES: INTENT(IN)

Surface: Structure containing the Surface data.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Same as input Atmosphere structure  
ATTRIBUTES: INTENT(IN)

RTSolution\_AD: Structure containing the RT solution adjoint inputs.  
\*\*NOTE: On EXIT from this function, the contents of this structure may be modified (e.g. set to zero.)  
UNITS: N/A  
TYPE: CRTM\_RTSolution\_type  
DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
ATTRIBUTES: INTENT(IN OUT)

Geometry: Structure containing the view geometry information.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type

DIMENSION: Same as input Atmosphere argument  
ATTRIBUTES: INTENT(IN)

ChannelInfo: Structure returned from the CRTM\_Init() function  
that contains the satellite/sensor channel index  
information.  
UNITS: N/A  
TYPE: CRTM\_ChannelInfo\_type  
DIMENSION: Rank-1 (n\_Sensors)  
ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Options: Options structure containing the optional forward model  
arguments for the CRTM.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Same as input Atmosphere structure  
ATTRIBUTES: INTENT(IN), OPTIONAL

OUTPUTS:

Atmosphere\_AD: Structure containing the adjoint Atmosphere data.  
\*\*NOTE: On ENTRY to this function, the contents of  
this structure should be defined (e.g.  
initialized to some value based on the  
position of this function in the call chain.)  
UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Same as input Atmosphere argument  
ATTRIBUTES: INTENT(IN OUT)

Surface\_AD: Structure containing the tangent-linear Surface data.  
\*\*NOTE: On ENTRY to this function, the contents of  
this structure should be defined (e.g.  
initialized to some value based on the  
position of this function in the call chain.)  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Same as input Atmosphere argument  
ATTRIBUTES: INTENT(IN OUT)

RTSolution: Structure containing the solution to the RT equation  
for the given inputs.  
UNITS: N/A  
TYPE: CRTM\_RTSolution\_type  
DIMENSION: Same as input RTSolution\_AD argument  
ATTRIBUTES: INTENT(IN OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS the computation was successful  
== FAILURE an unrecoverable error occurred  
UNITS: N/A  
TYPE: INTEGER

DIMENSION: Scalar

SIDE EFFECTS:

Note that the input adjoint arguments are modified upon exit, and the output adjoint arguments must be defined upon entry. This is a consequence of the adjoint formulation where, effectively, the chain rule is being used and this function could reside anywhere in the chain of derivative terms.

COMMENTS:

- The Options optional structure arguments contain spectral information (e.g. emissivity) that must have the same spectral dimensionality (the "L" dimension) as the RTSolution structures.
- The INTENT on the output RTSolution, Atmosphere\_AD, and Surface\_AD arguments are IN OUT rather than just OUT. This is necessary because the arguments should be defined upon input. To prevent memory leaks, the IN OUT INTENT is a must.

#### 4.2.5 CRTM\_K\_Matrix interface

NAME:

CRTM\_K\_Matrix

PURPOSE:

Function that calculates the K-matrix of top-of-atmosphere (TOA) radiances and brightness temperatures for an input atmospheric profile or profile set and user specified satellites/channels.

CALLING SEQUENCE:

```
Error_Status = CRTM_K_Matrix( Atmosphere      , &
                               Surface         , &
                               RTSolution_K    , &
                               Geometry        , &
                               ChannelInfo     , &
                               Atmosphere_K    , &
                               Surface_K       , &
                               RTSolution      , &
                               Options = Options )
```

INPUTS:

|             |   |
|-------------|---|
| Atmosphere: | Structure containing the Atmosphere data. |
| UNITS:      | N/A                                       |
| TYPE:       | CRTM_Atmosphere_type                      |
| DIMENSION:  | Rank-1 (n_Profiles)                       |
| ATTRIBUTES: | INTENT(IN)                                |
| Surface:    | Structure containing the Surface data.    |
| UNITS:      | N/A                                       |

TYPE: CRTM\_Surface\_type  
 DIMENSION: Same as input Atmosphere argument.  
 ATTRIBUTES: INTENT(IN)

RTSolution\_K: Structure containing the RT solution K-matrix inputs.  
 \*\*NOTE: On EXIT from this function, the contents of this structure may be modified (e.g. set to zero.)  
 UNITS: N/A  
 TYPE: CRTM\_RTSolution\_type  
 DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
 ATTRIBUTES: INTENT(IN OUT)

Geometry: Structure containing the view geometry information.  
 UNITS: N/A  
 TYPE: CRTM\_Geometry\_type  
 DIMENSION: Same as input Atmosphere argument  
 ATTRIBUTES: INTENT(IN)

ChannelInfo: Structure returned from the CRTM\_Init() function that contains the satellite/sesnor channel index information.  
 UNITS: N/A  
 TYPE: CRTM\_ChannelInfo\_type  
 DIMENSION: Rank-1 (n\_Sensors)  
 ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Options: Options structure containing the optional forward model arguments for the CRTM.  
 UNITS: N/A  
 TYPE: CRTM\_Options\_type  
 DIMENSION: Same as input Atmosphere structure  
 ATTRIBUTES: INTENT(IN), OPTIONAL

OUTPUTS:

Atmosphere\_K: Structure containing the K-matrix Atmosphere data.  
 \*\*NOTE: On ENTRY to this function, the contents of this structure should be defined (e.g. initialized to some value based on the position of this function in the call chain.)  
 UNITS: N/A  
 TYPE: CRTM\_Atmosphere\_type  
 DIMENSION: Same as input RTSolution\_K argument  
 ATTRIBUTES: INTENT(IN OUT)

Surface\_K: Structure containing the tangent-linear Surface data.  
 \*\*NOTE: On ENTRY to this function, the contents of this structure should be defined (e.g. initialized to some value based on the position of this function in the call chain.)  
 UNITS: N/A  
 TYPE: CRTM\_Surface\_type

DIMENSION: Same as input RTSolution\_K argument  
ATTRIBUTES: INTENT(IN OUT)

RTSolution: Structure containing the solution to the RT equation  
for the given inputs.  
UNITS: N/A  
TYPE: CRTM\_RTSolution\_type  
DIMENSION: Same as input RTSolution\_K argument  
ATTRIBUTES: INTENT(IN OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS the computation was successful  
== FAILURE an unrecoverable error occurred  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

SIDE EFFECTS:

Note that the input K-matrix arguments are modified upon exit, and  
the output K-matrix arguments must be defined upon entry. This is  
a consequence of the K-matrix formulation where, effectively, the  
chain rule is being used and this function could reside anywhere  
in the chain of derivative terms.

COMMENTS:

- The Options optional structure arguments contain  
spectral information (e.g. emissivity) that must have the same  
spectral dimensionality (the "L" dimension) as the RTSolution  
structures.
- The INTENT on the output RTSolution, Atmosphere\_K, and Surface\_K,  
arguments are IN OUT rather than just OUT. This is necessary because  
the arguments should be defined upon input. To prevent memory leaks,  
the IN OUT INTENT is a must.

#### 4.2.6 CRTM\_Destroy interface

NAME:

CRTM\_Destroy

PURPOSE:

Function to deallocate all the shared data arrays allocated and  
populated during the CRTM initialization.

CALLING SEQUENCE:

```
Error_Status = CRTM_Destroy( ChannelInfo      , &  
                             Process_ID = Process_ID )
```

#### OUTPUTS:

ChannelInfo: Reinitialized ChannelInfo structure.  
UNITS: N/A  
TYPE: CRTM\_ChannelInfo\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN OUT)

#### OPTIONAL INPUTS:

Process\_ID: Set this argument to the MPI process ID that this function call is running under. This value is used solely for controlling message output. If MPI is not being used, ignore this argument.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status. The error codes are defined in the Message\_Handler module.  
If == SUCCESS the CRTM deallocations were successful  
== FAILURE an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### SIDE EFFECTS:

All CRTM shared data arrays and structures are deallocated.

#### COMMENTS:

Note the INTENT on the output ChannelInfo argument is IN OUT rather than just OUT. This is necessary because the argument may be defined upon input. To prevent memory leaks, the IN OUT INTENT is a must.

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A

*Structure and procedure interface definitions*

## A.1 ChannelInfo Structure

---

```
TYPE :: CRTM_ChannelInfo_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimensions
  INTEGER :: n_Channels = 0 ! L dimension
  ! Scalar data
  CHARACTER(STRLEN) :: Sensor_ID      = ''
  INTEGER           :: WMO_Satellite_ID = INVALID_WMO_SATELLITE_ID
  INTEGER           :: WMO_Sensor_ID   = INVALID_WMO_SENSOR_ID
  INTEGER           :: Sensor_Index    = 0
  ! Array data
  INTEGER, ALLOCATABLE :: Sensor_Channel(:) ! L
  INTEGER, ALLOCATABLE :: Channel_Index(:)  ! L
END TYPE CRTM_ChannelInfo_type
```

**Figure A.1:** CRTM\_ChannelInfo\_type structure definition.

### A.1.1 CRTM\_ChannelInfo Associated interface

**NAME:**

CRTM\_ChannelInfo\_Associated

**PURPOSE:**

Elemental function to test the status of the allocatable components of a CRTM ChannelInfo object.

**CALLING SEQUENCE:**

Status = CRTM\_ChannelInfo\_Associated( ChannelInfo )

**OBJECTS:**

ChannelInfo: ChannelInfo object which is to have its member's status tested.  
UNITS: N/A  
TYPE: TYPE(CRTM\_ChannelInfo\_type)  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN)

**FUNCTION RESULT:**

Status: The return value is a logical value indicating the status of the ChannelInfo members.  
.TRUE. - if the array components are allocated.  
.FALSE. - if the array components are not allocated.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Same as input ChannelInfo argument

### *A.1.2 CRTM\_ChannelInfo\_DefineVersion interface*

NAME:

CRTM\_ChannelInfo\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_ChannelInfo\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.1.3 CRTM\_ChannelInfo\_Destroy interface*

NAME:

CRTM\_ChannelInfo\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM ChannelInfo objects.

CALLING SEQUENCE:

CALL CRTM\_ChannelInfo\_Destroy( ChannelInfo )

OBJECTS:

ChannelInfo: Re-initialized ChannelInfo object.  
UNITS: N/A  
TYPE: TYPE(CRTM\_ChannelInfo\_type)  
DIMENSION: Scalar OR any rank  
ATTRIBUTES: INTENT(OUT)

### *A.1.4 CRTM\_ChannelInfo\_Inspect interface*

NAME:

CRTM\_ChannelInfo\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM ChannelInfo object  
to stdout.

CALLING SEQUENCE:

```
CALL CRTM_ChannelInfo_Inspect( ChannelInfo )
```

INPUTS:

```
ChannelInfo:  ChannelInfo object to display.
              UNITS:      N/A
              TYPE:      TYPE(CRTM_ChannelInfo_type)
              DIMENSION:  Scalar
              ATTRIBUTES: INTENT(IN)
```

### *A.1.5 CRTM\_ChannelInfo\_n\_Channels interface*

NAME:

```
CRTM_ChannelInfo_n_Channels
```

PURPOSE:

```
Function to return the number of channels defined in a ChannelInfo
structure or structure array
```

CALLING SEQUENCE:

```
n_Channels = CRTM_ChannelInfo_n_Channels( ChannelInfo )
```

INPUTS:

```
ChannelInfo: ChannelInfo structure or structure which is to have its
              channels counted.
              UNITS:      N/A
              TYPE:      TYPE(CRTM_ChannelInfo_type)
              DIMENSION:  Scalar
                        or
                        Rank-1
              ATTRIBUTES: INTENT(IN)
```

FUNCTION RESULT:

```
n_Channels:  The number of defined channels in the input argument.
              UNITS:      N/A
              TYPE:      INTEGER
              DIMENSION:  Scalar
```

## A.2 Atmosphere Structure

---

```
TYPE :: CRTM_Atmosphere_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimension values
  INTEGER :: Max_Layers    = 0  ! K dimension
  INTEGER :: n_Layers      = 0  ! Kuse dimension
  INTEGER :: n_Absorbers   = 0  ! J dimension
  INTEGER :: Max_Clouds    = 0  ! Nc dimension
  INTEGER :: n_Clouds      = 0  ! NcUse dimension
  INTEGER :: Max_Aerosols  = 0  ! Na dimension
  INTEGER :: n_Aerosols    = 0  ! NaUse dimension
  ! Number of added layers
  INTEGER :: n_Added_Layers = 0
  ! Climatology model associated with the profile
  INTEGER :: Climatology = US_STANDARD_ATMOSPHERE
  ! Absorber ID and units
  INTEGER, ALLOCATABLE :: Absorber_ID(:)    ! J
  INTEGER, ALLOCATABLE :: Absorber_Units(:) ! J
  ! Profile LEVEL and LAYER quantities
  REAL(fp), ALLOCATABLE :: Level_Pressure(:) ! 0:K
  REAL(fp), ALLOCATABLE :: Pressure(:)       ! K
  REAL(fp), ALLOCATABLE :: Temperature(:)    ! K
  REAL(fp), ALLOCATABLE :: Absorber(:, :)    ! K x J
  ! Clouds associated with each profile
  TYPE(CRTM_Cloud_type), ALLOCATABLE :: Cloud(:) ! Nc
  ! Aerosols associated with each profile
  TYPE(CRTM_Aerosol_type), ALLOCATABLE :: Aerosol(:) ! Na
END TYPE CRTM_Atmosphere_type
```

**Figure A.2:** CRTM\_Atmosphere\_type structure definition.

| <b>Climatology Type</b>  | <b>Parameter</b>       |
|--------------------------|------------------------|
| Tropical                 | TROPICAL               |
| Midlatitude summer       | MIDLATITUDE_SUMMER     |
| Midlatitude winter       | MIDLATITUDE_WINTER     |
| Subarctic summer         | SUBARCTIC_SUMMER       |
| Subarctic winter         | SUBARCTIC_WINTER       |
| U.S. Standard Atmosphere | US_STANDARD_ATMOSPHERE |

**Table A.1:** CRTM Atmosphere structure valid Climatology definitions. The same set as defined for LBLRTM is used.

| <b>Molecule</b>  | <b>Parameter</b> | <b>Molecule</b>               | <b>Parameter</b> |
|------------------|------------------|-------------------------------|------------------|
| H <sub>2</sub> O | H2O_ID           | HI                            | HI_ID            |
| CO <sub>2</sub>  | C02_ID           | ClO                           | ClO_ID           |
| O <sub>3</sub>   | O3_ID            | OCS                           | OCS_ID           |
| N <sub>2</sub> O | N2O_ID           | H <sub>2</sub> CO             | H2CO_ID          |
| CO               | C0_ID            | HOCl                          | HOCl_ID          |
| CH <sub>4</sub>  | CH4_ID           | N <sub>2</sub>                | N2_ID            |
| O <sub>2</sub>   | O2_ID            | HCN                           | HCN_ID           |
| NO               | NO_ID            | CH <sub>3</sub> I             | CH3I_ID          |
| SO <sub>2</sub>  | S02_ID           | H <sub>2</sub> O <sub>2</sub> | H2O2_ID          |
| NO <sub>2</sub>  | N02_ID           | C <sub>2</sub> H <sub>2</sub> | C2H2_ID          |
| NH <sub>3</sub>  | NH3_ID           | C <sub>2</sub> H <sub>6</sub> | C2H6_ID          |
| HNO <sub>3</sub> | HNO3_ID          | PH <sub>3</sub>               | PH3_ID           |
| OH               | OH_ID            | COF <sub>2</sub>              | COF2_ID          |
| HF               | HF_ID            | SF <sub>6</sub>               | SF6_ID           |
| HCl              | HCl_ID           | H <sub>2</sub> S              | H2S_ID           |
| HBr              | HBr_ID           | HCOOH                         | HCOOH_ID         |

**Table A.2:** CRTM Atmosphere structure valid Absorber.ID definitions. The same molecule set as defined for HITRAN is used.

| <b>Units</b>   | <b>Parameter</b>             |
|--|------------------------------|
| Volume mixing ratio, ppmv                              | VOLUME_MIXING_RATIO_UNITS    |
| Number density, cm <sup>-3</sup>                       | NUMBER_DENSITY_UNITS         |
| Mass mixing ratio, g/kg                                | MASS_MIXING_RATIO_UNITS      |
| Mass density, g.m <sup>-3</sup>                        | MASS_DENSITY_UNITS           |
| Partial pressure, hPa                                  | PARTIAL_PRESSURE_UNITS       |
| Dewpoint temperature, K ( <b>H<sub>2</sub>O ONLY</b> ) | DEWPOINT_TEMPERATURE_K_UNITS |
| Dewpoint temperature, C ( <b>H<sub>2</sub>O ONLY</b> ) | DEWPOINT_TEMPERATURE_C_UNITS |
| Relative humidity, % ( <b>H<sub>2</sub>O ONLY</b> )    | RELATIVE_HUMIDITY_UNITS      |
| Specific amount, g/g                                   | SPECIFIC_AMOUNT_UNITS        |
| Integrated path, mm                                    | INTEGRATED_PATH_UNITS        |

**Table A.3:** CRTM Atmosphere structure valid Absorber.Units definitions. The same set as defined for LBLRTM is used.

### *A.2.1 CRTM\_Atmosphere\_AddLayerCopy interface*

NAME:

CRTM\_Atmosphere\_AddLayerCopy

PURPOSE:

Elemental function to copy an instance of the CRTM Atmosphere object with additional layers added to the TOA of the input.

CALLING SEQUENCE:

Atm\_out = CRTM\_Atmosphere\_AddLayerCopy( Atm, n\_Added\_Layers )

OBJECTS:

Atm:                    Atmosphere structure to copy.  
UNITS:                N/A  
TYPE:                 CRTM\_Atmosphere\_type  
DIMENSION:          Scalar or any rank  
ATTRIBUTES:        INTENT(OUT)

INPUTS:

n\_Added\_Layers:    Number of layers to add to the function result.  
UNITS:             N/A  
TYPE:              INTEGER  
DIMENSION:        Same as atmosphere object  
ATTRIBUTES:       INTENT(IN)

FUNCTION RESULT:

Atm\_out:            Copy of the input atmosphere structure with space for  
                     extra layers added to TOA.  
UNITS:             N/A  
TYPE:              CRTM\_Atmosphere\_type  
DIMENSION:        Same as input.  
ATTRIBUTES:       INTENT(OUT)

### *A.2.2 CRTM\_Atmosphere\_Associated interface*

NAME:

CRTM\_Atmosphere\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM Atmosphere object.

CALLING SEQUENCE:

Status = CRTM\_Atmosphere\_Associated( Atm )

OBJECTS:

Atm:                Atmosphere structure which is to have its member's  
                     status tested.

UNITS: N/A  
 TYPE: CRTM\_Atmosphere\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the Atmosphere members.  
       .TRUE. - if the array components are allocated.  
       .FALSE. - if the array components are not allocated.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as input

### A.2.3 CRTM\_Atmosphere\_Compare interface

NAME:

CRTM\_Atmosphere\_Compare

PURPOSE:

Elemental function to compare two CRTM\_Atmosphere objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_Atmosphere\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y: Two CRTM Atmosphere objects to be compared.  
 UNITS: N/A  
 TYPE: CRTM\_Atmosphere\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig: Number of significant figure to compare floating point components.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.2.4 CRTM\_Atmosphere\_Create interface



NAME:

CRTM\_Atmosphere\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM Atmosphere object.

CALLING SEQUENCE:

```
CALL CRTM_Atmosphere_Create( Atm      , &
                             n_Layers , &
                             n_Absorbers, &
                             n_Clouds  , &
                             n_Aerosols )
```

OBJECTS:

Atm:            Atmosphere structure.  
UNITS:          N/A  
TYPE:           CRTM\_Atmosphere\_type  
DIMENSION:      Scalar or any rank  
ATTRIBUTES:    INTENT(OUT)

INPUTS:

n\_Layers:      Number of layers dimension.  
Must be > 0.  
UNITS:          N/A  
TYPE:           INTEGER  
DIMENSION:      Same as atmosphere object  
ATTRIBUTES:    INTENT(IN)

n\_Absorbers:   Number of absorbers dimension.  
Must be > 0.  
UNITS:          N/A  
TYPE:           INTEGER  
DIMENSION:      Same as atmosphere object  
ATTRIBUTES:    INTENT(IN)

n\_Clouds:      Number of clouds dimension.  
Can be = 0 (i.e. clear sky).  
UNITS:          N/A  
TYPE:           INTEGER  
DIMENSION:      Same as atmosphere object  
ATTRIBUTES:    INTENT(IN)

n\_Aerosols:    Number of aerosols dimension.  
Can be = 0 (i.e. no aerosols).  
UNITS:          N/A  
TYPE:           INTEGER  
DIMENSION:      Same as atmosphere object  
ATTRIBUTES:    INTENT(IN)

### *A.2.5 CRTM\_Atmosphere\_DefineVersion interface*

NAME:

CRTM\_Atmosphere\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Atmosphere\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.2.6 CRTM\_Atmosphere\_Destroy interface*

NAME:

CRTM\_Atmosphere\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM Atmosphere objects.

CALLING SEQUENCE:

CALL CRTM\_Atmosphere\_Destroy( Atm )

OBJECTS:

Atm: Re-initialized Atmosphere structure.  
UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

### *A.2.7 CRTM\_Atmosphere\_Inspect interface*

NAME:

CRTM\_Atmosphere\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM Atmosphere object to stdout.

CALLING SEQUENCE:

```
CALL CRTM_Atmosphere_Inspect( Atm )
```

INPUTS:

```
Atm:  CRTM Atmosphere object to display.  
      UNITS:      N/A  
      TYPE:       CRTM_Atmosphere_type  
      DIMENSION:  Scalar  
      ATTRIBUTES: INTENT(IN)
```

### *A.2.8 CRTM\_Atmosphere\_IsValid interface*

NAME:

```
CRTM_Atmosphere_IsValid
```

PURPOSE:

```
Non-pure function to perform some simple validity checks on a  
CRTM Atmosphere object.
```

```
If invalid data is found, a message is printed to stdout.
```

CALLING SEQUENCE:

```
result = CRTM_Atmosphere_IsValid( Atm )
```

```
or
```

```
IF ( CRTM_Atmosphere_IsValid( Atm ) ) THEN....
```

OBJECTS:

```
Atm:      CRTM Atmosphere object which is to have its  
          contents checked.  
          UNITS:      N/A  
          TYPE:       CRTM_Atmosphere_type  
          DIMENSION:  Scalar  
          ATTRIBUTES: INTENT(IN)
```

FUNCTION RESULT:

```
result:   Logical variable indicating whether or not the input  
          passed the check.  
          If == .FALSE., Atmosphere object is unused or contains  
              invalid data.  
          == .TRUE., Atmosphere object can be used in CRTM.  
          UNITS:      N/A  
          TYPE:       LOGICAL  
          DIMENSION:  Scalar
```

### *A.2.9 CRTM\_Atmosphere\_Zero interface*

NAME:

CRTM\_Atmosphere\_Zero

PURPOSE:

Elemental subroutine to zero out the data arrays  
in a CRTM Atmosphere object.

CALLING SEQUENCE:

CALL CRTM\_Atmosphere\_Zero( Atm )

OUTPUTS:

Atm: CRTM Atmosphere structure in which the data arrays  
are to be zeroed out.  
UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

COMMENTS:

- The dimension components of the structure are *\*NOT\** set to zero.
- The Climatology, Absorber\_ID, and Absorber\_Units components are *\*NOT\** reset in this routine.

#### *A.2.10 CRTM\_Atmosphere\_IOVersion interface*

NAME:

CRTM\_Atmosphere\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Atmosphere\_IOVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

#### *A.2.11 CRTM\_Atmosphere\_InquireFile interface*

NAME:

CRTM\_Atmosphere\_InquireFile

PURPOSE:

Function to inquire CRTM Atmosphere object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Atmosphere_InquireFile( Filename           , &
                                             n_Channels = n_Channels, &
                                             n_Profiles = n_Profiles )
```

INPUTS:

Filename: Character string specifying the name of a  
CRTM Atmosphere data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_Channels: The number of spectral channels for which there is  
data in the file. Note that this value will always  
be 0 for a profile-only dataset-- it only has meaning  
for K-matrix data.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

n\_Profiles: The number of profiles in the data file.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### *A.2.12 CRTM\_Atmosphere\_ReadFile interface*

NAME:

CRTM\_Atmosphere\_ReadFile

PURPOSE:

Function to read CRTM Atmosphere object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Atmosphere_ReadFile( Filename           , &
                                         Atmosphere         , &
                                         Quiet               = Quiet           , &
                                         n_Channels          = n_Channels        , &
                                         n_Profiles          = n_Profiles        , &
```

#### INPUTS:

```
Filename:    Character string specifying the name of an
              Atmosphere format data file to read.
UNITS:       N/A
TYPE:        CHARACTER(*)
DIMENSION:   Scalar
ATTRIBUTES:  INTENT(IN)
```

#### OUTPUTS:

```
Atmosphere:  CRTM Atmosphere object array containing the Atmosphere
              data. Note the following meanings attributed to the
              dimensions of the object array:
Rank-1: M profiles.
              Only profile data are to be read in. The file
              does not contain channel information. The
              dimension of the structure is understood to
              be the PROFILE dimension.
Rank-2: L channels x M profiles
              Channel and profile data are to be read in.
              The file contains both channel and profile
              information. The first dimension of the
              structure is the CHANNEL dimension, the second
              is the PROFILE dimension. This is to allow
              K-matrix structures to be read in with the
              same function.
UNITS:       N/A
TYPE:        CRTM_Atmosphere_type
DIMENSION:   Rank-1 (M) or Rank-2 (L x M)
ATTRIBUTES:  INTENT(OUT)
```

#### OPTIONAL INPUTS:

```
Quiet:       Set this logical argument to suppress INFORMATION
              messages being printed to stdout
              If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].
              == .TRUE., INFORMATION messages are SUPPRESSED.
              If not specified, default is .FALSE.
UNITS:       N/A
TYPE:        LOGICAL
DIMENSION:   Scalar
ATTRIBUTES:  INTENT(IN), OPTIONAL
```

#### OPTIONAL OUTPUTS:

```
n_Channels:  The number of channels for which data was read. Note that
              this value will always be 0 for a profile-only dataset--
              it only has meaning for K-matrix data.
UNITS:       N/A
TYPE:        INTEGER
DIMENSION:   Scalar
```

ATTRIBUTES: OPTIONAL, INTENT(OUT)

n\_Profiles: The number of profiles for which data was read.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file read was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### *A.2.13 CRTM\_Atmosphere\_WriteFile interface*

NAME:

CRTM\_Atmosphere\_WriteFile

PURPOSE:

Function to write CRTM Atmosphere object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Atmosphere_WriteFile( Filename      , &  
                                           Atmosphere    , &  
                                           Quiet = Quiet  )
```

INPUTS:

Filename: Character string specifying the name of the  
Atmosphere format data file to write.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

Atmosphere: CRTM Atmosphere object array containing the Atmosphere  
data. Note the following meanings attributed to the  
dimensions of the Atmosphere array:

Rank-1: M profiles.

Only profile data are to be read in. The file  
does not contain channel information. The  
dimension of the array is understood to  
be the PROFILE dimension.

Rank-2: L channels x M profiles

Channel and profile data are to be read in.  
The file contains both channel and profile

information. The first dimension of the array is the CHANNEL dimension, the second is the PROFILE dimension. This is to allow K-matrix structures to be read in with the same function.

UNITS: N/A  
TYPE: CRTM\_Atmosphere\_type  
DIMENSION: Rank-1 (M) or Rank-2 (L x M)  
ATTRIBUTES: INTENT(IN)

#### OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.



## A.3 Cloud Structure

```
TYPE :: CRTM_Cloud_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimension values
  INTEGER :: Max_Layers = 0 ! K dimension.
  INTEGER :: n_Layers = 0 ! Kuse dimension.
  ! Number of added layers
  INTEGER :: n_Added_Layers = 0
  ! Cloud type
  INTEGER :: Type = INVALID_CLOUD
  ! Cloud state variables
  REAL(fp), ALLOCATABLE :: Effective_Radius(:) ! K. Units are microns
  REAL(fp), ALLOCATABLE :: Effective_Variance(:) ! K. Units are microns^2
  REAL(fp), ALLOCATABLE :: Water_Content(:) ! K. Units are kg/m^2
END TYPE CRTM_Cloud_type
```

**Figure A.3:** CRTM\_Cloud\_type structure definition.

| Cloud Type | Parameter     |
|------------|---------------|
| Water      | WATER_CLOUD   |
| Ice        | ICE_CLOUD     |
| Rain       | RAIN_CLOUD    |
| Snow       | SNOW_CLOUD    |
| Graupel    | GRAUPEL_CLOUD |
| Hail       | HAIL_CLOUD    |

**Table A.4:** CRTM Cloud structure valid Type definitions.

### *A.3.1 CRTM\_Cloud\_AddLayerCopy interface*

NAME:

CRTM\_Cloud\_AddLayerCopy

PURPOSE:

Elemental function to copy an instance of the CRTM Cloud object with additional layers added to the TOA of the input.

CALLING SEQUENCE:

cld\_out = CRTM\_Cloud\_AddLayerCopy( cld, n\_Added\_Layers )

OBJECTS:

cld: Cloud structure to copy.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Added\_Layers: Number of layers to add to the function result.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Same as Cloud object  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

cld\_out: Copy of the input Cloud structure with space for extra layers added to TOA.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Same as input.  
ATTRIBUTES: INTENT(OUT)

### *A.3.2 CRTM\_Cloud\_Associated interface*

NAME:

CRTM\_Cloud\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM Cloud object.

CALLING SEQUENCE:

Status = CRTM\_Cloud\_Associated( Cloud )

OBJECTS:

Cloud: Cloud structure which is to have its member's status tested.

UNITS: N/A  
 TYPE: CRTM\_Cloud\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the Cloud members.  
       .TRUE. - if the array components are allocated.  
       .FALSE. - if the array components are not allocated.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as input Cloud argument

### A.3.3 CRTM\_Cloud\_Compare interface

NAME:

CRTM\_Cloud\_Compare

PURPOSE:

Elemental function to compare two CRTM\_Cloud objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_Cloud\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y: Two CRTM Cloud objects to be compared.  
 UNITS: N/A  
 TYPE: CRTM\_Cloud\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig: Number of significant figure to compare floating point components.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.3.4 CRTM\_Cloud\_Create interface

NAME:

CRTM\_Cloud\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM Cloud object.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_Create( Cloud, n\_Layers )

OBJECTS:

Cloud: Cloud structure.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Layers: Number of layers for which there is cloud data.  
Must be > 0.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Same as Cloud object  
ATTRIBUTES: INTENT(IN)

### *A.3.5 CRTM\_Cloud\_DefineVersion interface*

NAME:

CRTM\_Cloud\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.3.6 CRTM\_Cloud\_Destroy interface*

NAME:

CRTM\_Cloud\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM Cloud objects.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_Destroy( Cloud )

OBJECTS:

Cloud:            Re-initialized Cloud structure.  
                  UNITS:        N/A  
                  TYPE:         CRTM\_Cloud\_type  
                  DIMENSION:   Scalar OR any rank  
                  ATTRIBUTES:   INTENT(OUT)

### *A.3.7 CRTM\_Cloud\_Inspect interface*

NAME:

CRTM\_Cloud\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM Cloud object to stdout.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_Inspect( Cloud )

INPUTS:

Cloud:            CRTM Cloud object to display.  
                  UNITS:        N/A  
                  TYPE:         CRTM\_Cloud\_type  
                  DIMENSION:   Scalar  
                  ATTRIBUTES:   INTENT(IN)

### *A.3.8 CRTM\_Cloud\_IsValid interface*

NAME:

CRTM\_Cloud\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a CRTM Cloud object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = CRTM\_Cloud\_IsValid( cloud )

or

IF ( CRTM\_Cloud\_IsValid( cloud ) ) THEN....

OBJECTS:

cloud: CRTM Cloud object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Cloud object is unused or contains  
invalid data.  
== .TRUE., Cloud object can be used in CRTM.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### A.3.9 CRTM\_Cloud\_Zero interface

NAME:

CRTM\_Cloud\_Zero

PURPOSE:

Elemental subroutine to zero out the data arrays in a CRTM Cloud object.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_Zero( Cloud )

OBJECTS:

Cloud: CRTM Cloud structure in which the data arrays are  
to be zeroed out.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

COMMENTS:

- The dimension components of the structure are \*NOT\* set to zero.
- The cloud type component is \*NOT\* reset.

### A.3.10 CRTM\_Cloud\_IOVersion interface

NAME:

CRTM\_Cloud\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Cloud\_IOVersion( Id )

OUTPUT ARGUMENTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### A.3.11 CRTM\_Cloud\_InquireFile interface

NAME:

CRTM\_Cloud\_InquireFile

PURPOSE:

Function to inquire CRTM Cloud object files.

CALLING SEQUENCE:

Error\_Status = CRTM\_Cloud\_InquireFile( Filename , &  
n\_Clouds = n\_Clouds )

INPUTS:

Filename: Character string specifying the name of a  
CRTM Cloud data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_Clouds: The number of Cloud profiles in the data file.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER

DIMENSION: Scalar

### A.3.12 CRTM\_Cloud\_ReadFile interface

NAME:

CRTM\_Cloud\_ReadFile

PURPOSE:

Function to read CRTM Cloud object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Cloud_ReadFile( Filename      , &
                                     Cloud          , &
                                     Quiet    = Quiet    , &
                                     No_Close = No_Close, &
                                     n_Clouds = n_Clouds )
```

INPUTS:

Filename: Character string specifying the name of a  
Cloud format data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OUTPUTS:

Cloud: CRTM Cloud object array containing the Cloud data.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(OUT)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

No\_Close: Set this logical argument to NOT close the file upon exit.  
If == .FALSE., the input file is closed upon exit [DEFAULT]  
== .TRUE., the input file is NOT closed upon exit.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar



ATTRIBUTES: INTENT(IN), OPTIONAL

OPTIONAL OUTPUTS:

n\_Clouds: The actual number of cloud profiles read in.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file read was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### A.3.13 CRTM\_Cloud\_WriteFile interface

NAME:

CRTM\_Cloud\_WriteFile

PURPOSE:

Function to write CRTM Cloud object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Cloud_WriteFile( Filename      , &  
                                     Cloud          , &  
                                     Quiet    = Quiet , &  
                                     No_Close = No_Close )
```

INPUTS:

Filename: Character string specifying the name of the  
Cloud format data file to write.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

Cloud: CRTM Cloud object array containing the Cloud data.  
UNITS: N/A  
TYPE: CRTM\_Cloud\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].

== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

No\_Close: Set this logical argument to NOT close the file upon exit.  
If == .FALSE., the input file is closed upon exit [DEFAULT]  
== .TRUE., the input file is NOT closed upon exit.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.

## A.4 Aerosol Structure

```

TYPE :: CRTM_Aerosol_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimension values
  INTEGER :: Max_Layers = 0  ! K dimension.
  INTEGER :: n_Layers = 0  ! Kuse dimension
  ! Number of added layers
  INTEGER :: n_Added_Layers = 0
  ! Aerosol type
  INTEGER :: Type = INVALID_AEROSOL
  ! Aerosol state variables
  REAL(fp), ALLOCATABLE :: Effective_Radius(:)  ! K. Units are microns
  REAL(fp), ALLOCATABLE :: Concentration(:)     ! K. Units are kg/m^2
END TYPE CRTM_Aerosol_type

```

**Figure A.4:** CRTM\_Aerosol\_type structure definition.

| Aerosol Type   | Parameter              | $r_{eff}$ Range ( $\mu\text{m}$ ) |
|----------------|------------------------|-----------------------------------|
| Dust           | DUST_AEROSOL           | 0.01 - 8                          |
| Sea salt SSAM  | SEASALT_SSAM_AEROSOL   | 0.3 - 1.45                        |
| Sea salt SSCM1 | SEASALT_SSCM1_AEROSOL  | 1.0 - 4.8                         |
| Sea salt SSCM2 | SEASALT_SSCM2_AEROSOL  | 3.25 - 17.3                       |
| Sea salt SSCM3 | SEASALT_SSCM3_AEROSOL  | 7.5 - 89                          |
| Organic carbon | ORGANIC_CARBON_AEROSOL | 0.09 - 0.21                       |
| Black carbon   | BLACK_CARBON_AEROSOL   | 0.036 - 0.074                     |
| Sulfate        | SULFATE_AEROSOL        | 0.24 - 0.8                        |

**Table A.5:** CRTM Aerosol structure valid Type definitions and effective radii. SSAM  $\equiv$  Sea Salt Accumulation Mode, SSCM  $\equiv$  Sea Salt Coarse Mode.

#### A.4.1 *CRTM\_Aerosol\_AddLayerCopy interface*

NAME:

CRTM\_Aerosol\_AddLayerCopy

PURPOSE:

Elemental function to copy an instance of the CRTM Aerosol object with additional layers added to the TOA of the input.

CALLING SEQUENCE:

aer\_out = CRTM\_Aerosol\_AddLayerCopy( aer, n\_Added\_Layers )

OBJECTS:

aer: Aerosol structure to copy.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Added\_Layers: Number of layers to add to the function result.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Same as Aerosol object  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

aer\_out: Copy of the input Aerosol structure with space for extra layers added to TOA.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Same as input.  
ATTRIBUTES: INTENT(OUT)

#### A.4.2 *CRTM\_Aerosol\_Associated interface*

NAME:

CRTM\_Aerosol\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM Aerosol object.

CALLING SEQUENCE:

Status = CRTM\_Aerosol\_Associated( Aerosol )

OBJECTS:

Aerosol: Aerosol structure which is to have its member's status tested.

UNITS: N/A  
 TYPE: CRTM\_Aerosol\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the Aerosol members.  
       .TRUE. - if the array components are allocated.  
       .FALSE. - if the array components are not allocated.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as input Aerosol argument

### A.4.3 CRTM\_Aerosol\_Compare interface

NAME:

CRTM\_Aerosol\_Compare

PURPOSE:

Elemental function to compare two CRTM\_Aerosol objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_Aerosol\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y: Two CRTM Aerosol objects to be compared.  
 UNITS: N/A  
 TYPE: CRTM\_Aerosol\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig: Number of significant figure to compare floating point components.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.4.4 CRTM\_Aerosol\_Create interface

NAME:

CRTM\_Aerosol\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM Aerosol object.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_Create( Aerosol, n\_Layers )

OBJECTS:

Aerosol: Aerosol structure.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Layers: Number of layers for which there is Aerosol data.  
Must be > 0.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Same as Aerosol object  
ATTRIBUTES: INTENT(IN)

#### *A.4.5 CRTM\_Aerosol\_DefineVersion interface*

NAME:

CRTM\_Aerosol\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

#### *A.4.6 CRTM\_Aerosol\_Destroy interface*

NAME:

CRTM\_Aerosol\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM Aerosol objects.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_Destroy( Aerosol )

OBJECTS:

Aerosol: Re-initialized Aerosol structure.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar OR any rank  
ATTRIBUTES: INTENT(OUT)

#### *A.4.7 CRTM\_Aerosol\_Inspect interface*

NAME:

CRTM\_Aerosol\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM Aerosol object to stdout.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_Inspect( Aerosol )

INPUTS:

Aerosol: CRTM Aerosol object to display.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

#### *A.4.8 CRTM\_Aerosol\_IsValid interface*

NAME:

CRTM\_Aerosol\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a CRTM Aerosol object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = CRTM\_Aerosol\_IsValid( Aerosol )

or

IF ( CRTM\_Aerosol\_IsValid( Aerosol ) ) THEN....

OBJECTS:

Aerosol: CRTM Aerosol object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Aerosol object is unused or contains  
invalid data.  
== .TRUE., Aerosol object can be used in CRTM.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

#### A.4.9 CRTM\_Aerosol\_Zero interface

NAME:

CRTM\_Aerosol\_Zero

PURPOSE:

Elemental subroutine to zero out the data arrays in a CRTM Aerosol object.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_Zero( Aerosol )

OBJECTS:

Aerosol: CRTM Aerosol object in which the data arrays are  
to be zeroed out.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

COMMENTS:

- The dimension components of the structure are \*NOT\* set to zero.
- The Aerosol type component is \*NOT\* reset.

#### A.4.10 CRTM\_Aerosol\_IOVersion interface

NAME:



CRTM\_Aerosol\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Aerosol\_IOVersion( Id )

OUTPUT ARGUMENTS:

Id: Character string containing the version Id information  
for the module.

UNITS: N/A

TYPE: CHARACTER(\*)

DIMENSION: Scalar

ATTRIBUTES: INTENT(OUT)

#### A.4.11 CRTM\_Aerosol\_InquireFile interface

NAME:

CRTM\_Aerosol\_InquireFile

PURPOSE:

Function to inquire CRTM Aerosol object files.

CALLING SEQUENCE:

Error\_Status = CRTM\_Aerosol\_InquireFile( Filename , &  
n\_Aerosols = n\_Aerosols )

INPUTS:

Filename: Character string specifying the name of a  
CRTM Aerosol data file to read.

UNITS: N/A

TYPE: CHARACTER(\*)

DIMENSION: Scalar

ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_Aerosols: The number of Aerosol profiles in the data file.

UNITS: N/A

TYPE: INTEGER

DIMENSION: Scalar

ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.

UNITS: N/A

TYPE: INTEGER

DIMENSION: Scalar

#### A.4.12 CRTM\_Aerosol\_ReadFile interface

NAME:

CRTM\_Aerosol\_ReadFile

PURPOSE:

Function to read CRTM Aerosol object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Aerosol_ReadFile( Filename      , &
                                       Aerosol        , &
                                       Quiet          = Quiet      , &
                                       No_Close       = No_Close   , &
                                       n_Aerosols      = n_Aerosols )
```

INPUTS:

Filename: Character string specifying the name of a  
Aerosol format data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OUTPUTS:

Aerosol: CRTM Aerosol object array containing the aerosol data.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(OUT)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

No\_Close: Set this logical argument to NOT close the file upon exit.  
If == .FALSE., the input file is closed upon exit [DEFAULT]  
== .TRUE., the input file is NOT closed upon exit.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

ATTRIBUTES: INTENT(IN), OPTIONAL

OPTIONAL OUTPUTS:

n\_Aerosols: The actual number of aerosol profiles read in.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file read was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### A.4.13 CRTM\_Aerosol\_WriteFile interface

NAME:

CRTM\_Aerosol\_WriteFile

PURPOSE:

Function to write CRTM Aerosol object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Aerosol_WriteFile( Filename      , &  
                                       Aerosol        , &  
                                       Quiet    = Quiet  , &  
                                       No_Close = No_Close )
```

INPUTS:

Filename: Character string specifying the name of the  
Aerosol format data file to write.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

Aerosol: CRTM Aerosol object array containing the Aerosol data.  
UNITS: N/A  
TYPE: CRTM\_Aerosol\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].

== .TRUE., INFORMATION messages are SUPPRESSED.  
 If not specified, default is .FALSE.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

No\_Close: Set this logical argument to NOT close the file upon exit.  
 If == .FALSE., the input file is closed upon exit [DEFAULT]  
 == .TRUE., the input file is NOT closed upon exit.  
 If not specified, default is .FALSE.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
 The error codes are defined in the Message\_Handler module.  
 If == SUCCESS, the file write was successful  
 == FAILURE, an unrecoverable error occurred.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar

#### SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.

## A.5 Surface Structure

---

```
TYPE :: CRTM_Surface_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .TRUE.  ! Placeholder for future expansion
  ! Dimension values
  ! ...None yet
  ! Gross type of surface determined by coverage
  REAL(fp) :: Land_Coverage = ZERO
  REAL(fp) :: Water_Coverage = ZERO
  REAL(fp) :: Snow_Coverage = ZERO
  REAL(fp) :: Ice_Coverage = ZERO
  ! Land surface type data
  INTEGER :: Land_Type = DEFAULT_LAND_TYPE
  REAL(fp) :: Land_Temperature = DEFAULT_LAND_TEMPERATURE
  REAL(fp) :: Soil_Moisture_Content = DEFAULT_SOIL_MOISTURE_CONTENT
  REAL(fp) :: Canopy_Water_Content = DEFAULT_CANOPY_WATER_CONTENT
  REAL(fp) :: Vegetation_Fraction = DEFAULT_VEGETATION_FRACTION
  REAL(fp) :: Soil_Temperature = DEFAULT_SOIL_TEMPERATURE
  ! Water type data
  INTEGER :: Water_Type = DEFAULT_WATER_TYPE
  REAL(fp) :: Water_Temperature = DEFAULT_WATER_TEMPERATURE
  REAL(fp) :: Wind_Speed = DEFAULT_WIND_SPEED
  REAL(fp) :: Wind_Direction = DEFAULT_WIND_DIRECTION
  REAL(fp) :: Salinity = DEFAULT_SALINITY
  ! Snow surface type data
  INTEGER :: Snow_Type = DEFAULT_SNOW_TYPE
  REAL(fp) :: Snow_Temperature = DEFAULT_SNOW_TEMPERATURE
  REAL(fp) :: Snow_Depth = DEFAULT_SNOW_DEPTH
  REAL(fp) :: Snow_Density = DEFAULT_SNOW_DENSITY
  REAL(fp) :: Snow_Grain_Size = DEFAULT_SNOW_GRAIN_SIZE
  ! Ice surface type data
  INTEGER :: Ice_Type = DEFAULT_ICE_TYPE
  REAL(fp) :: Ice_Temperature = DEFAULT_ICE_TEMPERATURE
  REAL(fp) :: Ice_Thickness = DEFAULT_ICE_THICKNESS
  REAL(fp) :: Ice_Density = DEFAULT_ICE_DENSITY
  REAL(fp) :: Ice_Roughness = DEFAULT_ICE_ROUGHNESS
  ! SensorData containing channel brightness temperatures
  TYPE(CRTM_SensorData_type) :: SensorData
END TYPE CRTM_Surface_type
```

**Figure A.5:** CRTM\_Surface\_type structure definition.

| Component             | Description  | Units              | Dimensions |
|-----------------------|--|--------------------|------------|
| n_Sensors             | The number of sensors for which data is provided inside the SensorData structure | N/A                | Scalar     |
| Land_Coverage         | Fraction of the FOV that is land surface   | N/A                | Scalar     |
| Water_Coverage        | Fraction of the FOV that is water surface  | N/A                | Scalar     |
| Snow_Coverage         | Fraction of the FOV that is snow surface   | N/A                | Scalar     |
| Ice_Coverage          | Fraction of the FOV that is ice surface  | N/A                | Scalar     |
| Wind_Speed            | Surface wind speed   | $\text{m.s}^{-1}$  | Scalar     |
| Wind_Direction        | Surface wind direction   | deg. E from N      | Scalar     |
| Land_Type             | Land surface type  | N/A                | Scalar     |
| Land_Temperature      | Land surface temperature   | Kelvin             | Scalar     |
| Soil_Moisture_Content | Volumetric water content of the soil   | $\text{g.cm}^{-3}$ | Scalar     |
| Canopy_Water_Content  | Gravimetric water content of the canopy  | $\text{g.cm}^{-3}$ | Scalar     |
| Vegetation_Fraction   | Vegetation fraction of the surface   | %                  | Scalar     |
| Soil_Temperature      | Soil temperature   | Kelvin             | Scalar     |
| Water_Type            | Water surface type   | N/A                | Scalar     |
| Water_Temperature     | Water surface temperature  | Kelvin             | Scalar     |
| Salinity              | Water salinity   | ‰                  | Scalar     |
| Snow_Type             | Snow surface type  | N/A                | Scalar     |
| Snow_Temperature      | Snow surface temperature   | Kelvin             | Scalar     |
| Snow_Depth            | Snow depth   | mm                 | Scalar     |
| Snow_Density          | Snow density   | $\text{g.m}^{-3}$  | Scalar     |
| Snow_Grain_Size       | Snow grain size  | mm                 | Scalar     |
| Ice_Type              | Ice surface type   | N/A                | Scalar     |
| Ice_Temperature       | Ice surface temperature  | Kelvin             | Scalar     |
| Ice_Thickness         | Thickness of ice   | mm                 | Scalar     |
| Ice_Density           | Density of ice   | $\text{g.m}^{-3}$  | Scalar     |
| Ice_Roughness         | Measure of the surface roughness of the ice                                      | N/A                | Scalar     |
| SensorData            | Satellite sensor data required for some surface emissivity algorithms            | N/A                | Scalar     |

**Table A.6:** CRTM Surface structure component description.

| Parameter                     | Value      | Units              |
|-------------------------------|------------|--------------------|
| Surface type independent data |            |                    |
| DEFAULT_WIND_SPEED            | 5.0        | m.s <sup>-1</sup>  |
| DEFAULT_WIND_DIRECTION        | 0.0        | deg. E from N      |
| Land surface type data        |            |                    |
| DEFAULT_LAND_TYPE             | GRASS_SOIL | N/A                |
| DEFAULT_LAND_TEMPERATURE      | 283.0      | K                  |
| DEFAULT_SOIL_MOISTURE_CONTENT | 0.05       | g.cm <sup>-3</sup> |
| DEFAULT_CANOPY_WATER_CONTENT  | 0.05       | g.cm <sup>-3</sup> |
| DEFAULT_VEGETATION_FRACTION   | 0.3        | 30%                |
| DEFAULT_SOIL_TEMPERATURE      | 283.0      | K                  |
| Water type data               |            |                    |
| DEFAULT_WATER_TYPE            | SEA_WATER  | N/A                |
| DEFAULT_WATER_TEMPERATURE     | 283.0      | K                  |
| DEFAULT_SALINITY              | 33.0       | ppmv               |
| Snow surface type data        |            |                    |
| DEFAULT_SNOW_TYPE             | NEW_SNOW   | N/A                |
| DEFAULT_SNOW_TEMPERATURE      | 263.0      | K                  |
| DEFAULT_SNOW_DEPTH            | 50.0       | mm                 |
| DEFAULT_SNOW_DENSITY          | 0.2        | g.cm <sup>-3</sup> |
| DEFAULT_SNOW_GRAIN_SIZE       | 2.0        | mm                 |
| Ice surface type data         |            |                    |
| DEFAULT_ICE_TYPE              | FRESH_ICE  | N/A                |
| DEFAULT_ICE_TEMPERATURE       | 263.0      | K                  |
| DEFAULT_ICE_THICKNESS         | 10.0       | mm                 |
| DEFAULT_ICE_DENSITY           | 0.9        | g.cm <sup>-3</sup> |
| DEFAULT_ICE_ROUGHNESS         | 0.0        | N/A                |

**Table A.7:** CRTM Surface structure default values.

| Land Type                | Parameter                |
|--------------------------|--------------------------|
| Compacted soil           | COMPACTED_SOIL           |
| Tilled soil              | TILLED_SOIL              |
| Sand                     | SAND                     |
| Rock                     | ROCK                     |
| Irrigated low vegetation | IRRIGATED_LOW_VEGETATION |
| Meadow grass             | MEADOW_GRASS             |
| Scrub                    | SCRUB                    |
| Broadleaf forest         | BROADLEAF_FOREST         |
| Pine forest              | PINE_FOREST              |
| Tundra                   | TUNDRA                   |
| Grass-soil               | GRASS_SOIL               |
| Broadleaf-pine forest    | BROADLEAF_PINE_FOREST    |
| Grass scrub              | GRASS_SCRUB              |
| Soil-grass-scrub         | SOIL_GRASS_SCRUB         |
| Urban concrete           | URBAN_CONCRETE           |
| Pine brush               | PINE_BRUSH               |
| Broadleaf brush          | BROADLEAF_BRUSH          |
| Wet soil                 | WET_SOIL                 |
| Scrub-soil               | SCRUB_SOIL               |
| Broadleaf(70)-Pine(30)   | BROADLEAF70_PINE30       |

**Table A.8:** CRTM Surface structure valid Land\_Type definitions.

| Water Type  | Parameter   |
|-------------|-------------|
| Sea water   | SEA_WATER   |
| Fresh water | FRESH_WATER |

**Table A.9:** CRTM Surface structure valid Water\_Type definitions.

| Snow Type            | Parameter           |
|----------------------|---------------------|
| Wet snow             | WET_SNOW            |
| Grass after snow     | GRASS_AFTER_SNOW    |
| Powder snow          | POWDER_SNOW         |
| RS snow(A)           | RS_SNOW_A           |
| RS snow(B)           | RS_SNOW_B           |
| RS snow(C)           | RS_SNOW_C           |
| RS snow(D)           | RS_SNOW_D           |
| RS snow(E)           | RS_SNOW_E           |
| Thin Crust snow      | THIN_CRUST_SNOW     |
| Thick crust snow     | THICK_CRUST_SNOW    |
| Shallow snow         | SHALLOW_SNOW        |
| Deep snow            | DEEP_SNOW           |
| Crust snow           | CRUST_SNOW          |
| Medium snow          | MEDIUM_SNOW         |
| Bottom crust snow(A) | BOTTOM_CRUST_SNOW_A |
| Bottom crust snow(B) | BOTTOM_CRUST_SNOW_B |

**Table A.10:** CRTM Surface structure valid Snow\_Type definitions.



| Ice Type              | Parameter          |
|-----------------------|--------------------|
| Fresh ice             | FRESH_ICE          |
| First year sea ice    | FIRST_YEAR_SEA_ICE |
| Multiple year sea ice | MULTI_YEAR_SEA_ICE |
| Ice floe              | ICE_FLOE           |
| Ice ridge             | ICE_RIDGE          |

**Table A.11:** CRTM Surface structure valid Ice\_Type definitions.

### *A.5.1 CRTM\_Surface\_Associated interface*

NAME:

CRTM\_Surface\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM Surface object.

CALLING SEQUENCE:

Status = CRTM\_Surface\_Associated( Sfc )

OBJECTS:

Sfc:           Surface structure which is to have its member's status tested.  
UNITS:         N/A  
TYPE:          CRTM\_Surface\_type  
DIMENSION:    Scalar or any rank  
ATTRIBUTES:   INTENT(IN)

FUNCTION RESULT:

Status:       The return value is a logical value indicating the status of the Surface members.  
              .TRUE. - if the array components are allocated.  
              .FALSE. - if the array components are not allocated.  
UNITS:         N/A  
TYPE:          LOGICAL  
DIMENSION:    Same as input

### *A.5.2 CRTM\_Surface\_Compare interface*

NAME:

CRTM\_Surface\_Compare

PURPOSE:

Elemental function to compare two CRTM\_Surface objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_Surface\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y:           Two CRTM Surface objects to be compared.  
UNITS:         N/A  
TYPE:          CRTM\_Surface\_type  
DIMENSION:    Scalar or any rank  
ATTRIBUTES:   INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig:       Number of significant figure to compare floating point components.

UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.5.3 CRTM\_Surface\_CoverageType interface

NAME:

CRTM\_Surface\_CoverageType

PURPOSE:

Elemental function to return the gross surface type based on coverage.

CALLING SEQUENCE:

type = CRTM\_Surface\_CoverageType( sfc )

INPUTS:

Sfc: CRTM Surface object for which the gross surface type is required.  
 UNITS: N/A  
 TYPE: CRTM\_Surface\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN)

FUNCTION:

type: Surface type indicator for the passed CRTM Surface object.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Same as input

COMMENTS:

For a scalar Surface object, this function result can be used to determine what gross surface types are included by using it to index the SURFACE\_TYPE\_NAME parameter arrays, e.g.

```
WRITE(*,*) SURFACE_TYPE_NAME(CRTM_Surface_CoverageType(sfc))
```

### A.5.4 CRTM\_Surface\_Create interface

NAME:

CRTM\_Surface\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM Surface object.

CALLING SEQUENCE:

```
CALL CRTM_Surface_Create( Sfc      , &
                          n_Channels )
```

OBJECTS:

```
Sfc:      Surface structure.
          UNITS:      N/A
          TYPE:      CRTM_Surface_type
          DIMENSION:  Scalar or any rank
          ATTRIBUTES: INTENT(OUT)
```

INPUT ARGUMENTS:

```
n_Channels:  Number of channels dimension of SensorData
              substructure
              ** Note: Can be = 0 (i.e. no sensor data). **
              UNITS:      N/A
              TYPE:      INTEGER
              DIMENSION:  Same as Surface object
              ATTRIBUTES: INTENT(IN)
```

#### *A.5.5 CRTM\_Surface\_DefineVersion interface*

NAME:

```
CRTM_Surface_DefineVersion
```

PURPOSE:

```
Subroutine to return the module version information.
```

CALLING SEQUENCE:

```
CALL CRTM_Surface_DefineVersion( Id )
```

OUTPUT ARGUMENTS:

```
Id:      Character string containing the version Id information
         for the module.
         UNITS:      N/A
         TYPE:      CHARACTER(*)
         DIMENSION:  Scalar
         ATTRIBUTES: INTENT(OUT)
```

#### *A.5.6 CRTM\_Surface\_Destroy interface*

NAME:

```
CRTM_Surface_Destroy
```

PURPOSE:

```
Elemental subroutine to re-initialize CRTM Surface objects.
```

CALLING SEQUENCE:

CALL CRTM\_Surface\_Destroy( Sfc )

OBJECTS:

Sfc: Re-initialized Surface structure.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

### *A.5.7 CRTM\_Surface\_Inspect interface*

NAME:

CRTM\_Surface\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM Surface object to stdout.

CALLING SEQUENCE:

CALL CRTM\_Surface\_Inspect( Sfc )

INPUTS:

Sfc: CRTM Surface object to display.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

### *A.5.8 CRTM\_Surface\_IsCoverageValid interface*

NAME:

CRTM\_Surface\_IsCoverageValid

PURPOSE:

Function to determine if the coverage fractions are valid for a CRTM Surface object.

CALLING SEQUENCE:

result = CRTM\_Surface\_IsCoverageValid( Sfc )

OBJECTS:

Sfc: CRTM Surface object which is to have its coverage fractions checked.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Scalar

ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Surface object coverage fractions are invalid.  
== .TRUE., Surface object coverage fractions are valid.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### A.5.9 CRTM\_Surface\_IsValid interface

NAME:

CRTM\_Surface\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a  
CRTM Surface object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = CRTM\_Surface\_IsValid( Sfc )

or

IF ( CRTM\_Surface\_IsValid( Sfc ) ) THEN....

OBJECTS:

Sfc: CRTM Surface object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Surface object is unused or contains  
invalid data.  
== .TRUE., Surface object can be used in CRTM.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

#### *A.5.10 CRTM\_Surface\_Zero interface*

NAME:

CRTM\_Surface\_Zero

PURPOSE:

Elemental subroutine to zero out the data arrays  
in a CRTM Surface object.

CALLING SEQUENCE:

CALL CRTM\_Surface\_Zero( Sfc )

OUTPUT ARGUMENTS:

Sfc: CRTM Surface structure in which the data arrays  
are to be zeroed out.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

COMMENTS:

- The various surface type indicator flags are  
\*NOT\* reset in this routine.

#### *A.5.11 CRTM\_Surface\_IOVersion interface*

NAME:

CRTM\_Surface\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Surface\_IOVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

#### *A.5.12 CRTM\_Surface\_InquireFile interface*

NAME:

CRTM\_Surface\_InquireFile

PURPOSE:

Function to inquire CRTM Surface object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Surface_InquireFile( Filename           , &
                                         n_Channels = n_Channels, &
                                         n_Profiles = n_Profiles )
```

INPUTS:

Filename: Character string specifying the name of a  
CRTM Surface data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_Channels: The number of spectral channels for which there is  
data in the file. Note that this value will always  
be 0 for a profile-only dataset-- it only has meaning  
for K-matrix data.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

n\_Profiles: The number of profiles in the data file.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### A.5.13 CRTM\_Surface\_ReadFile interface

NAME:

CRTM\_Surface\_ReadFile

PURPOSE:

Function to read CRTM Surface object files.



#### CALLING SEQUENCE:

```
Error_Status = CRTM_Surface_ReadFile( Filename           , &
                                     Surface             , &
                                     Quiet               = Quiet           , &
                                     n_Channels          = n_Channels        , &
                                     n_Profiles          = n_Profiles        , &
```

#### INPUTS:

Filename: Character string specifying the name of an  
Surface format data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

#### OUTPUTS:

Surface: CRTM Surface object array containing the Surface  
data. Note the following meanings attributed to the  
dimensions of the object array:  
Rank-1: M profiles.  
Only profile data are to be read in. The file  
does not contain channel information. The  
dimension of the structure is understood to  
be the PROFILE dimension.  
Rank-2: L channels x M profiles  
Channel and profile data are to be read in.  
The file contains both channel and profile  
information. The first dimension of the  
structure is the CHANNEL dimension, the second  
is the PROFILE dimension. This is to allow  
K-matrix structures to be read in with the  
same function.  
UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Rank-1 (M) or Rank-2 (L x M)  
ATTRIBUTES: INTENT(OUT)

#### OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### OPTIONAL OUTPUTS:

n\_Channels: The number of channels for which data was read. Note that  
this value will always be 0 for a profile-only dataset--  
it only has meaning for K-matrix data.  
UNITS: N/A

TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: OPTIONAL, INTENT(OUT)

n\_Profiles: The number of profiles for which data was read.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: OPTIONAL, INTENT(OUT)

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
 The error codes are defined in the Message\_Handler module.  
 If == SUCCESS, the file read was successful  
           == FAILURE, an unrecoverable error occurred.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar

### A.5.14 CRTM\_Surface\_WriteFile interface

#### NAME:

CRTM\_Surface\_WriteFile

#### PURPOSE:

Function to write CRTM Surface object files.

#### CALLING SEQUENCE:

```
Error_Status = CRTM_Surface_WriteFile( Filename      , &
                                       Surface        , &
                                       Quiet = Quiet  )
```

#### INPUTS:

Filename: Character string specifying the name of the  
 Surface format data file to write.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN)

Surface: CRTM Surface object array containing the Surface  
 data. Note the following meanings attributed to the  
 dimensions of the Surface array:  
 Rank-1: M profiles.  
           Only profile data are to be read in. The file  
           does not contain channel information. The  
           dimension of the array is understood to  
           be the PROFILE dimension.  
 Rank-2: L channels x M profiles

Channel and profile data are to be read in.  
The file contains both channel and profile  
information. The first dimension of the  
array is the CHANNEL dimension, the second  
is the PROFILE dimension. This is to allow  
K-matrix structures to be read in with the  
same function.

UNITS: N/A  
TYPE: CRTM\_Surface\_type  
DIMENSION: Rank-1 (M) or Rank-2 (L x M)  
ATTRIBUTES: INTENT(IN)

#### OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before  
returning to the calling routine.

## A.6 SensorData Structure

```

TYPE :: CRTM_SensorData_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimension values
  INTEGER :: n_Channels = 0 ! L
  ! The data sensor IDs
  CHARACTER(STRLEN) :: Sensor_Id      = ' '
  INTEGER           :: WMO_Satellite_ID = INVALID_WMO_SATELLITE_ID
  INTEGER           :: WMO_Sensor_ID   = INVALID_WMO_SENSOR_ID
  ! The sensor channels and brightness temperatures
  INTEGER , ALLOCATABLE :: Sensor_Channel(:) ! L
  REAL(fp), ALLOCATABLE :: Tb(:)           ! L
END TYPE CRTM_SensorData_type

```

**Figure A.6:** CRTM\_SensorData\_type structure definition.

| Component        | Description  | Units  | Dimensions |
|------------------|--|--------|------------|
| n_Channels       | Number of channels to use in SfcOptics emissivity algorithms (L) | N/A    | Scalar     |
| Sensor_Id        | The sensor id  | N/A    | Scalar     |
| WMO_Satellite_Id | The WMO satellite Id   | N/A    | Scalar     |
| WMO_Sensor_Id    | The WMO sensor Id  | N/A    | Scalar     |
| Sensor_Channel   | The channel numbers  | N/A    | L          |
| Tb               | The brightness temperature measurements for each channel         | Kelvin | L          |

**Table A.12:** CRTM SensorData structure component description.

### *A.6.1 CRTM\_SensorData\_Associated interface*

NAME:

CRTM\_SensorData\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM SensorData object.

CALLING SEQUENCE:

Status = CRTM\_SensorData\_Associated( SensorData )

OBJECTS:

SensorData: SensorData structure which is to have its member's status tested.

UNITS: N/A

TYPE: CRTM\_SensorData\_type

DIMENSION: Scalar or any rank

ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the SensorData members.

.TRUE. - if the array components are allocated.

.FALSE. - if the array components are not allocated.

UNITS: N/A

TYPE: LOGICAL

DIMENSION: Same as input SensorData argument

### *A.6.2 CRTM\_SensorData\_Compare interface*

NAME:

CRTM\_SensorData\_Compare

PURPOSE:

Elemental function to compare two CRTM\_SensorData objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_SensorData\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y: Two CRTM SensorData objects to be compared.

UNITS: N/A

TYPE: CRTM\_SensorData\_type

DIMENSION: Scalar or any rank

ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig: Number of significant figure to compare floating point components.

UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.6.3 *CRTM\_SensorData\_Create interface*

NAME:

CRTM\_SensorData\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM SensorData object.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_Create( SensorData, n\_Channels )

OBJECTS:

SensorData: SensorData structure.  
 UNITS: N/A  
 TYPE: CRTM\_SensorData\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Channels: Number of sensor channels.  
 Must be > 0.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Same as SensorData object  
 ATTRIBUTES: INTENT(IN)

### A.6.4 *CRTM\_SensorData\_DefineVersion interface*

NAME:

CRTM\_SensorData\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_DefineVersion( Id )

OUTPUT ARGUMENTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.6.5 CRTM\_SensorData\_Destroy interface*

NAME:

CRTM\_SensorData\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM SensorData objects.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_Destroy( SensorData )

OBJECTS:

SensorData: Re-initialized SensorData structure.  
UNITS: N/A  
TYPE: CRTM\_SensorData\_type  
DIMENSION: Scalar OR any rank  
ATTRIBUTES: INTENT(OUT)

### *A.6.6 CRTM\_SensorData\_Inspect interface*

NAME:

CRTM\_SensorData\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM SensorData object to stdout.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_Inspect( SensorData )

INPUTS:

SensorData: CRTM SensorData object to display.  
UNITS: N/A  
TYPE: CRTM\_SensorData\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

### *A.6.7 CRTM\_SensorData\_IsValid interface*

NAME:

CRTM\_SensorData\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a CRTM SensorData object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = CRTM\_SensorData\_IsValid( SensorData )

or

IF ( CRTM\_SensorData\_IsValid( SensorData ) ) THEN....

OBJECTS:

SensorData: CRTM SensorData object which is to have its contents checked.  
UNITS: N/A  
TYPE: CRTM\_SensorData\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input passed the check.  
If == .FALSE., SensorData object is unused or contains invalid data.  
== .TRUE., SensorData object can be used in CRTM.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### *A.6.8 CRTM\_SensorData\_Zero interface*

NAME:

CRTM\_SensorData\_Zero

PURPOSE:

Elemental subroutine to zero out the data arrays in a CRTM SensorData object.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_Zero( SensorData )

OBJECTS:

SensorData: CRTM SensorData structure in which the data arrays are



to be zeroed out.  
 UNITS: N/A  
 TYPE: CRTM\_SensorData\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN OUT)

COMMENTS:

- The dimension components of the structure are *\*NOT\** set to zero.
- The SensorData sensor id and channel components are *\*NOT\** reset.

### *A.6.9 CRTM\_SensorData\_IOVersion interface*

NAME:

CRTM\_SensorData\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_SensorData\_IOVersion( Id )

OUTPUT ARGUMENTS:

Id: Character string containing the version Id information  
 for the module.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(OUT)

### *A.6.10 CRTM\_SensorData\_InquireFile interface*

NAME:

CRTM\_SensorData\_InquireFile

PURPOSE:

Function to inquire CRTM SensorData object files.

CALLING SEQUENCE:

Error\_Status = CRTM\_SensorData\_InquireFile( Filename , &  
 n\_DataSets = n\_DataSets )

INPUTS:

Filename: Character string specifying the name of a  
 CRTM SensorData data file to read.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar

ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_DataSets: The number of datasets in the file.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### A.6.11 CRTM\_SensorData\_ReadFile interface

NAME:

CRTM\_SensorData\_ReadFile

PURPOSE:

Function to read CRTM SensorData object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_SensorData_ReadFile( Filename           , &  
                                         SensorData         , &  
                                         Quiet              = Quiet      , &  
                                         No_Close           = No_Close   , &  
                                         n_DataSets         = n_DataSets  )
```

INPUTS:

Filename: Character string specifying the name of a  
SensorData format data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OUTPUTS:

SensorData: CRTM SensorData object array containing the sensor data.  
UNITS: N/A  
TYPE: CRTM\_SensorData\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(OUT)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION

```

messages being printed to stdout
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].
    == .TRUE., INFORMATION messages are SUPPRESSED.
If not specified, default is .FALSE.
UNITS:      N/A
TYPE:       LOGICAL
DIMENSION:  Scalar
ATTRIBUTES: INTENT(IN), OPTIONAL

No_Close:   Set this logical argument to NOT close the file upon exit.
            If == .FALSE., the input file is closed upon exit [DEFAULT]
            == .TRUE., the input file is NOT closed upon exit.
            If not specified, default is .FALSE.
UNITS:      N/A
TYPE:       LOGICAL
DIMENSION:  Scalar
ATTRIBUTES: INTENT(IN), OPTIONAL

OPTIONAL OUTPUTS:
  n_DataSets: The actual number of datasets read in.
              UNITS:      N/A
              TYPE:       INTEGER
              DIMENSION:  Scalar
              ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:
  Error_Status: The return value is an integer defining the error status.
               The error codes are defined in the Message_Handler module.
               If == SUCCESS, the file read was successful
               == FAILURE, an unrecoverable error occurred.
UNITS:      N/A
TYPE:       INTEGER
DIMENSION:  Scalar

```

### A.6.12 CRTM\_SensorData\_WriteFile interface

```

NAME:
  CRTM_SensorData_WriteFile

PURPOSE:
  Function to write CRTM SensorData object files.

CALLING SEQUENCE:
  Error_Status = CRTM_SensorData_WriteFile( Filename      , &
                                           SensorData    , &
                                           Quiet      = Quiet , &
                                           No_Close = No_Close )

INPUTS:
  Filename:      Character string specifying the name of the

```

SensorData format data file to write.

UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

SensorData: CRTM SensorData object array containing the datasets.  
UNITS: N/A  
TYPE: CRTM\_SensorData\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(IN)

#### OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

No\_Close: Set this logical argument to NOT close the file upon exit.  
If == .FALSE., the input file is closed upon exit [DEFAULT]  
== .TRUE., the input file is NOT closed upon exit.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

#### SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.

## A.7 Geometry Structure

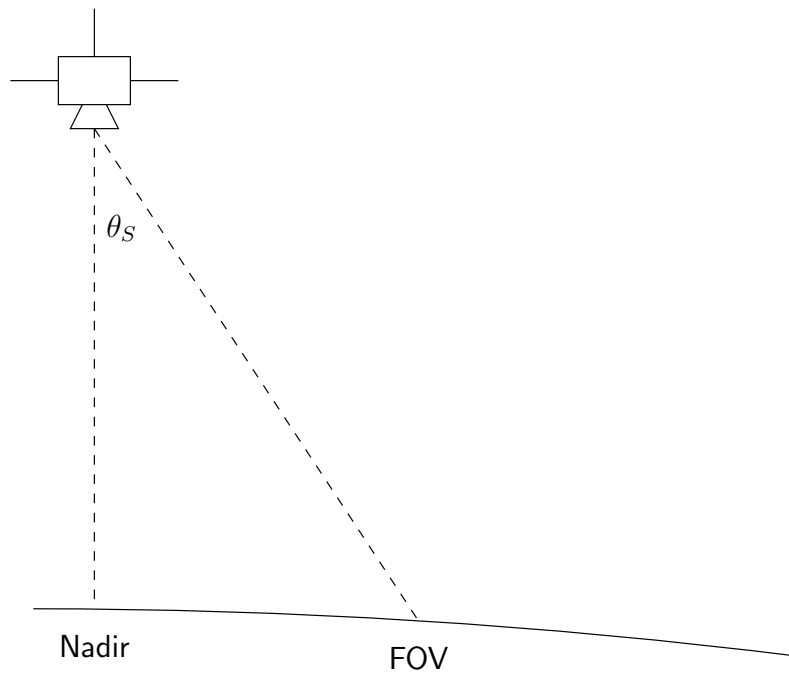
---

```
TYPE :: CRTM_Geometry_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .TRUE.  ! Placeholder for future expansion
  ! Field of view index (1-nFOV)
  INTEGER :: iFOV = 0
  ! Earth location
  REAL(fp) :: Longitude      = ZERO
  REAL(fp) :: Latitude       = ZERO
  REAL(fp) :: Surface_Altitude = ZERO
  ! Sensor angle information
  REAL(fp) :: Sensor_Scan_Angle  = ZERO
  REAL(fp) :: Sensor_Zenith_Angle = ZERO
  REAL(fp) :: Sensor_Azimuth_Angle = ZERO
  ! Source angle information
  REAL(fp) :: Source_Zenith_Angle = 100.0_fp  ! Below horizon
  REAL(fp) :: Source_Azimuth_Angle = ZERO
  ! Flux angle information
  REAL(fp) :: Flux_Zenith_Angle = DIFFUSIVITY_ANGLE
  ! Date for geometry calculations
  INTEGER :: Year  = 2001
  INTEGER :: Month = 1
  INTEGER :: Day   = 1
END TYPE CRTM_Geometry_type
```

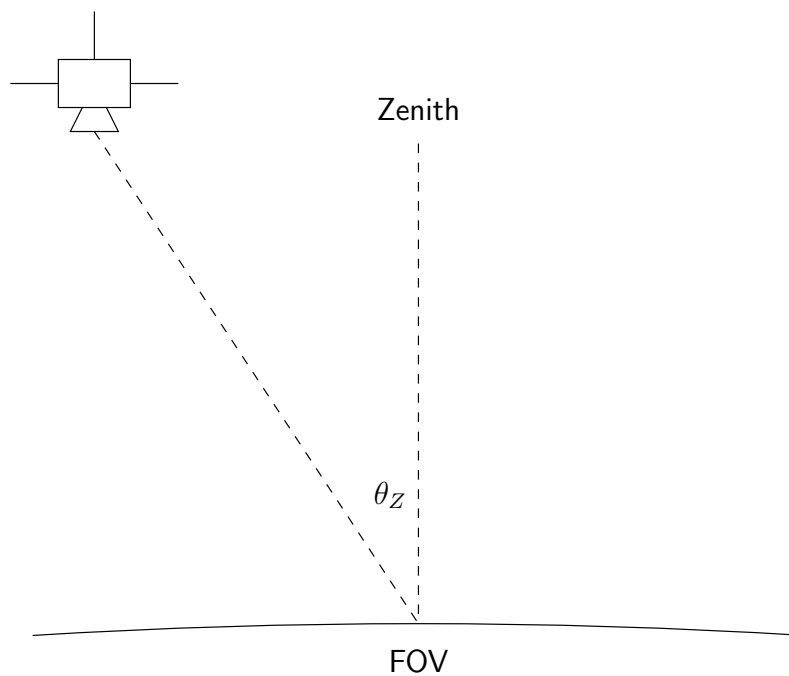
**Figure A.7:** CRTM\_Geometry\_type structure definition.

| Component            | Description  | Units            | Dimensions |
|----------------------|--|------------------|------------|
| iFOV                 | The scan line FOV index  | N/A              | Scalar     |
| Longitude            | Earth longitude  | deg. E (0→360)   | Scalar     |
| Latitude             | Earth latitude   | deg. N (-90→+90) | Scalar     |
| Surface_Altitude     | Altitude of the Earth's surface at the specified lon/lat location  | metres (m)       | Scalar     |
| Sensor_Scan_Angle    | The sensor scan angle from nadir. See fig.A.8  | degrees          | Scalar     |
| Sensor_Zenith_Angle  | The sensor zenith angle of the FOV. See fig.A.9  | degrees          | Scalar     |
| Sensor_Azimuth_Angle | The sensor azimuth angle is the angle subtended by the horizontal projection of a direct line from the satellite to the FOV and the North-South axis measured clockwise from North. See fig.A.10                                   | deg. from N      | Scalar     |
| Source_Zenith_Angle  | The source zenith angle. The source is typically the Sun (IR/VIS) or Moon (MW/VIS) [only solar source valid in current release] See fig.A.11   | degrees          | Scalar     |
| Source_Azimuth_Angle | The source azimuth angle is the angle subtended by the horizontal projection of a direct line from the source to the FOV and the North-South axis measured clockwise from North. See fig.A.12                                      | deg. from N      | Scalar     |
| Flux_Zenith_Angle    | The zenith angle used to approximate downwelling flux transmissivity. If not set, the default value is that of the diffusivity approximation, such that $\sec(F) = 5/3$ . Maximum allowed value is determined from $\sec(F) = 9/4$ | degrees          | Scalar     |
| Year                 | The year in 4-digit format   | N/A              | Scalar     |
| Month                | The month of year (1-12)   | N/A              | Scalar     |
| Day                  | The day of month (1-28/29/30/31)   | N/A              | Scalar     |

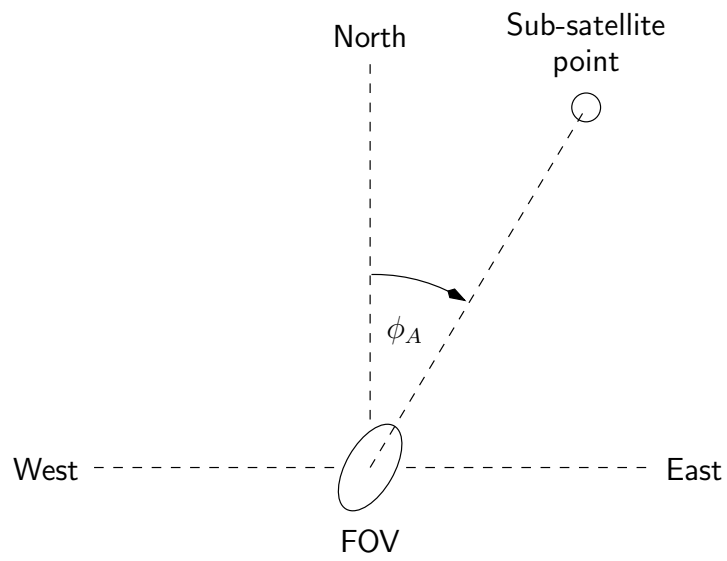
**Table A.13:** CRTM Geometry structure component description.



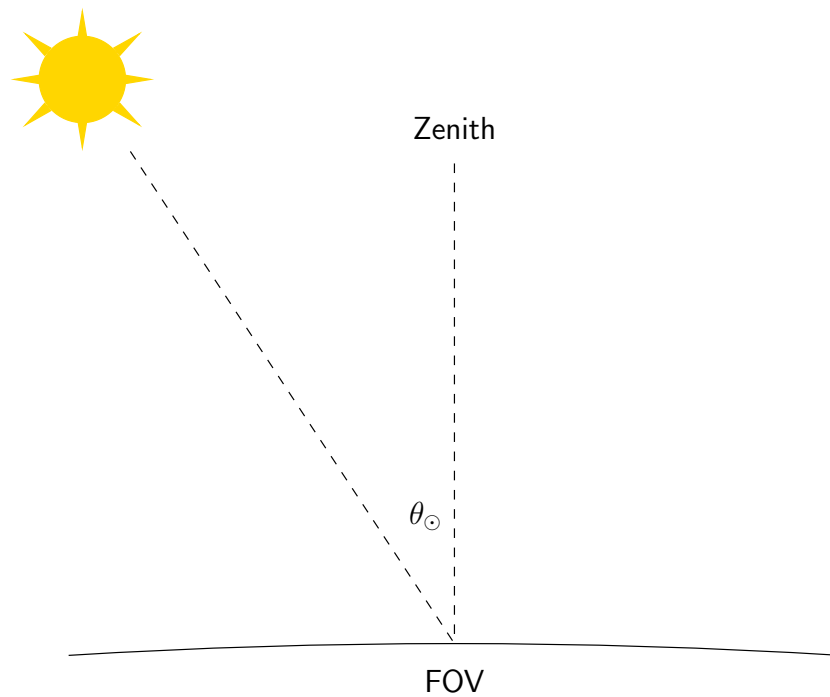
**Figure A.8:** Definition of Geometry sensor scan angle component.



**Figure A.9:** Definition of Geometry sensor zenith angle component.

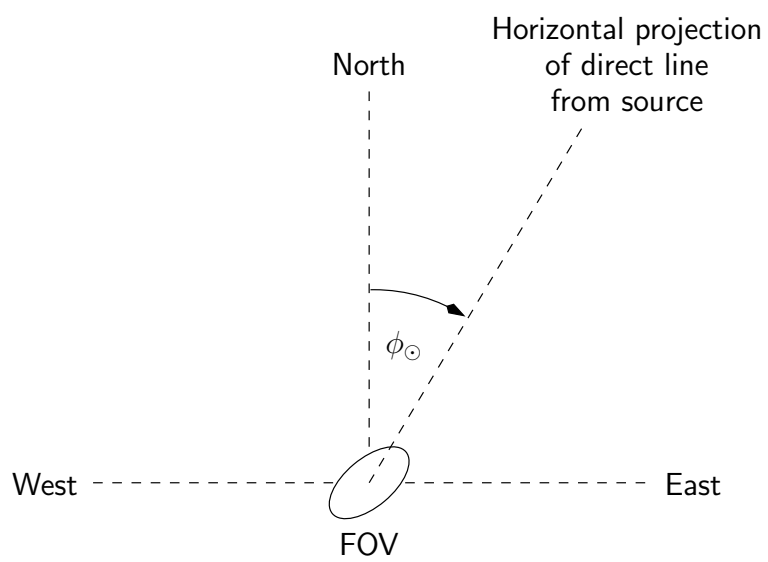


**Figure A.10:** Definition of Geometry sensor azimuth angle component.



**Figure A.11:** Definition of Geometry source zenith angle component.





**Figure A.12:** Definition of Geometry source azimuth angle component.

### *A.7.1 CRTM\_Geometry\_DefineVersion interface*

NAME:

CRTM\_Geometry\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Geometry\_DefineVersion( Id )

OUTPUT ARGUMENTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.7.2 CRTM\_Geometry\_Destroy interface*

NAME:

CRTM\_Geometry\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM Geometry objects.

CALLING SEQUENCE:

CALL CRTM\_Geometry\_Destroy( geo )

OBJECTS:

geo: Re-initialized Geometry structure.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

### *A.7.3 CRTM\_Geometry\_GetValue interface*

NAME:

CRTM\_Geometry\_GetValue

PURPOSE:

Elemental subroutine to get the values of CRTM Geometry  
object components.

# CALLING SEQUENCE:

```

CALL CRTM_Geometry_GetValue( geo, &
                             iFOV           = iFOV           , &
                             Longitude       = Longitude      , &
                             Latitude       = Latitude       , &
                             Surface_Altitude = Surface_Altitude , &
                             Sensor_Scan_Angle = Sensor_Scan_Angle , &
                             Sensor_Zenith_Angle = Sensor_Zenith_Angle , &
                             Sensor_Azimuth_Angle = Sensor_Azimuth_Angle , &
                             Source_Zenith_Angle = Source_Zenith_Angle , &
                             Source_Azimuth_Angle = Source_Azimuth_Angle , &
                             Flux_Zenith_Angle = Flux_Zenith_Angle , &
                             Year           = Year           , &
                             Month          = Month          , &
                             Day            = Day            )

```

# OBJECTS:

```

geo:      Geometry object from which component values
          are to be retrieved.
UNITS:    N/A
TYPE:     CRTM_Geometry_type
DIMENSION: Scalar or any rank
ATTRIBUTES: INTENT(IN OUT)

```

# OPTIONAL OUTPUTS:

```

iFOV:      Sensor field-of-view index.
UNITS:     N/A
TYPE:     INTEGER
DIMENSION: Scalar or same as geo input
ATTRIBUTES: INTENT(OUT), OPTIONAL

Longitude: Earth longitude
UNITS:     degrees East (0->360)
TYPE:     REAL(fp)
DIMENSION: Scalar or same as geo input
ATTRIBUTES: INTENT(OUT), OPTIONAL

Latitude:  Earth latitude.
UNITS:     degrees North (-90->+90)
TYPE:     REAL(fp)
DIMENSION: Scalar or same as geo input
ATTRIBUTES: INTENT(OUT), OPTIONAL

Surface_Altitude: Altitude of the Earth's surface at the specifed
                  lon/lat location.
UNITS:     metres (m)
TYPE:     REAL(fp)
DIMENSION: Scalar or same as geo input
ATTRIBUTES: INTENT(OUT), OPTIONAL

Sensor_Scan_Angle: The sensor scan angle from nadir.
UNITS:     degrees
TYPE:     REAL(fp)
DIMENSION: Scalar or same as geo input

```

ATTRIBUTES: INTENT(OUT), OPTIONAL

Sensor\_Zenith\_Angle: The zenith angle from the field-of-view to the sensor.  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Sensor\_Azimuth\_Angle: The azimuth angle subtended by the horizontal projection of a direct line from the satellite to the FOV and the North-South axis measured clockwise from North.  
 UNITS: degrees from North (0->360)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Source\_Zenith\_Angle: The zenith angle from the field-of-view to a source (sun or moon).  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Source\_Azimuth\_Angle: The azimuth angle subtended by the horizontal projection of a direct line from the source to the FOV and the North-South axis measured clockwise from North.  
 UNITS: degrees from North (0->360)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Flux\_Zenith\_Angle: The zenith angle used to approximate downwelling flux transmissivity  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Year: The year in 4-digit format, e.g. 1997.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Month: The month of the year (1-12).  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Day: The day of the month (1-28/29/30/31).

UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

#### *A.7.4 CRTM\_Geometry\_Inspect interface*

NAME:  
     CRTM\_Geometry\_Inspect

PURPOSE:  
     Subroutine to print the contents of a CRTM Geometry object to stdout.

CALLING SEQUENCE:  
     CALL CRTM\_Geometry\_Inspect( geo )

INPUTS:  
     geo: CRTM Geometry object to display.  
         UNITS: N/A  
         TYPE: CRTM\_Geometry\_type  
         DIMENSION: Scalar  
         ATTRIBUTES: INTENT(IN)

#### *A.7.5 CRTM\_Geometry\_IsValid interface*

NAME:  
     CRTM\_Geometry\_IsValid

PURPOSE:  
     Non-pure function to perform some simple validity checks on a CRTM Geometry object.  
  
     If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:  
     result = CRTM\_Geometry\_IsValid( geo )  
  
     or  
  
     IF ( CRTM\_Geometry\_IsValid( geo ) ) THEN....

OBJECTS:  
     geo: CRTM Geometry object which is to have its contents checked.  
         UNITS: N/A  
         TYPE: CRTM\_Geometry\_type  
         DIMENSION: Scalar

ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Geometry object is unused or contains  
invalid data.  
== .TRUE., Geometry object can be used in CRTM.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### A.7.6 CRTM\_Geometry\_SetValue interface

NAME:

CRTM\_Geometry\_SetValue

PURPOSE:

Elemental subroutine to set the values of CRTM Geometry  
object components.

CALLING SEQUENCE:

```
CALL CRTM_Geometry_SetValue( geo, &  
                             iFOV           = iFOV           , &  
                             Longitude       = Longitude      , &  
                             Latitude        = Latitude       , &  
                             Surface_Altitude = Surface_Altitude , &  
                             Sensor_Scan_Angle = Sensor_Scan_Angle , &  
                             Sensor_Zenith_Angle = Sensor_Zenith_Angle , &  
                             Sensor_Azimuth_Angle = Sensor_Azimuth_Angle , &  
                             Source_Zenith_Angle = Source_Zenith_Angle , &  
                             Source_Azimuth_Angle = Source_Azimuth_Angle , &  
                             Flux_Zenith_Angle = Flux_Zenith_Angle , &  
                             Year            = Year           , &  
                             Month           = Month          , &  
                             Day             = Day            )
```

OBJECTS:

geo: Geometry object for which component values  
are to be set.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

OPTIONAL INPUTS:

iFOV: Sensor field-of-view index.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar or same as geo input

ATTRIBUTES: INTENT(IN), OPTIONAL

Longitude: Earth longitude  
 UNITS: degrees East (0->360)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Latitude: Earth latitude.  
 UNITS: degrees North (-90->+90)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Surface\_Altitude: Altitude of the Earth's surface at the specified lon/lat location.  
 UNITS: metres (m)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Sensor\_Scan\_Angle: The sensor scan angle from nadir.  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Sensor\_Zenith\_Angle: The zenith angle from the field-of-view to the sensor.  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Sensor\_Azimuth\_Angle: The azimuth angle subtended by the horizontal projection of a direct line from the satellite to the FOV and the North-South axis measured clockwise from North.  
 UNITS: degrees from North (0->360)  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Source\_Zenith\_Angle: The zenith angle from the field-of-view to a source (sun or moon).  
 UNITS: degrees  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as geo input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

Source\_Azimuth\_Angle: The azimuth angle subtended by the horizontal projection of a direct line from the source to the FOV and the North-South axis measured clockwise from North.

|                    |  |
|--------------------|--|
|                    | UNITS: degrees from North (0->360)                                   |
|                    | TYPE: REAL(fp)   |
|                    | DIMENSION: Scalar or same as geo input                               |
|                    | ATTRIBUTES: INTENT(IN), OPTIONAL                                     |
| Flux_Zenith_Angle: | The zenith angle used to approximate downwelling flux transmissivity |
|                    | UNITS: degrees   |
|                    | TYPE: REAL(fp)   |
|                    | DIMENSION: Scalar or same as geo input                               |
|                    | ATTRIBUTES: INTENT(IN), OPTIONAL                                     |
| Year:              | The year in 4-digit format, e.g. 1997.                               |
|                    | UNITS: N/A   |
|                    | TYPE: INTEGER  |
|                    | DIMENSION: Scalar or same as geo input                               |
|                    | ATTRIBUTES: INTENT(IN), OPTIONAL                                     |
| Month:             | The month of the year (1-12).  |
|                    | UNITS: N/A   |
|                    | TYPE: INTEGER  |
|                    | DIMENSION: Scalar or same as geo input                               |
|                    | ATTRIBUTES: INTENT(IN), OPTIONAL                                     |
| Day:               | The day of the month (1-28/29/30/31).                                |
|                    | UNITS: N/A   |
|                    | TYPE: INTEGER  |
|                    | DIMENSION: Scalar or same as geo input                               |
|                    | ATTRIBUTES: INTENT(IN), OPTIONAL                                     |

### *A.7.7 CRTM\_Geometry\_IOVersion interface*

NAME:

CRTM\_Geometry\_IOVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Geometry\_IOVersion( Id )

OUTPUT ARGUMENTS:

|     |  |
|-----|--|
| Id: | Character string containing the version Id information for the module. |
|     | UNITS: N/A   |
|     | TYPE: CHARACTER(*)   |
|     | DIMENSION: Scalar  |
|     | ATTRIBUTES: INTENT(OUT)  |



### *A.7.8 CRTM\_Geometry\_InquireFile interface*

NAME:

CRTM\_Geometry\_InquireFile

PURPOSE:

Function to inquire CRTM Geometry object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Geometry_InquireFile( Filename           , &
                                           n_Profiles = n_Profiles )
```

INPUTS:

Filename: Character string specifying the name of a  
CRTM Geometry data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

OPTIONAL OUTPUTS:

n\_Profiles: The number of profiles for which there is geometry  
information in the data file.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file inquire was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### *A.7.9 CRTM\_Geometry\_ReadFile interface*

NAME:

CRTM\_Geometry\_ReadFile

PURPOSE:

Function to read CRTM Geometry object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Geometry_ReadFile( Filename           , &
                                       Geometry             , &
                                       Quiet = Quiet         , &
                                       n_Profiles = n_Profiles )
```

#### INPUTS:

Filename: Character string specifying the name of an  
a Geometry data file to read.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

#### OUTPUTS:

Geometry: CRTM Geometry object array containing the  
data read from file.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(OUT)

#### OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

#### OPTIONAL OUTPUTS:

n\_Profiles: The number of profiles for which data was read.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar  
ATTRIBUTES: OPTIONAL, INTENT(OUT)

#### FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file read was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

### A.7.10 CRTM\_Geometry\_WriteFile interface

#### NAME:

CRTM\_Geometry\_WriteFile

#### PURPOSE:

Function to write CRTM Geometry object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_Geometry_WriteFile( Filename      , &
                                         Geometry      , &
                                         Quiet = Quiet  )
```

INPUTS:

Filename: Character string specifying the name of the  
Geometry format data file to write.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

Geometry: CRTM Geometry object array containing the Geometry  
data to write.  
UNITS: N/A  
TYPE: CRTM\_Geometry\_type  
DIMENSION: Rank-1  
ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.

## A.8 RTSolution Structure

---

```
TYPE :: CRTM_RTSolution_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Dimensions
  INTEGER :: n_Layers = 0 ! K
  ! Internal variables. Users do not need to worry about these.
  LOGICAL :: Scattering_Flag = .TRUE.
  INTEGER :: n_Full_Streams = 0
  INTEGER :: n_Stokes = 0
  ! Forward radiative transfer intermediate results for a single channel
  !   These components are not defined when they are used as TL, AD
  !   and K variables
  REAL(fp) :: Surface_Emissivity = ZERO
  REAL(fp) :: Up_Radiance = ZERO
  REAL(fp) :: Down_Radiance = ZERO
  REAL(fp) :: Down_Solar_Radiance = ZERO
  REAL(fp) :: Surface_Planck_Radiance = ZERO
  REAL(fp), ALLOCATABLE :: Upwelling_Radiance(:) ! K
  ! The layer optical depths
  REAL(fp), ALLOCATABLE :: Layer_Optical_Depth(:) ! K
  ! Radiative transfer results for a single channel/node
  REAL(fp) :: Radiance = ZERO
  REAL(fp) :: Brightness_Temperature = ZERO
END TYPE CRTM_RTSolution_type
```

**Figure A.13:** CRTM\_RTSolution\_type structure definition.

| Component               | Description  | Units                                     | Dimensions |
|-------------------------|--|---|------------|
| n_Layers                | Number of atmospheric profile layers (K)   | N/A                                       | Scalar     |
| Surface_Emissivity      | The computed surface emissivity  | N/A                                       | Scalar     |
| Up_Radiance             | The atmospheric portion of the upwelling radiance  | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | Scalar     |
| Down_Radiance           | The atmospheric portion of the downwelling radiance  | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | Scalar     |
| Down_Solar_Radiance     | The downwelling direct solar radiance  | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | Scalar     |
| Surface_Planck_Radiance | The surface radiance   | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | Scalar     |
| Upwelling_Radiance      | The upwelling radiance profile, including the reflected downwelling and surface contributions. | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | K          |
| Layer_Optical_Depth     | The layer optical depth profile  | N/A                                       | K          |
| Radiance                | The sensor radiance  | mW/(m <sup>2</sup> .sr.cm <sup>-1</sup> ) | Scalar     |
| Brightness_Temperature  | The sensor brightness temperature  | Kelvin                                    | Scalar     |

**Table A.14:** CRTM RTSolution structure component description

### *A.8.1 CRTM\_RTSolution\_Associated interface*

NAME:

CRTM\_RTSolution\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM RTSolution object.

CALLING SEQUENCE:

Status = CRTM\_RTSolution\_Associated( RTSolution )

OBJECTS:

RTSolution: RTSolution structure which is to have its member's status tested.

UNITS: N/A

TYPE: CRTM\_RTSolution\_type

DIMENSION: Scalar or any rank

ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the RTSolution members.  
.TRUE. - if the array components are allocated.  
.FALSE. - if the array components are not allocated.

UNITS: N/A

TYPE: LOGICAL

DIMENSION: Same as input RTSolution argument

### *A.8.2 CRTM\_RTSolution\_Compare interface*

NAME:

CRTM\_RTSolution\_Compare

PURPOSE:

Elemental function to compare two CRTM\_RTSolution objects to within a user specified number of significant figures.

CALLING SEQUENCE:

is\_comparable = CRTM\_RTSolution\_Compare( x, y, n\_SigFig=n\_SigFig )

OBJECTS:

x, y: Two CRTM RTSolution objects to be compared.

UNITS: N/A

TYPE: CRTM\_RTSolution\_type

DIMENSION: Scalar or any rank

ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

n\_SigFig: Number of significant figure to compare floating point components.

UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

is\_equal: Logical value indicating whether the inputs are equal.  
 UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Same as inputs.

### A.8.3 CRTM\_RTSolution\_Create interface

NAME:

CRTM\_RTSolution\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM RTSolution object.

CALLING SEQUENCE:

CALL CRTM\_RTSolution\_Create( RTSolution, n\_Layers )

OBJECTS:

RTSolution: RTSolution structure.  
 UNITS: N/A  
 TYPE: CRTM\_RTSolution\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Layers: Number of layers for which there is RTSolution data.  
 Must be > 0.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Same as RTSolution object  
 ATTRIBUTES: INTENT(IN)

### A.8.4 CRTM\_RTSolution\_DefineVersion interface

NAME:

CRTM\_RTSolution\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_RTSolution\_DefineVersion( Id )

OUTPUTS:  
     Id:                   Character string containing the version Id information  
                           for the module.  
     UNITS:                N/A  
     TYPE:                 CHARACTER(\*)  
     DIMENSION:   Scalar  
     ATTRIBUTES: INTENT(OUT)

#### *A.8.5 CRTM\_RTSolution\_Destroy interface*

NAME:  
     CRTM\_RTSolution\_Destroy

PURPOSE:  
     Elemental subroutine to re-initialize CRTM RTSolution objects.

CALLING SEQUENCE:  
     CALL CRTM\_RTSolution\_Destroy( RTSolution )

OBJECTS:  
     RTSolution:   Re-initialized RTSolution structure.  
                   UNITS:        N/A  
                   TYPE:         CRTM\_RTSolution\_type  
                   DIMENSION:   Scalar OR any rank  
                   ATTRIBUTES: INTENT(OUT)

#### *A.8.6 CRTM\_RTSolution\_Inspect interface*

NAME:  
     CRTM\_RTSolution\_Inspect

PURPOSE:  
     Subroutine to print the contents of a CRTM RTSolution object to stdout.

CALLING SEQUENCE:  
     CALL CRTM\_RTSolution\_Inspect( RTSolution )

INPUTS:  
     RTSolution:   CRTM RTSolution object to display.  
                   UNITS:        N/A  
                   TYPE:         CRTM\_RTSolution\_type  
                   DIMENSION:   Scalar  
                   ATTRIBUTES: INTENT(IN)



### A.8.7 CRTM\_RTSolution\_IOVersion interface

NAME:  
    CRTM\_RTSolution\_IOVersion

PURPOSE:  
    Subroutine to return the module version information.

CALLING SEQUENCE:  
    CALL CRTM\_RTSolution\_IOVersion( Id )

OUTPUTS:

|             |  |
|-------------|--|
| Id:         | Character string containing the version Id information for the module. |
| UNITS:      | N/A  |
| TYPE:       | CHARACTER(*)   |
| DIMENSION:  | Scalar   |
| ATTRIBUTES: | INTENT(OUT)  |

### A.8.8 CRTM\_RTSolution\_InquireFile interface

NAME:  
    CRTM\_RTSolution\_InquireFile

PURPOSE:  
    Function to inquire CRTM RTSolution object files.

CALLING SEQUENCE:  
    Error\_Status = CRTM\_RTSolution\_InquireFile( Filename , &  
  n\_Channels = n\_Channels, &  
  n\_Profiles = n\_Profiles )

INPUTS:

|             |  |
|-------------|--|
| Filename:   | Character string specifying the name of a CRTM RTSolution data file to read. |
| UNITS:      | N/A  |
| TYPE:       | CHARACTER(*)   |
| DIMENSION:  | Scalar   |
| ATTRIBUTES: | INTENT(IN)   |

OPTIONAL OUTPUTS:

|             |  |
|-------------|--|
| n_Channels: | The number of spectral channels for which there is data in the file. |
| UNITS:      | N/A  |
| TYPE:       | INTEGER  |
| DIMENSION:  | Scalar   |
| ATTRIBUTES: | OPTIONAL, INTENT(OUT)  |
| n_Profiles: | The number of profiles in the data file.                             |
| UNITS:      | N/A  |

TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: OPTIONAL, INTENT(OUT)

**FUNCTION RESULT:**

Error\_Status: The return value is an integer defining the error status.  
 The error codes are defined in the Message\_Handler module.  
 If == SUCCESS, the file inquire was successful  
 == FAILURE, an unrecoverable error occurred.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar

### *A.8.9 CRTM\_RTSolution\_ReadFile interface*

**NAME:**

CRTM\_RTSolution\_ReadFile

**PURPOSE:**

Function to read CRTM RTSolution object files.

**CALLING SEQUENCE:**

```
Error_Status = CRTM_RTSolution_ReadFile( Filename           , &
                                         RTSolution          , &
                                         Quiet               = Quiet       , &
                                         n_Channels          = n_Channels    , &
                                         n_Profiles          = n_Profiles    , &
```

**INPUTS:**

Filename: Character string specifying the name of an  
 RTSolution format data file to read.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN)

**OUTPUTS:**

RTSolution: CRTM RTSolution object array containing the RTSolution  
 data.  
 UNITS: N/A  
 TYPE: CRTM\_RTSolution\_type  
 DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
 ATTRIBUTES: INTENT(OUT)

**OPTIONAL INPUTS:**

Quiet: Set this logical argument to suppress INFORMATION  
 messages being printed to stdout  
 If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
 == .TRUE., INFORMATION messages are SUPPRESSED.  
 If not specified, default is .FALSE.

UNITS: N/A  
 TYPE: LOGICAL  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN), OPTIONAL

OPTIONAL OUTPUTS:

n\_Channels: The number of channels for which data was read.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: OPTIONAL, INTENT(OUT)

n\_Profiles: The number of profiles for which data was read.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar  
 ATTRIBUTES: OPTIONAL, INTENT(OUT)

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
 The error codes are defined in the Message\_Handler module.  
 If == SUCCESS, the file read was successful  
       == FAILURE, an unrecoverable error occurred.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar

#### A.8.10 CRTM\_RTSolution\_WriteFile interface

NAME:

CRTM\_RTSolution\_WriteFile

PURPOSE:

Function to write CRTM RTSolution object files.

CALLING SEQUENCE:

```
Error_Status = CRTM_RTSolution_WriteFile( Filename      , &
                                           RTSolution    , &
                                           Quiet = Quiet  )
```

INPUTS:

Filename: Character string specifying the name of the  
 RTSolution format data file to write.  
 UNITS: N/A  
 TYPE: CHARACTER(\*)  
 DIMENSION: Scalar  
 ATTRIBUTES: INTENT(IN)

RTSolution: CRTM RTSolution object array containing the RTSolution

data.  
UNITS: N/A  
TYPE: CRTM\_RTSolution\_type  
DIMENSION: Rank-2 (n\_Channels x n\_Profiles)  
ATTRIBUTES: INTENT(IN)

OPTIONAL INPUTS:

Quiet: Set this logical argument to suppress INFORMATION  
messages being printed to stdout  
If == .FALSE., INFORMATION messages are OUTPUT [DEFAULT].  
== .TRUE., INFORMATION messages are SUPPRESSED.  
If not specified, default is .FALSE.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN), OPTIONAL

FUNCTION RESULT:

Error\_Status: The return value is an integer defining the error status.  
The error codes are defined in the Message\_Handler module.  
If == SUCCESS, the file write was successful  
== FAILURE, an unrecoverable error occurred.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar

SIDE EFFECTS:

- If the output file already exists, it is overwritten.
- If an error occurs during \*writing\*, the output file is deleted before returning to the calling routine.

## A.9 Options Structure

---

```
TYPE :: CRTM_Options_type
  ! Allocation indicator
  LOGICAL :: Is_Allocated = .FALSE.
  ! Input checking on by default
  LOGICAL :: Check_Input = .TRUE.
  ! User defined emissivity/reflectivity
  ! ...Dimensions
  INTEGER :: n_Channels = 0 ! L dimension
  ! ...Index into channel-specific components
  INTEGER :: Channel = 0
  ! ...Emissivity optional arguments
  LOGICAL :: Use_Emissivity = .FALSE.
  REAL(fp), ALLOCATABLE :: Emissivity(:) ! L
  ! ...Direct reflectivity optional arguments
  LOGICAL :: Use_Direct_Reflectivity = .FALSE.
  REAL(fp), ALLOCATABLE :: Direct_Reflectivity(:) ! L
  ! Antenna correction application
  LOGICAL :: Use_Antenna_Correction = .FALSE.
  ! SSU instrument input
  TYPE(SSU_Input_type) :: SSU
  ! Zeeman-splitting input
  TYPE(Zeeman_Input_type) :: Zeeman
END TYPE CRTM_Options_type
```

**Figure A.14:** CRTM\_Options\_type structure definition.

| Component               | Description   | Units | Dimensions |
|-------------------------|---|-------|------------|
| Check_Input             | Logical switch to enable or disable input data checking.<br>If:<br>.FALSE.: No input data check.<br>.TRUE. : Input data <i>is</i> checked [DEFAULT].  | N/A   | Scalar     |
| n_Channels              | Number of sensor channels (L).  | N/A   | Scalar     |
| Channel                 | Index into channel-specific components.   | N/A   | Scalar     |
| Use_Emissivity          | Logical switch to apply user-defined surface emissivity.<br>If:<br>.FALSE.: Calculate emissivity [DEFAULT].<br>.TRUE. : Use user-defined emissivity   | N/A   | Scalar     |
| Emissivity              | User-defined surface emissivity for each sensor channel.  | N/A   | L          |
| Use_Direct_Reflectivity | Logical switch to apply user-defined reflectivity for downwelling source (e.g. solar). This switch is ignored unless the <code>Use_Emissivity</code> switch is also set. If:<br>.FALSE.: Calculate reflectivity [DEFAULT].<br>.TRUE. : Use user-defined reflectivity  | N/A   | Scalar     |
| Direct_Reflectivity     | User-defined direct reflectivity for downwelling source for each sensor channel.  | N/A   | L          |
| Use_Antenna_Correction  | Logical switch to apply antenna correction for the AMSU-A, AMSU-B, and MHS sensors. Note that for this switch to be effective in the CRTM call, the FOV field of the input <code>Geometry</code> structure must be set and the antenna correction coefficients must be present in the sensor <code>SpcCoeff</code> datafile. If:<br>.FALSE.: No correction [DEFAULT].<br>.TRUE. : Apply antenna correction. | N/A   | Scalar     |
| SSU                     | Structure component containing optional SSU sensor-specific input. See section <a href="#">A.10</a> .   | N/A   | Scalar     |
| Zeeman                  | Structure component containing optional input for those sensors where Zeeman-splitting is an issue for high-peaking channels. See section <a href="#">A.11</a> .  | N/A   | Scalar     |

**Table A.15:** CRTM Options structure component description

### *A.9.1 CRTM\_Options\_Associated interface*

NAME:

CRTM\_Options\_Associated

PURPOSE:

Elemental function to test the status of the allocatable components of a CRTM Options object.

CALLING SEQUENCE:

Status = CRTM\_Options\_Associated( Options )

OBJECTS:

Options: Options structure which is to have its member's status tested.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

Status: The return value is a logical value indicating the status of the Options members.  
.TRUE. - if the array components are allocated.  
.FALSE. - if the array components are not allocated.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Same as input Options argument

### *A.9.2 CRTM\_Options\_Create interface*

NAME:

CRTM\_Options\_Create

PURPOSE:

Elemental subroutine to create an instance of the CRTM Options object.

CALLING SEQUENCE:

CALL CRTM\_Options\_Create( Options, n\_Channels )

OBJECTS:

Options: Options structure.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(OUT)

INPUTS:

n\_Channels: Number of channels for which there is Options data.  
Must be > 0.

This dimension only applies to the emissivity-related components.

UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Same as Options object  
ATTRIBUTES: INTENT(IN)

### *A.9.3 CRTM\_Options\_DefineVersion interface*

NAME:

CRTM\_Options\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL CRTM\_Options\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information for the module.

UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.9.4 CRTM\_Options\_Destroy interface*

NAME:

CRTM\_Options\_Destroy

PURPOSE:

Elemental subroutine to re-initialize CRTM Options objects.

CALLING SEQUENCE:

CALL CRTM\_Options\_Destroy( Options )

OBJECTS:

Options: Re-initialized Options structure.

UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Scalar OR any rank  
ATTRIBUTES: INTENT(OUT)



### *A.9.5 CRTM\_Options\_Inspect interface*

NAME:

CRTM\_Options\_Inspect

PURPOSE:

Subroutine to print the contents of a CRTM Options object to stdout.

CALLING SEQUENCE:

CALL CRTM\_Options\_Inspect( Options )

INPUTS:

Options: CRTM Options object to display.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

### *A.9.6 CRTM\_Options\_IsValid interface*

NAME:

CRTM\_Options\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a CRTM Options object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = CRTM\_Options\_IsValid( opt )

or

IF ( CRTM\_Options\_IsValid( opt ) ) THEN....

OBJECTS:

opt: CRTM Options object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: CRTM\_Options\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., Options object is unused or contains  
invalid data.  
== .TRUE., Options object can be used in CRTM.

UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

## A.10 SSU\_Input Structure

The `SSU_Input` structure is a component of the `Options` input structure. Note in figure A.15 that the structure is declared as `PRIVATE`. As such, the only way to set values in, or get values from, the structure is via the `SSU_Input_SetValue` or `SSU_Input_GetValue` subroutines respectively.

```

TYPE :: SSU_Input_type
  PRIVATE
  ! Time in decimal year (e.g. 2009.08892694 corresponds to 11:00 Feb. 2, 2009)
  REAL(fp) :: Time = ZERO
  ! SSU CO2 cell pressures (hPa)
  REAL(fp) :: Cell_Pressure(MAX_N_CHANNELS) = ZERO
END TYPE SSU_Input_type

```

**Figure A.15:** `SSU_Input_type` structure definition.

| Component     | Description  | Units | Dimensions         |
|---------------|--|-------|--------------------|
| Time          | Time in decimal year corresponding to SSU observation. | N/A   | Scalar             |
| Cell_Pressure | The SSU CO <sub>2</sub> cell pressures.                | hPa   | MAX_N_CHANNELS (3) |

**Table A.16:** CRTM `SSU_Input` structure component description

### A.10.1 `SSU_Input_CellPressureIsSet` interface

NAME:

`SSU_Input_CellPressureIsSet`

PURPOSE:

Elemental function to determine if `SSU_Input` object cell pressures are set (i.e. > zero).

CALLING SEQUENCE:

`result = SSU_Input_CellPressureIsSet( ssu )`

or

`IF ( SSU_Input_CellPressureIsSet( ssu ) ) THEN`

...

`END IF`

OBJECTS:

`ssu`: `SSU_Input` object for which the cell pressures are to be tested.

UNITS: N/A

TYPE: `SSU_Input_type`

DIMENSION: Scalar or any rank

ATTRIBUTES: `INTENT(IN)`

FUNCTION RESULT:

result: Logical variable indicating whether or not all the  
SSU cell pressures are set.  
If == .FALSE., cell pressure values are <= 0.0hPa and  
thus are considered to be NOT set or valid.  
== .TRUE., cell pressure values are > 0.0hPa and  
thus are considered to be set and valid.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### *A.10.2 SSU\_Input\_DefineVersion interface*

NAME:

SSU\_Input\_DefineVersion

PURPOSE:

Subroutine to return the module version information.

CALLING SEQUENCE:

CALL SSU\_Input\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### *A.10.3 SSU\_Input\_GetValue interface*

NAME:

SSU\_Input\_GetValue

PURPOSE:

Elemental subroutine to Get the values of SSU\_Input  
object components.

CALLING SEQUENCE:

CALL SSU\_Input\_GetValue( SSU\_Input, &  
Channel = Channel, &  
Time = Time, &  
Cell\_Pressure = Cell\_Pressure, &  
n\_Channels = n\_Channels )

OBJECTS:

SSU\_Input: SSU\_Input object for which component values are to be set.  
 UNITS: N/A  
 TYPE: SSU\_Input\_type  
 DIMENSION: Scalar or any rank  
 ATTRIBUTES: INTENT(IN OUT)

OPTIONAL INPUTS:

Channel: SSU channel for which the CO2 cell pressure is required.  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as SSU\_Input  
 ATTRIBUTES: INTENT(IN), OPTIONAL

OPTIONAL OUTPUTS:

Time: SSU instrument mission time.  
 UNITS: decimal year  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as SSU\_Input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

Cell\_Pressure: SSU channel CO2 cell pressure. Must be specified with the Channel optional input dummy argument.  
 UNITS: hPa  
 TYPE: REAL(fp)  
 DIMENSION: Scalar or same as SSU\_Input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

n\_Channels: Number of SSU channels..  
 UNITS: N/A  
 TYPE: INTEGER  
 DIMENSION: Scalar or same as SSU\_Input  
 ATTRIBUTES: INTENT(OUT), OPTIONAL

#### A.10.4 SSU\_Input\_Inspect interface

NAME:  
 SSU\_Input\_Inspect

PURPOSE:  
 Subroutine to print the contents of an SSU\_Input object to stdout.

CALLING SEQUENCE:  
 CALL SSU\_Input\_Inspect( ssu )

INPUTS:

ssu: SSU\_Input object to display.  
 UNITS: N/A

TYPE: SSU\_Input\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

#### *A.10.5 SSU\_Input\_IsValid interface*

NAME:

SSU\_Input\_IsValid

PURPOSE:

Non-pure function to perform some simple validity checks on a SSU\_Input object.

If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:

result = SSU\_Input\_IsValid( ssu )

or

IF ( SSU\_Input\_IsValid( ssu ) ) THEN....

OBJECTS:

ssu: SSU\_Input object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: SSU\_Input\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., object is unused or contains  
invalid data.  
== .TRUE., object can be used.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

#### *A.10.6 SSU\_Input\_SetValue interface*

NAME:

SSU\_Input\_SetValue

PURPOSE:

Elemental subroutine to set the values of SSU\_Input

object components.

CALLING SEQUENCE:

```
CALL SSU_Input_SetValue( SSU_Input           , &
                        Time                 = Time           , &
                        Cell_Pressure       = Cell_Pressure, &
                        Channel              = Channel         )
```

OBJECTS:

SSU\_Input: SSU\_Input object for which component values  
are to be set.  
UNITS: N/A  
TYPE: SSU\_Input\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

OPTIONAL INPUTS:

Time: SSU instrument mission time.  
UNITS: decimal year  
TYPE: REAL(fp)  
DIMENSION: Scalar or same as SSU\_Input  
ATTRIBUTES: INTENT(IN), OPTIONAL

Cell\_Pressure: SSU channel CO2 cell pressure. Must be  
specified with the Channel optional dummy  
argument.  
UNITS: hPa  
TYPE: REAL(fp)  
DIMENSION: Scalar or same as SSU\_Input  
ATTRIBUTES: INTENT(IN), OPTIONAL

Channel: SSU channel for which the CO2 cell pressure  
is to be set. Must be specified with the  
Cell\_Pressure optional dummy argument.  
UNITS: N/A  
TYPE: INTEGER  
DIMENSION: Scalar or same as SSU\_Input  
ATTRIBUTES: INTENT(IN), OPTIONAL

## A.11 Zeeman\_Input Structure

The `Zeeman_Input` structure is a component of the `Options` input structure. Note in figure A.16 that the structure is declared as `PRIVATE`. As such, the only way to set values in, or get values from, the structure is via the `Zeeman_Input_SetValue` or `Zeeman_Input_GetValue` subroutines respectively.

```

TYPE :: Zeeman_Input_type
  PRIVATE
  ! Earth magnetic field strength in Gauss
  REAL(fp) :: Be = DEFAULT_MAGENTIC_FIELD
  ! Cosine of the angle between the Earth
  ! magnetic field and wave propagation direction
  REAL(fp) :: Cos_ThetaB = ZERO
  ! Cosine of the azimuth angle of the Be vector.
  REAL(fp) :: Cos_PhiB = ZERO
  ! Doppler frequency shift caused by Earth-rotation.
  REAL(fp) :: Doppler_Shift = ZERO
END TYPE Zeeman_Input_type

```

Figure A.16: `Zeeman_Input_type` structure definition.

| Component     | Description  | Units | Dimensions |
|---------------|--|-------|------------|
| Be            | Earth magnetic field strength.   | Gauss | Scalar     |
| Cos_ThetaB    | Cosine of the angle between the Earth magnetic field and wave propagation direction.   | N/A   | Scalar     |
| Cos_PhiB      | Cosine of the azimuth angle of the $\mathbf{B}_e$ vector in the $(\mathbf{v}, \mathbf{h}, \mathbf{k})$ coordinates system, where $\mathbf{v}$ , $\mathbf{h}$ and $\mathbf{k}$ comprise a right-hand orthogonal system, similar to the $(\mathbf{x}, \mathbf{y}, \mathbf{z})$ Cartesian coordinates. The $\mathbf{h}$ vector is normal to the plane containing the $\mathbf{k}$ and $\mathbf{z}$ vectors, where $\mathbf{k}$ points to the wave propagation direction and $\mathbf{z}$ points to the zenith. $\mathbf{h} = (\mathbf{z} \times \mathbf{k})/ \mathbf{z} \times \mathbf{k} $ . The azimuth angle is the angle on the $(\mathbf{v}, \mathbf{h})$ plane from the positive $\mathbf{v}$ axis to the projected line of the $\mathbf{B}_e$ vector on this plane, positive counterclockwise. | N/A   | Scalar     |
| Doppler_Shift | Doppler frequency shift caused by Earth-rotation (positive towards sensor). A zero value means no frequency shift.   | KHz   | Scalar     |

Table A.17: CRTM `Zeeman_Input` structure component description

### A.11.1 `Zeeman_Input_DefineVersion` interface

NAME:

`Zeeman_Input_DefineVersion`

PURPOSE:



Subroutine to return the module version information.

CALLING SEQUENCE:

CALL Zeeman\_Input\_DefineVersion( Id )

OUTPUTS:

Id: Character string containing the version Id information  
for the module.  
UNITS: N/A  
TYPE: CHARACTER(\*)  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(OUT)

### A.11.2 Zeeman\_Input\_GetValue interface

NAME:

Zeeman\_Input\_GetValue

PURPOSE:

Elemental subroutine to get the values of Zeeman\_Input  
object components.

CALLING SEQUENCE:

CALL Zeeman\_Input\_GetValue( Zeeman\_Input , &  
Field\_Strength = Field\_Strength, &  
Cos\_ThetaB = Cos\_ThetaB , &  
Cos\_PhiB = Cos\_PhiB , &  
Doppler\_Shift = Doppler\_Shift )

OBJECTS:

Zeeman\_Input: Zeeman\_Input object for which component values  
are to be set.  
UNITS: N/A  
TYPE: Zeeman\_Input\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

OPTIONAL OUTPUTS:

Field\_Strength: Earth's magnetic field strength  
UNITS: Gauss  
TYPE: REAL(fp)  
DIMENSION: Scalar or same as Zeeman\_Input  
ATTRIBUTES: INTENT(OUT), OPTIONAL

Cos\_ThetaB: Cosine of the angle between the Earth magnetic  
field and wave propagation vectors.  
UNITS: N/A  
TYPE: REAL(fp)  
DIMENSION: Scalar or same as Zeeman\_Input  
ATTRIBUTES: INTENT(OUT), OPTIONAL

Cos\_PhiB:           Cosine of the azimuth angle of the Earth magnetic field vector.  
                     UNITS:       N/A  
                     TYPE:        REAL(fp)  
                     DIMENSION: Scalar or same as Zeeman\_Input  
                     ATTRIBUTES: INTENT(OUT), OPTIONAL

Doppler\_Shift:       Doppler frequency shift caused by Earth-rotation. Positive towards sensor.  
                     UNITS:       KHz  
                     TYPE:        REAL(fp)  
                     DIMENSION: Scalar or same as Zeeman\_Input  
                     ATTRIBUTES: INTENT(OUT), OPTIONAL

### *A.11.3 Zeeman\_Input\_Inspect interface*

NAME:  
       Zeeman\_Input\_Inspect

PURPOSE:  
       Subroutine to print the contents of an Zeeman\_Input object to stdout.

CALLING SEQUENCE:  
       CALL Zeeman\_Input\_Inspect( z )

INPUTS:  
       z:            Zeeman\_Input object to display.  
                     UNITS:       N/A  
                     TYPE:        Zeeman\_Input\_type  
                     DIMENSION: Scalar  
                     ATTRIBUTES: INTENT(IN)

### *A.11.4 Zeeman\_Input\_IsValid interface*

NAME:  
       Zeeman\_Input\_IsValid

PURPOSE:  
       Non-pure function to perform some simple validity checks on a Zeeman\_Input object.  
       If invalid data is found, a message is printed to stdout.

CALLING SEQUENCE:  
       result = Zeeman\_Input\_IsValid( z )

or

IF ( Zeeman\_Input\_IsValid( z ) ) THEN....

OBJECTS:

z: Zeeman\_Input object which is to have its  
contents checked.  
UNITS: N/A  
TYPE: Zeeman\_Input\_type  
DIMENSION: Scalar  
ATTRIBUTES: INTENT(IN)

FUNCTION RESULT:

result: Logical variable indicating whether or not the input  
passed the check.  
If == .FALSE., object is unused or contains  
invalid data.  
== .TRUE., object can be used.  
UNITS: N/A  
TYPE: LOGICAL  
DIMENSION: Scalar

### *A.11.5 Zeeman\_Input\_SetValue interface*

NAME:

Zeeman\_Input\_SetValue

PURPOSE:

Elemental subroutine to set the values of Zeeman\_Input  
object components.

CALLING SEQUENCE:

CALL Zeeman\_Input\_SetValue( Zeeman\_Input , &  
Field\_Strength = Field\_Strength, &  
Cos\_ThetaB = Cos\_ThetaB , &  
Cos\_PhiB = Cos\_PhiB , &  
Doppler\_Shift = Doppler\_Shift )

OBJECTS:

Zeeman\_Input: Zeeman\_Input object for which component values  
are to be set.  
UNITS: N/A  
TYPE: Zeeman\_Input\_type  
DIMENSION: Scalar or any rank  
ATTRIBUTES: INTENT(IN OUT)

OPTIONAL INPUTS:

Field\_Strength: Earth's magnetic field strength  
UNITS: Gauss  
TYPE: REAL(fp)

|                |   |
|----------------|---|
|                | DIMENSION: Scalar or same as Zeeman_Input<br>ATTRIBUTES: INTENT(IN), OPTIONAL   |
| Cos_ThetaB:    | Cosine of the angle between the Earth magnetic field and wave propagation vectors.<br>UNITS: N/A<br>TYPE: REAL(fp)<br>DIMENSION: Scalar or same as Zeeman_Input<br>ATTRIBUTES: INTENT(IN), OPTIONAL |
| Cos_PhiB:      | Cosine of the azimuth angle of the Earth magnetic field vector.<br>UNITS: N/A<br>TYPE: REAL(fp)<br>DIMENSION: Scalar or same as Zeeman_Input<br>ATTRIBUTES: INTENT(IN), OPTIONAL                    |
| Doppler_Shift: | Doppler frequency shift caused by Earth-rotation. Positive towards sensor.<br>UNITS: KHz<br>TYPE: REAL(fp)<br>DIMENSION: Scalar or same as Zeeman_Input<br>ATTRIBUTES: INTENT(IN), OPTIONAL         |

## *B*

### *Valid Sensor Identifiers*

This section contains a table detailing the instruments for which there are CRTM coefficients. For most sensors there are transmittance coefficient (**TauCoeff**) datafiles for both the Optical Depth in Absorber Space (ODAS; also known as Compact-OPTRAN) and Optical Depth in Pressure Space (ODPS) transmittance algorithms. All visible and SSU channels have only ODAS coefficients.

**Table B.1:** CRTM sensor identifiers and the availability of ODAS or ODPS TauCoeff files

| Instrument                | Sensor Id     | ODAS available | ODPS available |
|---------------------------|---------------|----------------|----------------|
| Envisat AATSR             | aatsr_envisat | yes            | yes            |
| GOES-R ABI                | abi_gr        | yes            | yes            |
| Aqua AIRS (281ch. subset) | airs281_aqua  | yes            | yes            |
| Aqua AIRS (324ch. subset) | airs324_aqua  | yes            | yes            |
| Aqua AIRS (all channels)  | airs2378_aqua | yes            | yes            |
| Aqua AIRS Module-1a       | airsM1a_aqua  | yes            | yes            |
| Aqua AIRS Module-1b       | airsM1b_aqua  | yes            | yes            |
| Aqua AIRS Module-2a       | airsM2a_aqua  | yes            | yes            |
| Aqua AIRS Module-2b       | airsM2b_aqua  | yes            | yes            |
| Aqua AIRS Module-3        | airsM3_aqua   | yes            | yes            |
| Aqua AIRS Module-4a       | airsM4a_aqua  | yes            | yes            |
| Aqua AIRS Module-4b       | airsM4b_aqua  | yes            | yes            |
| Aqua AIRS Module-4c       | airsM4c_aqua  | yes            | yes            |
| Aqua AIRS Module-4d       | airsM4d_aqua  | yes            | yes            |
| Aqua AIRS Module-5        | airsM5_aqua   | yes            | yes            |
| Aqua AIRS Module-6        | airsM6_aqua   | yes            | yes            |
| Aqua AIRS Module-7        | airsM7_aqua   | yes            | yes            |
| Aqua AIRS Module-8        | airsM8_aqua   | yes            | yes            |
| Aqua AIRS Module-9        | airsM9_aqua   | yes            | yes            |
| Aqua AIRS Module-10       | airsM10_aqua  | yes            | yes            |
| Aqua AIRS Module-11       | airsM11_aqua  | yes            | yes            |
| Aqua AIRS Module-12       | airsM12_aqua  | yes            | yes            |
| Aqua AMSR-E               | amsre_aqua    | yes            | yes            |
| Aqua AMSU-A               | amsua_aqua    | yes            | yes            |
| NOAA-15 AMSU-A            | amsua_n15     | yes            | yes            |
| NOAA-16 AMSU-A            | amsua_n16     | yes            | yes            |
| NOAA-17 AMSU-A            | amsua_n17     | yes            | yes            |
| NOAA-18 AMSU-A            | amsua_n18     | yes            | yes            |
| NOAA-19 AMSU-A            | amsua_n19     | yes            | yes            |
| MetOp-A AMSU-A            | amsua_metop-a | yes            | yes            |
| MetOp-B AMSU-A            | amsua_metop-b | yes            | yes            |
| MetOp-C AMSU-A            | amsua_metop-c | yes            | yes            |
| NOAA-15 AMSU-B            | amsub_n15     | yes            | yes            |
| NOAA-16 AMSU-B            | amsub_n16     | yes            | yes            |
| NOAA-17 AMSU-B            | amsub_n17     | yes            | yes            |
| NPP ATMS                  | atms_npp      | yes            | yes            |
| ERS-1 ATSR                | atsr1_ers1    | yes            | yes            |
| ERS-2 ATSR                | atsr2_ers2    | yes            | yes            |
| TIROS-N AVHRR/2           | avhrr2_tirosn | yes            | yes            |
| NOAA-06 AVHRR/2           | avhrr2_n06    | yes            | yes            |
| NOAA-07 AVHRR/2           | avhrr2_n07    | yes            | yes            |
| NOAA-08 AVHRR/2           | avhrr2_n08    | yes            | yes            |
| NOAA-09 AVHRR/2           | avhrr2_n09    | yes            | yes            |
| NOAA-10 AVHRR/2           | avhrr2_n10    | yes            | yes            |
| NOAA-11 AVHRR/2           | avhrr2_n11    | yes            | yes            |
| NOAA-12 AVHRR/2           | avhrr2_n12    | yes            | yes            |
| NOAA-14 AVHRR/2           | avhrr2_n14    | yes            | yes            |
| NOAA-15 AVHRR/3           | avhrr3_n15    | yes            | yes            |
| NOAA-16 AVHRR/3           | avhrr3_n16    | yes            | yes            |

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**Table B.1** – Continued

| <b>Instrument</b>            | <b>Sensor Id</b> | <b>ODAS available</b> | <b>ODPS available</b> |
|------------------------------|------------------|-----------------------|-----------------------|
| NOAA-17 AVHRR/3              | avhrr3_n17       | yes                   | yes                   |
| NOAA-18 AVHRR/3              | avhrr3_n18       | yes                   | yes                   |
| NOAA-19 AVHRR/3              | avhrr3_n19       | yes                   | yes                   |
| MetOp-A AVHRR/3              | avhrr3_metop-a   | yes                   | yes                   |
| MetOp-B AVHRR/3              | avhrr3_metop-b   | yes                   | yes                   |
| NPP CrIS (374ch. subset)     | cris374_npp      | yes                   | yes                   |
| NPP CrIS (399ch. subset)     | cris399_npp      | yes                   | yes                   |
| NPP CrIS (all channels)      | cris1305_npp     | yes                   | yes                   |
| NPP CrIS Band 1              | crisB1_npp       | yes                   | yes                   |
| NPP CrIS Band 2              | crisB2_npp       | yes                   | yes                   |
| NPP CrIS Band 3              | crisB3_npp       | yes                   | yes                   |
| GPM GMI                      | gmi_gpm          | yes                   | yes                   |
| TIROS-N HIRS/2               | hirs2_tirosn     | yes                   | yes                   |
| NOAA-06 HIRS/2               | hirs2_n06        | yes                   | yes                   |
| NOAA-07 HIRS/2               | hirs2_n07        | yes                   | yes                   |
| NOAA-08 HIRS/2               | hirs2_n08        | yes                   | yes                   |
| NOAA-09 HIRS/2               | hirs2_n09        | yes                   | yes                   |
| NOAA-10 HIRS/2               | hirs2_n10        | yes                   | yes                   |
| NOAA-11 HIRS/2               | hirs2_n11        | yes                   | yes                   |
| NOAA-12 HIRS/2               | hirs2_n12        | yes                   | yes                   |
| NOAA-14 HIRS/2               | hirs2_n14        | yes                   | yes                   |
| NOAA-15 HIRS/3               | hirs3_n15        | yes                   | yes                   |
| NOAA-16 HIRS/3               | hirs3_n16        | yes                   | yes                   |
| NOAA-17 HIRS/3               | hirs3_n17        | yes                   | yes                   |
| NOAA-18 HIRS/4               | hirs4_n18        | yes                   | yes                   |
| NOAA-19 HIRS/4               | hirs4_n19        | yes                   | yes                   |
| MetOp-A HIRS/4               | hirs4_metop-a    | yes                   | yes                   |
| MetOp-B HIRS/4               | hirs4_metop-b    | yes                   | yes                   |
| Aqua HSB                     | hsb_aqua         | yes                   | yes                   |
| MetOp-A IASI (300ch. subset) | iasi300_metop-a  | yes                   | yes                   |
| MetOp-A IASI (316ch. subset) | iasi316_metop-a  | yes                   | yes                   |
| MetOp-A IASI (616ch. subset) | iasi616_metop-a  | yes                   | yes                   |
| MetOp-A IASI (all channels)  | iasi8461_metop-a | yes                   | yes                   |
| MetOp-A IASI Band 1          | iasiB1_metop-a   | yes                   | yes                   |
| MetOp-A IASI Band 2          | iasiB2_metop-a   | yes                   | yes                   |
| MetOp-A IASI Band 3          | iasiB3_metop-a   | yes                   | yes                   |
| MetOp-B IASI (300ch. subset) | iasi300_metop-b  | yes                   | yes                   |
| MetOp-B IASI (316ch. subset) | iasi316_metop-b  | yes                   | yes                   |
| MetOp-B IASI (616ch. subset) | iasi616_metop-b  | yes                   | yes                   |
| MetOp-B IASI (all channels)  | iasi8461_metop-b | yes                   | yes                   |
| MetOp-B IASI Band 1          | iasiB1_metop-b   | yes                   | yes                   |
| MetOp-B IASI Band 2          | iasiB2_metop-b   | yes                   | yes                   |
| MetOp-B IASI Band 3          | iasiB3_metop-b   | yes                   | yes                   |
| GOES-08 Imager               | imgr_g08         | yes                   | yes                   |
| GOES-09 Imager               | imgr_g09         | yes                   | yes                   |
| GOES-10 Imager               | imgr_g10         | yes                   | yes                   |
| GOES-11 Imager               | imgr_g11         | yes                   | yes                   |
| GOES-12 Imager               | imgr_g12         | yes                   | yes                   |
| GOES-13 Imager               | imgr_g13         | yes                   | yes                   |
| GOES-14 Imager               | imgr_g14         | yes                   | yes                   |

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**Table B.1** – Continued

| <b>Instrument</b>            | <b>Sensor Id</b> | <b>ODAS available</b> | <b>ODPS available</b> |
|------------------------------|------------------|-----------------------|-----------------------|
| GOES-15 Imager               | imgr_g15         | yes                   | yes                   |
| MTSAT-1R Imager              | imgr_mt1r        | yes                   | yes                   |
| MTSAT-2 Imager               | imgr_mt2         | yes                   | yes                   |
| Fengyun-3a IRAS              | iras_fy3a        | yes                   | yes                   |
| Fengyun-3b IRAS              | iras_fy3b        | yes                   | yes                   |
| Megha-Tropiques MADRAS       | madras_meghat    | yes                   | yes                   |
| Fengyun-3a MERSI             | mersi_fy3a       | yes                   | yes                   |
| NOAA-18 MHS                  | mhs_n18          | yes                   | yes                   |
| NOAA-19 MHS                  | mhs_n19          | yes                   | yes                   |
| MetOp-A MHS                  | mhs_metop-a      | yes                   | yes                   |
| MetOp-B MHS                  | mhs_metop-b      | yes                   | yes                   |
| MetOp-C MHS                  | mhs_metop-c      | yes                   | yes                   |
| COMS-1 MI (low patch)        | mi-l_coms        | yes                   | yes                   |
| COMS-1 MI (medium patch)     | mi-m_coms        | yes                   | yes                   |
| Aqua MODIS                   | modis_aqua       | yes                   | yes                   |
| Terra MODIS                  | modis_terra      | yes                   | yes                   |
| TIROS-N MSU                  | msu_tirosn       | yes                   | yes                   |
| NOAA-06 MSU                  | msu_n06          | yes                   | yes                   |
| NOAA-07 MSU                  | msu_n07          | yes                   | yes                   |
| NOAA-08 MSU                  | msu_n08          | yes                   | yes                   |
| NOAA-09 MSU                  | msu_n09          | yes                   | yes                   |
| NOAA-10 MSU                  | msu_n10          | yes                   | yes                   |
| NOAA-11 MSU                  | msu_n11          | yes                   | yes                   |
| NOAA-12 MSU                  | msu_n12          | yes                   | yes                   |
| NOAA-14 MSU                  | msu_n14          | yes                   | yes                   |
| Meteosat-3 MVIRI (backup)    | mviriBKUP_m03    | no                    | yes                   |
| Meteosat-4 MVIRI (backup)    | mviriBKUP_m04    | no                    | yes                   |
| Meteosat-5 MVIRI (backup)    | mviriBKUP_m05    | no                    | yes                   |
| Meteosat-6 MVIRI (backup)    | mviriBKUP_m06    | no                    | yes                   |
| Meteosat-7 MVIRI (backup)    | mviriBKUP_m07    | no                    | yes                   |
| Meteosat-3 MVIRI (nominal)   | mviriNOM_m03     | no                    | yes                   |
| Meteosat-4 MVIRI (nominal)   | mviriNOM_m04     | no                    | yes                   |
| Meteosat-5 MVIRI (nominal)   | mviriNOM_m05     | no                    | yes                   |
| Meteosat-6 MVIRI (nominal)   | mviriNOM_m06     | no                    | yes                   |
| Meteosat-7 MVIRI (nominal)   | mviriNOM_m07     | no                    | yes                   |
| Fengyun-3a MWHS              | mwhs_fy3a        | yes                   | yes                   |
| Fengyun-3b MWHS              | mwhs_fy3b        | yes                   | yes                   |
| Fengyun-3a MWRI              | mwri_fy3a        | yes                   | yes                   |
| Fengyun-3b MWRI              | mwri_fy3b        | yes                   | yes                   |
| Fengyun-3a MWTS              | mwts_fy3a        | yes                   | yes                   |
| Fengyun-3b MWTS              | mwts_fy3b        | yes                   | yes                   |
| Megha-Tropiques SAPHIR       | saphir_meghat    | yes                   | yes                   |
| Meteosat-08 SEVIRI           | seviri_m08       | yes                   | yes                   |
| Meteosat-09 SEVIRI           | seviri_m09       | yes                   | yes                   |
| Meteosat-10 SEVIRI           | seviri_m10       | yes                   | yes                   |
| GOES-10 Sounder (Detector 1) | sndrD1_g10       | yes                   | yes                   |
| GOES-10 Sounder (Detector 2) | sndrD2_g10       | yes                   | yes                   |
| GOES-10 Sounder (Detector 3) | sndrD3_g10       | yes                   | yes                   |
| GOES-10 Sounder (Detector 4) | sndrD4_g10       | yes                   | yes                   |
| GOES-11 Sounder (Detector 1) | sndrD1_g11       | yes                   | yes                   |

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Table B.1 – Continued

| Instrument                   | Sensor Id  | ODAS available | ODPS available |
|------------------------------|------------|----------------|----------------|
| GOES-11 Sounder (Detector 2) | sndrD2.g11 | yes            | yes            |
| GOES-11 Sounder (Detector 3) | sndrD3.g11 | yes            | yes            |
| GOES-11 Sounder (Detector 4) | sndrD4.g11 | yes            | yes            |
| GOES-12 Sounder (Detector 1) | sndrD1.g12 | yes            | yes            |
| GOES-12 Sounder (Detector 2) | sndrD2.g12 | yes            | yes            |
| GOES-12 Sounder (Detector 3) | sndrD3.g12 | yes            | yes            |
| GOES-12 Sounder (Detector 4) | sndrD4.g12 | yes            | yes            |
| GOES-13 Sounder (Detector 1) | sndrD1.g13 | yes            | yes            |
| GOES-13 Sounder (Detector 2) | sndrD2.g13 | yes            | yes            |
| GOES-13 Sounder (Detector 3) | sndrD3.g13 | yes            | yes            |
| GOES-13 Sounder (Detector 4) | sndrD4.g13 | yes            | yes            |
| GOES-14 Sounder (Detector 1) | sndrD1.g14 | yes            | yes            |
| GOES-14 Sounder (Detector 2) | sndrD2.g14 | yes            | yes            |
| GOES-14 Sounder (Detector 3) | sndrD3.g14 | yes            | yes            |
| GOES-14 Sounder (Detector 4) | sndrD4.g14 | yes            | yes            |
| GOES-15 Sounder (Detector 1) | sndrD1.g15 | yes            | yes            |
| GOES-15 Sounder (Detector 2) | sndrD2.g15 | yes            | yes            |
| GOES-15 Sounder (Detector 3) | sndrD3.g15 | yes            | yes            |
| GOES-15 Sounder (Detector 4) | sndrD4.g15 | yes            | yes            |
| GOES-08 Sounder              | sndr.g08   | yes            | yes            |
| GOES-09 Sounder              | sndr.g09   | yes            | yes            |
| GOES-10 Sounder              | sndr.g10   | yes            | yes            |
| GOES-11 Sounder              | sndr.g11   | yes            | yes            |
| GOES-12 Sounder              | sndr.g12   | yes            | yes            |
| GOES-13 Sounder              | sndr.g13   | yes            | yes            |
| GOES-14 Sounder              | sndr.g14   | yes            | yes            |
| GOES-15 Sounder              | sndr.g15   | yes            | yes            |
| DMSP-08 SSM/I                | ssmi.f08   | yes            | yes            |
| DMSP-10 SSM/I                | ssmi.f10   | yes            | yes            |
| DMSP-11 SSM/I                | ssmi.f11   | yes            | yes            |
| DMSP-13 SSM/I                | ssmi.f13   | yes            | yes            |
| DMSP-14 SSM/I                | ssmi.f14   | yes            | yes            |
| DMSP-15 SSM/I                | ssmi.f15   | yes            | yes            |
| DMSP-16 SSMIS                | ssmis.f16  | yes            | yes            |
| DMSP-17 SSMIS                | ssmis.f17  | yes            | yes            |
| DMSP-18 SSMIS                | ssmis.f18  | yes            | yes            |
| DMSP-19 SSMIS                | ssmis.f19  | yes            | yes            |
| DMSP-20 SSMIS                | ssmis.f20  | yes            | yes            |
| DMSP-13 SSM/T-1              | ssmt1.f13  | yes            | yes            |
| DMSP-15 SSM/T-1              | ssmt1.f15  | yes            | yes            |
| DMSP-14 SSM/T-2              | ssmt2.f14  | yes            | yes            |
| DMSP-15 SSM/T-2              | ssmt2.f15  | yes            | yes            |
| TIROS-N SSU                  | ssu.tirosn | yes            | yes            |
| NOAA-06 SSU                  | ssu.n06    | yes            | yes            |
| NOAA-07 SSU                  | ssu.n07    | yes            | yes            |
| NOAA-08 SSU                  | ssu.n08    | yes            | yes            |
| NOAA-09 SSU                  | ssu.n09    | yes            | yes            |
| NOAA-11 SSU                  | ssu.n11    | yes            | yes            |
| NOAA-14 SSU                  | ssu.n14    | yes            | yes            |
| TRMM TMI                     | tmi.trmm   | yes            | yes            |

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**Table B.1** – Continued

| <b>Instrument</b>                  | <b>Sensor Id</b> | <b>ODAS available</b> | <b>ODPS available</b> |
|------------------------------------|------------------|-----------------------|-----------------------|
| GOES-R ABI (visible)               | v.abi_gr         | yes                   | no                    |
| NOAA-15 AVHRR/3 (visible)          | v.avhrr3_n15     | yes                   | no                    |
| NOAA-16 AVHRR/3 (visible)          | v.avhrr3_n16     | yes                   | no                    |
| NOAA-17 AVHRR/3 (visible)          | v.avhrr3_n17     | yes                   | no                    |
| NOAA-18 AVHRR/3 (visible)          | v.avhrr3_n18     | yes                   | no                    |
| NOAA-19 AVHRR/3 (visible)          | v.avhrr3_n19     | yes                   | no                    |
| MetOp-A AVHRR/3 (visible)          | v.avhrr3_metop-a | yes                   | no                    |
| MetOp-B AVHRR/3 (visible)          | v.avhrr3_metop-b | yes                   | no                    |
| GOES-11 Imager (visible)           | v.imgr_g11       | yes                   | no                    |
| GOES-12 Imager (visible)           | v.imgr_g12       | yes                   | no                    |
| GOES-13 Imager (visible)           | v.imgr_g13       | yes                   | no                    |
| GOES-14 Imager (visible)           | v.imgr_g14       | yes                   | no                    |
| GOES-15 Imager (visible)           | v.imgr_g15       | yes                   | no                    |
| MTSAT-2 Imager (visible)           | v.imgr_mt2       | yes                   | no                    |
| Aqua MODIS (visible)               | v.modis_aqua     | yes                   | no                    |
| Terra MODIS (visible)              | v.modis_terra    | yes                   | no                    |
| Meteosat-08 SEVIRI (visible)       | v.seviri_m08     | yes                   | no                    |
| Meteosat-09 SEVIRI (visible)       | v.seviri_m09     | yes                   | no                    |
| Meteosat-10 SEVIRI (visible)       | v.seviri_m10     | yes                   | no                    |
| NPP VIIRS Imager, HiRes (visible)  | v.viirs-i_npp    | yes                   | no                    |
| NPP VIIRS Imager, ModRes (visible) | v.viirs-m_npp    | yes                   | no                    |
| GOES-4 VAS                         | vas_g04          | no                    | yes                   |
| GOES-5 VAS                         | vas_g05          | no                    | yes                   |
| GOES-6 VAS                         | vas_g06          | no                    | yes                   |
| GOES-7 VAS                         | vas_g07          | no                    | yes                   |
| NPP VIIRS Imager, HiRes            | viirs-i_npp      | yes                   | yes                   |
| NPP VIIRS Imager, ModRes           | viirs-m_npp      | yes                   | yes                   |
| Fengyun-3a VIRR                    | virr_fy3a        | yes                   | yes                   |
| GMS-5 VISSR (Detector A)           | vissrDetA_gms5   | yes                   | yes                   |
| GMS-5 VISSR (Detector B)           | vissrDetB_gms5   | no                    | yes                   |
| Kalpana-1 VHRR                     | vhrr_kalpana1    | yes                   | yes                   |
| ITOS VTPR-S1                       | vtprS1_itos      | yes                   | yes                   |
| ITOS VTPR-S2                       | vtprS2_itos      | yes                   | yes                   |
| ITOS VTPR-S3                       | vtprS3_itos      | yes                   | yes                   |
| ITOS VTPR-S4                       | vtprS4_itos      | yes                   | yes                   |
| Coriolis WindSat                   | windsat_coriolis | yes                   | yes                   |

# C

## *Migration Path from REL-1.2.x to REL-2.0.x*

This section details the user code changes that need to be made to migrate from using CRTM v1.2.x to v2.0.x.

### C.1 CRTM Initialization

---

The `Sensor_Id` argument to the CRTM initialisation function identifies the sensors for which the CRTM will be initialised. In v1.2.x this argument was optional because generic `SpcCoeff` and `TauCoeff` files could be used. In v2.0.x, generic `SpcCoeff` and `TauCoeff` coefficient files are no longer accepted and, thus, a sensor identifier *must* be specified.

In v1.2.x the `CRTM_Init` interface looked like:

```
errStatus = CRTM_Init( ChannelInfo, Sensor_ID=Sensor_ID )
```

where `Sensor_Id` is optional. The v2.0.x interface is now,

```
errStatus = CRTM_Init( Sensor_ID, ChannelInfo )
```

where both the `Sensor_Id` and `ChannelInfo` arguments are mandatory. See the [CRTM\\_Init](#) section for complete details about the v2.0.x interface.

### C.2 CRTM Structure Life Cycle Changes

---

As mentioned in the “[What’s New in v2.0](#)” section, the user-accessible structures (i.e. those used to define the inputs to, and return the outputs from, the CRTM) and their associated life cycle procedures (i.e. allocation and deallocation) have been changed. To mitigate the possibility of memory leaks, the definitions of array members of structures have had their `POINTER` attribute replaced with `ALLOCATABLE`. This was a first step in preparation for use of Fortran2003 Object Oriented features in the CRTM (once Fortran2003 compiler become widely available), where the derived type structure definitions will be reclassified as objects and their procedures will be type-bound. The changes in the affected user-accessible structure procedures are shown below.

In addition to the general interface changes, all of the structure life cycle procedures are now elemental. That is, there is no longer a restriction on the dimensionality of the arguments as long as they are conformable.

#### C.2.1 Atmosphere

##### Creation

In v1.2.x the Atmosphere structure allocation was a function returning an error status,

```

errStatus = CRTM_Allocate_Atmosphere( n_Layers    , &
                                      n_Absorbers, &
                                      n_Clouds    , &
                                      n_Aerosols  , &
                                      Atmosphere  )

IF ( errStatus /= SUCCESS ) THEN
  ...
END IF

```

The v2.0.x interface was changed to an elemental subroutine,

```

CALL CRTM_Atmosphere_Create( Atmosphere , &
                             n_Layers    , &
                             n_Absorbers, &
                             n_Clouds    , &
                             n_Aerosols  )

IF ( .NOT. CRTM_Atmosphere_Associated( Atmosphere ) ) THEN
  ...
END IF

```

where the error checking is achieved via the `CRTM_Atmosphere_Associated` function call.

## Destruction

In v1.2.x the Atmosphere structure destruction was a function returning an error status,

```

errStatus = CRTM_Destroy_Atmosphere( Atmosphere )
IF ( errStatus /= SUCCESS ) THEN
  ...
END IF

```

The v2.0.x interface was changed to an elemental subroutine,

```

CALL CRTM_Atmosphere_Destroy( Atmosphere )
IF ( CRTM_Atmosphere_Associated( Atmosphere ) ) THEN
  ...
END IF

```

where, again, the error checking is achieved via the `CRTM_Atmosphere_Associated` function call.

## C.2.2 Surface

The Surface structure procedure changes only apply if you utilise the `SensorData` component.

### Creation

In v1.2.x the Surface structure allocation was a function returning an error status,

```

errStatus = CRTM_Surface_Allocate( n_Channels, &
                                   Surface      )

IF ( errStatus /= SUCCESS ) THEN
  ...
END IF

```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_Surface_Create( Surface,    &
                          n_Channels )
IF ( .NOT. CRTM_Surface_Associated( Surface ) ) THEN
...
END IF
```

where the error checking is achieved via the `CRTM_Surface_Associated` function call.

## Destruction

In v1.2.x the Surface structure destruction was a function returning an error status,

```
errStatus = CRTM_Destroy_Surface( Surface )
IF ( errStatus /= SUCCESS ) THEN
...
END IF
```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_Surface_Destroy( Surface )
IF ( CRTM_Surface_Associated( Surface ) ) THEN
...
END IF
```

where, again, the error checking is achieved via the `CRTM_Surface_Associated` function call.

## C.2.3 Options

### Creation

In v1.2.x the Options structure allocation was a function returning an error status,

```
errStatus = CRTM_Options_Allocate( n_Channels, &
                                   Options      )
IF ( errStatus /= SUCCESS ) THEN
...
END IF
```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_Options_Create( Options    , &
                          n_Channels )
IF ( .NOT. CRTM_Options_Associated( Options ) ) THEN
...
END IF
```

where the error checking is achieved via the `CRTM_Options_Associated` function call.

## Destruction

In v1.2.x the Options structure destruction was a function returning an error status,

```
errStatus = CRTM_Destroy_Options( Options )
IF ( errStatus /= SUCCESS ) THEN
...
END IF
```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_Options_Destroy( Options )
IF ( CRTM_Options_Associated( Options ) ) THEN
...
END IF
```

where, again, the error checking is achieved via the `CRTM_Options_Associated` function call.

## C.2.4 RTSolution

### Creation

In v1.2.x the RTSolution structure allocation was a function returning an error status,

```
errStatus = CRTM_RTSolution_Allocate( n_Layers , &
                                      RTSolution )
IF ( errStatus /= SUCCESS ) THEN
...
END IF
```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_RTSolution_Create( RTSolution, &
                             n_Layers )
IF ( .NOT. CRTM_RTSolution_Associated( RTSolution ) ) THEN
...
END IF
```

where the error checking is achieved via the `CRTM_RTSolution_Associated` function call.

### Destruction

In v1.2.x the RTSolution structure destruction was a function returning an error status,

```
errStatus = CRTM_Destroy_RTSolution( RTSolution )
IF ( errStatus /= SUCCESS ) THEN
...
END IF
```

The v2.0.x interface was changed to an elemental subroutine,

```
CALL CRTM_RTSolution_Destroy( RTSolution )
IF ( CRTM_RTSolution_Associated( RTSolution ) ) THEN
...
END IF
```

where, again, the error checking is achieved via the `CRTM_RTSolution_Associated` function call.

## C.3 CRTM Structure Replacement

---

An additional change was the replacement of the `CRTM_GeometryInfo_type` input structure definition with that of `CRTM_Geometry_type`. This was done to strictly separate the user defined inputs from the derived values determined inside the main CRTM functions.

In v1.2.x the input structure definition would look something like:

```
TYPE(CRTM_GeometryInfo_type) :: geo(N_PROFILES)
```

for a predefined number of atmospheric profiles (via `N_PROFILES`). The v2.0.x definition would be,

```
TYPE(CRTM_Geometry_type) :: geo(N_PROFILES)
```

Users should check that they are assigning values to all the necessary structure components.